# Setting Port Numbers for Fast Graph Exploration 

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## Graph exploration

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## Performance criterion

To minimize the period

## Motivations (1)

## Exploration by mobile agents

- Physical robot: exploration of environments unreachable by humans
- Software agent: network maintenance


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## Exploration by mobile agents

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Equivalence between logic and automata
[Engelfriet, Hoogeboom, STACS 2006]
Through characterization of string, tree or graph languages

- Automata with nested pebbles
- First-order logic with transitive closure


## Motivations (2)

## (undirected st-connectivity)

- $G=\{V, E\}$ an undirected graph
- $s, t \in V$ two vertices of $G$

Are $s$ and $t$ in the same connected component of $G$ ?

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- $L=$ class of problems solvable by deterministic log-space computations
- $\operatorname{SL}(\supseteq \mathrm{L})=$ class of problems solvable by symmetric non-deterministic log-space computations


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> Reingold, STOC 2005
> Undirected ST-Connectivity in Log-Space
> USTCON $\in L \Rightarrow S L=L$

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## Anonymous

- No node labeling
- Local edge labeling


## Example of an anonymous graph



## Mealy automaton (1)



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## Mealy automaton (2)

## Input

- S : current state
- $i$ : input port number
- d : node's degree


## Output

- $S^{\prime}$ : new state
- $j$ : output port number


## Transition function

- $f(S, i, d)=\left(S^{\prime}, j\right)$


## Outline

(1) Introduction
(2) Related work

- Impossibility results
- Exploration of trees
- Exploration with assistance
(3) Our model and results

4) Algorithm/automaton
(5) Conclusion

## Impossibility results (1)

## Budach, Math. Nachrichten, 1978 <br> Automata and Labyrinths

No finite automaton can explore all graphs.

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Automata and Labyrinths
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> Rabin, Seminar talk at Berkeley, 1967
> Maze threading automata

No finite automaton with a finite number of pebbles can explore all graphs.

## Impossibility results (2)

## , Acta Informatica, 1980 <br> Automaten in planaren Graphen

No finite team of finite cooperative automata can explore all (cubic planar) graphs.

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## Rollik, Acta Informatica, 1980

Automaten in planaren Graphen
No finite team of finite cooperative automata can explore all (cubic planar) graphs.

A JAG (Jumping Automaton for Graphs) is a team of finite automata that cooperate constantly. Moreover an automaton can jump to a vertex occupied by another automaton.

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## , SIAMJC, 1980

Space lower bounds for maze threadability on restricted machines

No JAG can explore all graphs.

## Universality for trees

An oblivious automaton (one single state) using the right-hand-on-the-wall rule $(i \mapsto i+1)$ explores all the trees.


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## Coloring nodes

Model

- An oracle colors (labels) the graph to help the automaton.
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## Cohen, Fraigniaud, Ilcinkas, Korman, Peleg, ICALP, 2005

Label-Guided Graph Exploration by a Finite Automaton

- There exist a finite automaton and an algorithm coloring in three colors such that the automaton can explore all graphs.
- There exist a automaton of $O(\log \Delta)$ memory bits and an algorithm coloring in only two colors such that the automaton can explore all graphs of maximum degree $\Delta$.


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> Dobrev, Jansson, Sadakane, Sung, SIROCCO, 2005 Finding Short Right-Hand-on-the-Wall Walks in Graphs
> There exist an algorithm for setting the port numbers, and an oblivious automaton using them, such that the automaton explores all graphs of size $n$ within the period $10 n$.

## Outline

## (1) Introduction

(2) Related work
(3) Our model and results

- Our model
- Results

4. Algorithm/automaton
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## Our model

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- An algorithm sets the port numbers to help the automaton.
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## Question

What is the mimimum function $\pi(n)$ such that there exist an algorithm for setting the local orientation, and a finite automaton using it, such that the automaton explores all graphs of size $n$ within the period $\pi(n)$ ?

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Dobrev et al.

$$
\pi(n) \leq 10 n
$$

## Our results

## Theorem <br> $\pi(n) \leq 4 n-2$

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## More precisely

- Very simple algorithm based on a spanning tree
- Three-state automaton
- Performance independent from the initial state and initial position of the automaton


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## More precisely

- Very simple algorithm based on a spanning tree
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## Additional properties

- Distributed algorithm
- Dynamic environment


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## Algorithm

## Port numbers compatible with a spanning tree $T$

- edge $e$ is in $T \Longleftrightarrow$ at least one of its port numbers is 1 ;
- the edges belonging to $T$ have the smallest port numbers.


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## Automaton

## States

- N: Normal
- T: Test
- B: Backtrack


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## Transition function

$$
\begin{aligned}
& f(N, i, d)= \begin{cases}(N, 1) & \text { if } i=d \\
(T, i+1) & \text { if } i \neq d\end{cases} \\
& f(T, i, d)= \begin{cases}(N, 1) & \text { if } i=1 \text { and } d=1 \\
(T, i+1) & \text { if } i=1 \text { and } d \neq 1 \\
(B, i) & \text { if } i \neq 1\end{cases} \\
& f(B, i, d)=(N, 1)
\end{aligned}
$$

## Example

- If on a tree-edge: right-hand-on-the-wall
- If not on a tree-edge: backtrack



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## Open problem

## Conclusion <br> $\pi(n) \leq 4 n-2$

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## Conjecture

$\pi(n)=4 n-O(1)$

## Open problem

## Conclusion

$\pi(n) \leq 4 n-2$
Conjecture
$\pi(n)=4 n-O(1)$

## Open problems

- $\pi(n)$ when the automaton is restricted to be oblivious?
- Find a fully self-stabilizing pair algorithm/automaton

