Graph temporalisation

Filippo Brunelli, Pierluigi Crescenzi and Laurent Viennot

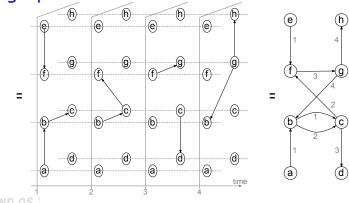


Inria Paris - GSSI - Irif (Université Paris Cité and CNRS)

https://onlinelibrary.wiley.com/doi/10.1002/net.22123

Tempogral - Poitiers 2022

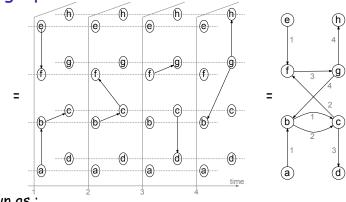
Temporal graphs



Also known as :

- time-dependent networks [Cooke, Halsey 1966],
- edge scheduled networks [Berman 1996], dynamic graphs [Harary, Gupta 1997], temporal networks [Kempe, Kleinberg, Kumar 2002], evolving graphs [Bhadra, Ferreira 2003],
- time-varying graphs [Casteigts, Flocchini, Quattrociocchi, Santoro 2012],
 - Iink streams [Latapy, Viard, Magnien 2018],...

Temporal graphs



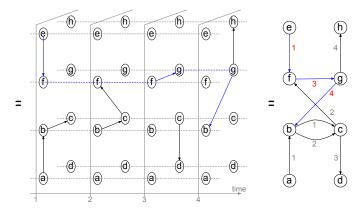
Also known as :

• time-dependent networks [Cooke, Halsey 1966],

• edge scheduled networks [Berman 1996], dynamic graphs [Harary, Gupta 1997], temporal networks [Kempe, Kleinberg, Kumar 2002], evolving graphs [Bhadra, Ferreira 2003],

• time-varying graphs [Casteigts, Flocchini, Quattrociocchi, Santoro 2012],

link streams [Latapy, Viard, Magnien 2018],...

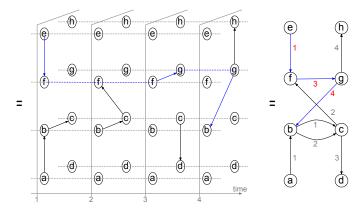


A path with increasing time labels.

Temporal paths are strict and waiting is allowed.

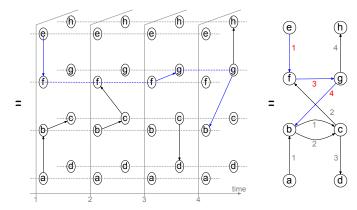
Reachable set $\mathcal{R}(u)$: the set of nodes v that u can reach by a temporal path (we let $u\mathcal{R}v$ denote $v \in \mathcal{R}(u)$).

Above, we have : eRb, bRh, $\neg aRf$, $\neg aRh$



A path with increasing time labels. Temporal paths are strict and waiting is allowed.

Reachable set $\mathcal{R}(u)$: the set of nodes v that u can reach by a temporal path (we let $u\mathcal{R}v$ denote $v \in \mathcal{R}(u)$). Above, we have : $e\mathcal{R}b$, $b\mathcal{R}h$, $\neg a\mathcal{R}f$, $\neg a\mathcal{R}h$

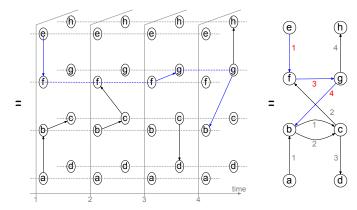


A path with increasing time labels.

Temporal paths are strict and waiting is allowed.

Reachable set $\mathcal{R}(u)$: the set of nodes v that u can reach by a temporal path (we let $u\mathcal{R}v$ denote $v \in \mathcal{R}(u)$).

Above, we have : eRb, bRh, $\neg aRf$, $\neg aRh$



A path with increasing time labels.

Temporal paths are strict and waiting is allowed.

Reachable set $\mathcal{R}(u)$: the set of nodes v that u can reach by a temporal path (we let $u\mathcal{R}v$ denote $v \in \mathcal{R}(u)$). Above, we have : $e\mathcal{R}b$, $b\mathcal{R}h$, $\neg a\mathcal{R}f$, $\neg a\mathcal{R}h$

Multidigraph temporalisation

Given a multidigraph M = (V, A) assign time labels to edges.

Maximum reachability goal (MRTT) : maximise total reachability $\sum_{u} |\mathcal{R}(u)|$.

Multidigraph temporalisation

Given a multidigraph M = (V, A) assign time labels to edges.

Maximum reachability goal (MRTT) : maximise total reachability $\sum_{u} |\mathcal{R}(u)|$.

Label-connected graph : assign time labels to an undirected graph (V,E) such that $\mathcal{R}(u)=V$ for all $u\in V.$

Undirected setting : if uv is available at time t, both (u,v) and (v,u) are available at time t.

Known results [Göbel, Cerdeira, Veldman 1991]:

• Deciding label-connectivity is NP-hard.

• A graph is label-connected iff it contains two edge-disjoint spanning tree-pairs and some 4-cycle condition.

Label-connected graph : assign time labels to an undirected graph (V, E) such that $\mathcal{R}(u) = V$ for all $u \in V$.

Undirected setting : if uv is available at time t, both (u,v) and (v,u) are available at time t.

Known results [Göbel, Cerdeira, Veldman 1991]:

• Deciding label-connectivity is NP-hard.

• A graph is label-connected iff it contains two edge-disjoint spanning tree-pairs and some 4-cycle condition.

Label-connected graph : assign time labels to an undirected graph (V, E) such that $\mathcal{R}(u) = V$ for all $u \in V$.

Undirected setting : if uv is available at time t, both (u,v) and (v,u) are available at time t.

Known results [Göbel, Cerdeira, Veldman 1991]:

• Deciding label-connectivity is NP-hard.

• A graph is label-connected iff it contains two edge-disjoint spanning tree-pairs and some 4-cycle condition.

Label-connected graph : assign time labels to an undirected graph (V, E) such that $\mathcal{R}(u) = V$ for all $u \in V$.

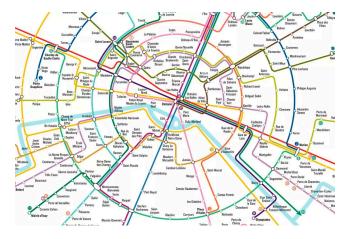
Undirected setting : if uv is available at time t, both (u,v) and (v,u) are available at time t.

Known results [Göbel, Cerdeira, Veldman 1991]:

• Deciding label-connectivity is NP-hard.

• A graph is label-connected iff it contains two edge-disjoint spanning tree-pairs and some 4-cycle condition.

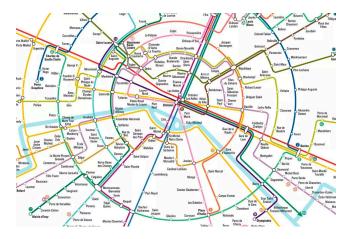
Public transport



Temporal edge : a vehicle on a line going from one stop to the next one.

The trip of a vehicle produces a sequence of temporal edges.

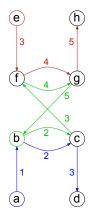
Public transport



Temporal edge : a vehicle on a line going from one stop to the next one.

The trip of a vehicle produces a sequence of temporal edges.

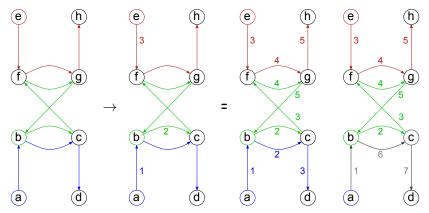
Public transport



Temporal edges are grouped into walks called trips.

Trip temporalisation

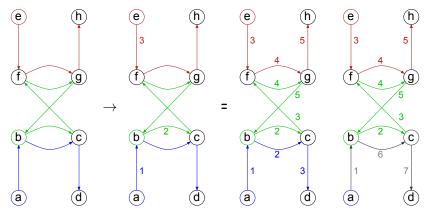
Trip temporalisation : Given a multidigraph M whose edges are partionned into t trips, set a starting time for each trip (we note n = |V(M)| and m = |E(M)|).



No trip temporalisation satisfies both aRh and eRd.

Trip temporalisation

Trip temporalisation : Given a multidigraph M whose edges are partionned into t trips, set a starting time for each trip (we note n = |V(M)| and m = |E(M)|).



No trip temporalisation satisfies both aRh and eRd.

One-to-one reachability is hard

O2O-RTT : given $u, v \in V$ decide if there exists a trip temporalisation such that $u\mathcal{R}v$.

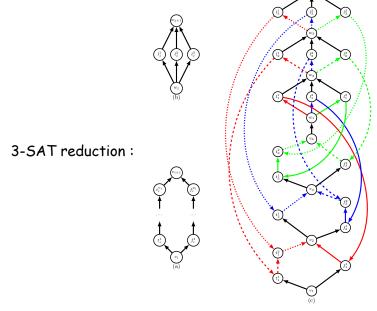
Theorem O2O-RTT is NP-complete.

One-to-one reachability is hard

O2O-RTT : given $u, v \in V$ decide if there exists a trip temporalisation such that $u\mathcal{R}v$.

Theorem O2O-RTT is NP-complete.

One-to-one reachability is hard



Theorem For any $\varepsilon > 0$, MRTT cannot be approximated within $O(n^{1-\varepsilon})$ unless P=NP.

Idea : connect many sources to v_1 and many sinks to w_{m+1} .

Theorem O2O-RTT using at most k trips can be solved in $2^{O(k)}m\log T$ where m = |E(M)| and T is the number of trips.

Theorem For any $\varepsilon > 0$, MRTT cannot be approximated within $O(n^{1-\varepsilon})$ unless P=NP.

Idea : connect many sources to v_1 and many sinks to w_{m+1} .

Theorem O2O-RTT using at most k trips can be solved in $2^{O(k)}m\log T$ where m = |E(M)| and T is the number of trips.

Theorem For any $\varepsilon > 0$, MRTT cannot be approximated within $O(n^{1-\varepsilon})$ unless P=NP.

Idea : connect many sources to v_1 and many sinks to w_{m+1} .

Theorem O2O-RTT using at most k trips can be solved in $2^{O(k)}m\log T$ where m = |E(M)| and T is the number of trips.

Theorem For any $\varepsilon > 0$, MRTT cannot be approximated within $O(n^{1-\varepsilon})$ unless P=NP.

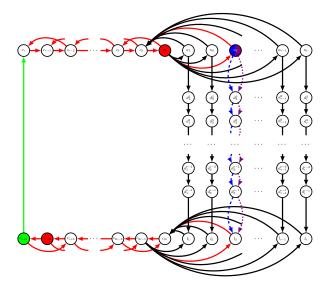
Idea : connect many sources to v_1 and many sinks to w_{m+1} .

Theorem O2O-RTT using at most k trips can be solved in $2^{O(k)}m\log T$ where m = |E(M)| and T is the number of trips.

Strong temporalisabilty

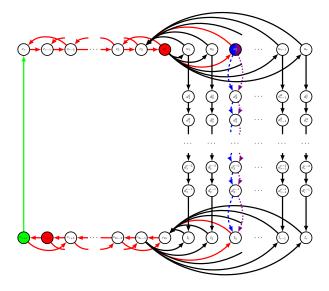
A trip network is strongly temporisable when for each pair $u, v \in V$, there exists a temporalisation such that $u \mathcal{R} v$.

A difficult strongly temporisable network



Bounded reachability : $\sum_{u} |\mathcal{R}(u)| = O(n^{1.5})$ (\sqrt{n} gap).

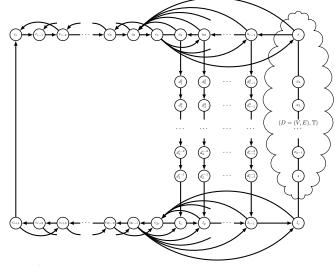
A difficult strongly temporisable network



Bounded reachability : $\sum_{u} |\mathcal{R}(u)| = O(n^{1.5})$ (\sqrt{n} gap).

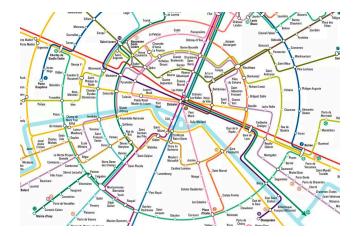
Unapproximability of MRTT

Theorem MRTT cannot be approximated within $\sqrt{n}/12$ unless P=NP even in strongly temporisable trip networks.



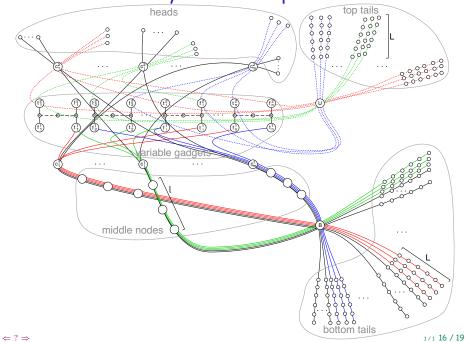
Reduction from O2O-MRTT.

Symmetricity



For every trip $\langle v_1, \dots, v_k \rangle$, there is a reverse trip $\langle v_k, \dots, v_1 \rangle$.

MRTT is hard in symmetric trip networks



Approximability of symmetric trip networks

Fact A symmetric trip network is strongly temporisable iff M is (strongly) connected.

Theorem MRTT can be approximated within 9/2 in strongly temporisable symmetric trip networks.

Idea :

- group trips and reverse trips into pairs,
- compute a centroid pair C, and a partition A, {C}, B of trip pairs,
 - schedule trips pairs in A, {C}, B respectively so that :
 - each node in $V(A \cup \{C\})$ can reach $V(\{C\} \cup B)$.

Approximability of symmetric trip networks

Fact A symmetric trip network is strongly temporisable iff M is (strongly) connected.

Theorem MRTT can be approximated within 9/2 in strongly temporisable symmetric trip networks.

Idea :

• group trips and reverse trips into pairs,

• compute a centroid pair C, and a partition A, {C}, B of trip pairs,

• schedule trips pairs in A, {C}, B respectively so that :

• each node in $V(A \cup \{C\})$ can reach $V(\{C\} \cup B)$.

Approximability of symmetric trip networks

Fact A symmetric trip network is strongly temporisable iff M is (strongly) connected.

Theorem MRTT can be approximated within 9/2 in strongly temporisable symmetric trip networks.

Idea :

• group trips and reverse trips into pairs,

• compute a centroid pair C, and a partition A, {C}, B of trip pairs,

- schedule trips pairs in A, {C}, B respectively so that :
 - each node in $V(A \cup \{C\})$ can reach $V(\{C\} \cup B)$.



All results hold with arbitrary positive delays on edges,

and with fixed waiting times at stops.

Open : varying waiting times can be chosen in the temporalisation.

Open : each trip is duplicated K times.

Open : directed graph temporalisation (more tomorrow).



All results hold with arbitrary positive delays on edges,

and with fixed waiting times at stops.

Open : varying waiting times can be chosen in the temporalisation.

Open : each trip is duplicated K times.

Open : directed graph temporalisation (more tomorrow).



All results hold with arbitrary positive delays on edges,

and with fixed waiting times at stops.

Open : varying waiting times can be chosen in the temporalisation.

Open : each trip is duplicated K times.

Open : directed graph temporalisation (more tomorrow).

Going further

All results hold with arbitrary positive delays on edges,

and with fixed waiting times at stops.

Open : varying waiting times can be chosen in the temporalisation.

Open : each trip is duplicated K times.

Open : directed graph temporalisation (more tomorrow).

Going further

All results hold with arbitrary positive delays on edges,

and with fixed waiting times at stops.

Open : varying waiting times can be chosen in the temporalisation.

Open : each trip is duplicated K times.

Open : directed graph temporalisation (more tomorrow).

Thanks.

Directed graph temporalisation

Define the temporal reachability of a temporal graph as the number of node pairs that are temporally connected.

Problem : given a strongly connected multi-digraph, assign one time label per edge so that temporal reachability is maximal.

or within a constant factor from maximal (approximation).

Define the temporal reachability of a temporal graph as the number of node pairs that are temporally connected.

Problem : given a strongly connected multi-digraph, assign one time label per edge so that temporal reachability is maximal.

or within a constant factor from maximal (approximation).

Define the temporal reachability of a temporal graph as the number of node pairs that are temporally connected.

Problem : given a strongly connected multi-digraph, assign one time label per edge so that temporal reachability is maximal.

or within a constant factor from maximal (approximation).

Undirected graph temporalisation is quite known

Given an undirected graph G, deciding whether there exists an assignment of one time label per edge such that all pairs are temporally connected is NP-complete. [Göbel, Cerdeira, Veldman 1991]

Approximation is obvious : take a spanning tree and assign time labels that connect $(n/2)^2$ pairs.

Related (Gossip/telephone problem [Bumby 1981]) : The minimum number of time labels allowing to temporally connect all pairs is 2n - 2, or 2n - 4 if G has a C_4 (one or two time labels per edge).

Undirected graph temporalisation is quite known

Given an undirected graph G, deciding whether there exists an assignment of one time label per edge such that all pairs are temporally connected is NP-complete. [Göbel, Cerdeira, Veldman 1991]

Approximation is obvious : take a spanning tree and assign time labels that connect $(n/2)^2$ pairs.

Related (Gossip/telephone problem [Bumby 1981]) : The minimum number of time labels allowing to temporally connect all pairs is 2n - 2, or 2n - 4 if G has a C_4 (one or two time labels per edge).

Undirected graph temporalisation is quite known

Given an undirected graph G, deciding whether there exists an assignment of one time label per edge such that all pairs are temporally connected is NP-complete. [Göbel, Cerdeira, Veldman 1991]

Approximation is obvious : take a spanning tree and assign time labels that connect $(n/2)^2$ pairs.

Related (Gossip/telephone problem [Bumby 1981]): The minimum number of time labels allowing to temporally connect all pairs is 2n - 2, or 2n - 4 if G has a C_4 (one or two time labels per edge).

Directed graph temporalisation : what we know

Given a strong digraph D, deciding whether there exists an assignment of one time label per edge such that all pairs are temporally connected is NP-complete. [Unpublished, ask Filippo]

(The above is not implied by the undirected hardness.)

Approximation? : there exists strong digraphs where it is not possible to connect $(n/2)^2$ pairs (but (n/3)(2n/3) is possible).

Directed graph temporalisation : what we know

Given a strong digraph D, deciding whether there exists an assignment of one time label per edge such that all pairs are temporally connected is NP-complete. [Unpublished, ask Filippo]

(The above is not implied by the undirected hardness.)

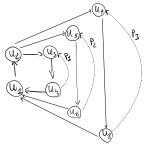
Approximation? : there exists strong digraphs where it is not possible to connect $(n/2)^2$ pairs (but (n/3)(2n/3) is possible).

Directed graph temporalisation : what we know

Given a strong digraph D, deciding whether there exists an assignment of one time label per edge such that all pairs are temporally connected is NP-complete. [Unpublished, ask Filippo]

(The above is not implied by the undirected hardness.)

Approximation? : there exists strong digraphs where it is not possible to connect $(n/2)^2$ pairs (but (n/3)(2n/3) is possible).



Related problem : Find an in-tree and an out-tree with same root that are edge disjoint and have size $\Omega(n)$.

It is NP-hard to decide if a strong digraph has such a pair. [Bang-Jensen 1991]

Conjecture : There exist c such that any c-edge-connected digraph has such a pair. [Thomassen 1989]

Related problem : Find an in-tree and an out-tree with same root that are edge disjoint and have size $\Omega(n)$.

It is NP-hard to decide if a strong digraph has such a pair. [Bang-Jensen 1991]

Conjecture : There exist c such that any c-edge-connected digraph has such a pair. [Thomassen 1989]

Related problem : Find an in-tree and an out-tree with same root that are edge disjoint and have size $\Omega(n)$.

It is NP-hard to decide if a strong digraph has such a pair. [Bang-Jensen 1991]

Conjecture : There exist c such that any c-edge-connected digraph has such a pair. [Thomassen 1989]

Related problem : Find an in-tree and an out-tree with same root that are edge disjoint and have size $\Omega(n)$.

It is NP-hard to decide if a strong digraph has such a pair. [Bang-Jensen 1991]

Conjecture : There exist c such that any c-edge-connected digraph has such a pair. [Thomassen 1989]