

# A Contraction Method to Decide MSO Theories of Deterministic Trees

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## What is the talk about?

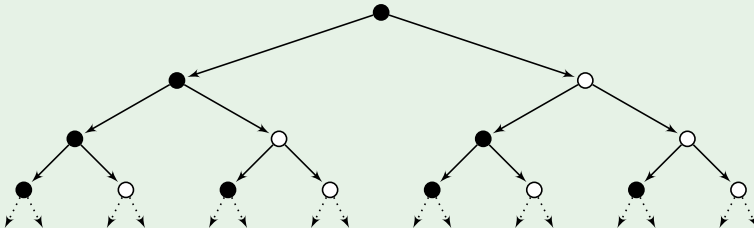
We shall consider the **model-checking** problem for **Monadic Second-Order (MSO) logic** over **deterministic colored trees**.

### Example

To decide whether the MSO formula

$$\varphi(X) = X(\text{root}) \wedge \forall x, y. (\text{left\_child}(x, y) \rightarrow X(y))$$

holds in the binary tree by interpreting the variable  $X$  with the set of *black colored vertices*:



## Outline

- ① *Short introduction*  
(the **automaton-based approach** to model-checking)
- ② *The proposed method*  
(extension of **Elgot-Rabins's contraction method** to trees)
- ③ *Application examples*  
(**reducible trees**, closure properties, and open problems)

## Theorem (Rabin '69)

For every MSO formula  $\varphi(X_1, \dots, X_n)$ , we can compute a Rabin tree automaton  $\mathcal{A}$  over the alphabet  $C = \mathcal{P}(\{1, \dots, n\})$  (and vice versa) such that, for every  $C$ -colored tree  $T$ ,

$$T \models \varphi(X_1, \dots, X_n) \quad \Leftrightarrow \quad T \in \mathcal{L}(\mathcal{A})$$

(read  $\varphi(X_1, \dots, X_n)$  holds in  $T$  iff  $\mathcal{A}$  accepts  $T$ ).

## Definition

The **acceptance problem**  $Acc_T$  of a tree  $T$  is the problem of deciding whether, for any given tree automaton  $\mathcal{A}$ ,  $T \in \mathcal{L}(\mathcal{A})$ .

## Corollary

The model-checking problem of a tree  $T$  is reducible to the acceptance problem of  $T$ .

## Fact

For any **regular** tree  $T$ ,  $Acc_T$  is decidable (simply test, for any automaton  $\mathcal{A}$ , whether the language  $\mathcal{L}(\mathcal{A}) \cap \{T\}$  is non-empty).

## Problem

What about non-regular trees?

## Solution idea

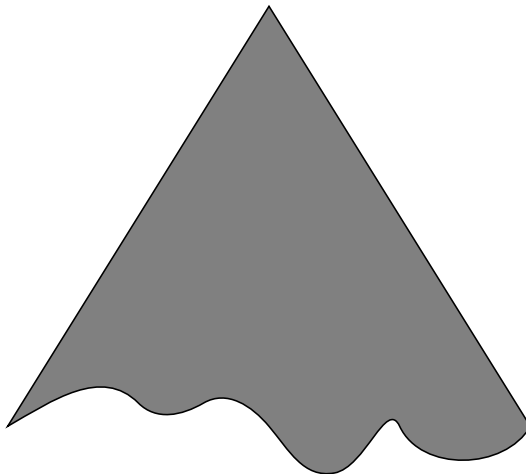
Generalize “**Contraction method**” (Elgot-Rabin '66) to trees.

Given a (non-regular) tree  $T$  and an automaton  $\mathcal{A}$ :

- 1 decompose  $T$  into **factors**,
- 2 ‘distill’ the relevant **features** of each factor  $F$  w.r.t. the behaviors of  $\mathcal{A}$  and collect them into an  **$\mathcal{A}$ -type**,
- 3 reason on the **contraction** tree (i.e., a tree-shaped arrangement of  $\mathcal{A}$ -types).

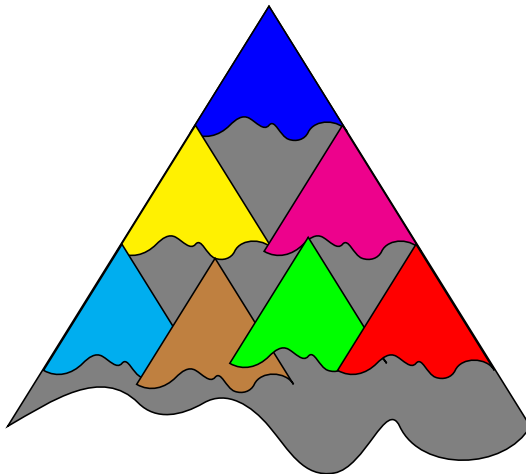
*A picture of the method:*

A tree automaton can have **similar behaviors** on different trees ...



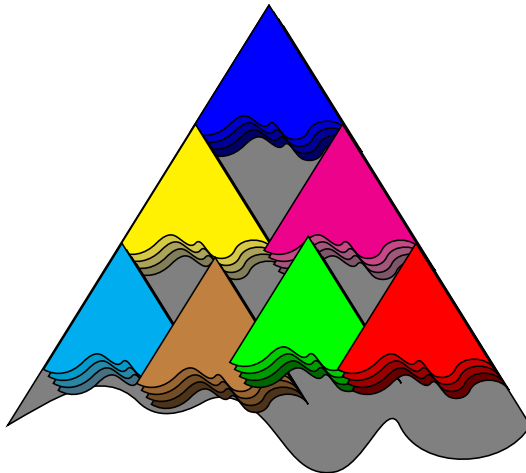
*A picture of the method:*

Given a tree  $T$  and an automaton  $\mathcal{A}$ , decompose  $T$  into **factors** ...



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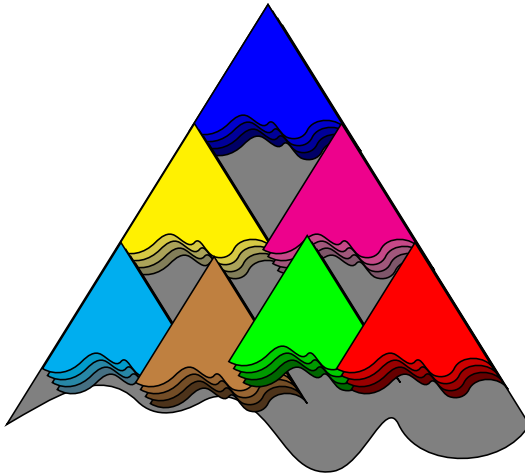
... and then consider the **equivalence classes**  
induced by the behavior of  $\mathcal{A}$  on each factor.





*A picture of the method:*

⇒ We can replace  $\mathcal{A}$  with an automaton  $\vec{\mathcal{A}}$  that runs on the (possibly regular) abstracted tree and mimics  $\mathcal{A}$ .



## Basic ingredients

The following notions will be briefly explained in the following:

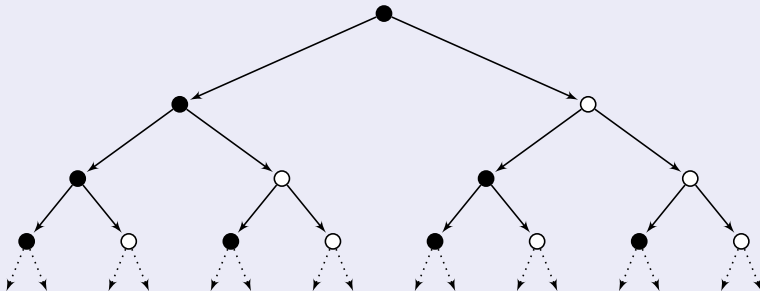
- **factorization**  $\Pi$  of a tree  $T$ ,
- **marked factor**  $\Pi^+(v)$ ,
- $\mathcal{A}$ -**type**  $[\Pi^+(v)]_{\mathcal{A}}$ ,
- $\mathcal{A}$ -**contraction**  $\vec{T}$ .

We will use the above notions to reduce an instance of  $Acc_T$  to a (hopefully simpler) instance of  $Acc_{\vec{T}}$  (for instance, the case where  $\vec{T}$  is a regular tree).

## Definition

A **factorization** of a tree  $T$  is an *uncolored* tree  $\Pi$  such that:

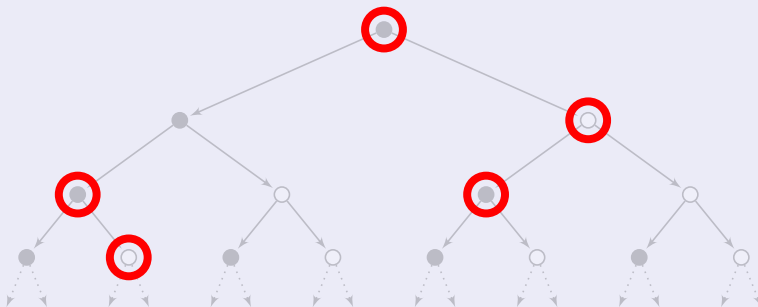
- $Dom(\Pi)$  is a subset of  $Dom(T)$  that includes the root,
- the edges are given by the *ancestor relation*  $\sqsubseteq$  of  $T$ ,
- the edge labels are arbitrarily chosen from a finite set  $B$ .



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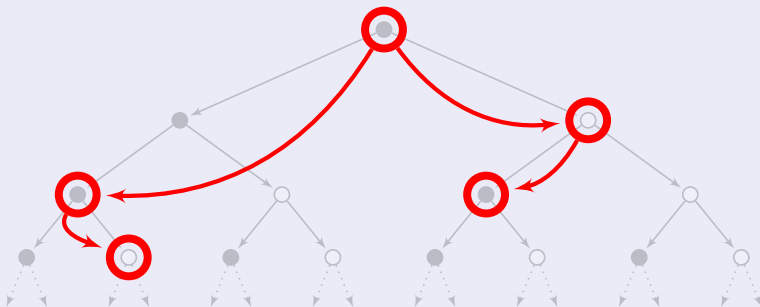
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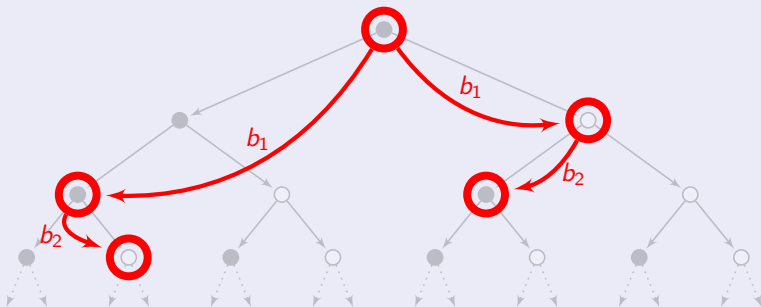
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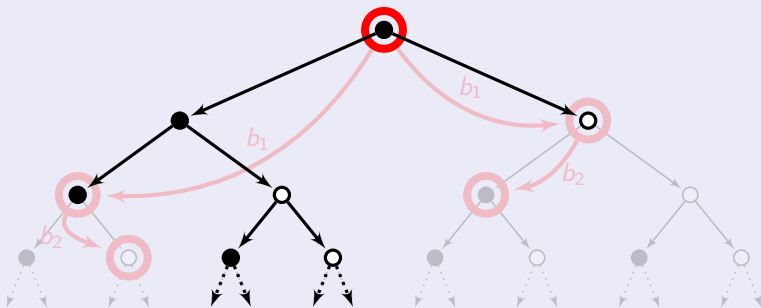
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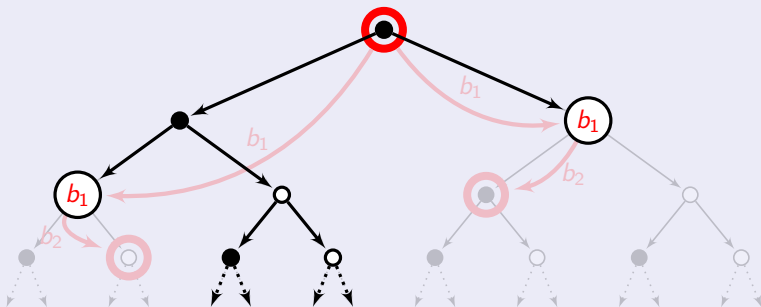
For every vertex  $v$  of  $\Pi$ , the **factor  $\Pi(v)$  of  $T$  in  $v$**  is the subgraph of  $T$  induced by the set

$$\{w \in \mathcal{D}om(T) : v \sqsubseteq w \sqsubseteq v' \text{ for all successors } v' \text{ of } v \text{ in } \Pi\}$$



## Definition

For every vertex  $v$  of  $\Pi$ , the **marked factor**  $\Pi^+(v)$  is obtained from the (unmarked) factor  $\Pi(v)$  by *recoloring* each leaf  $w$  with *the label of the incoming edge of  $\Pi$* .



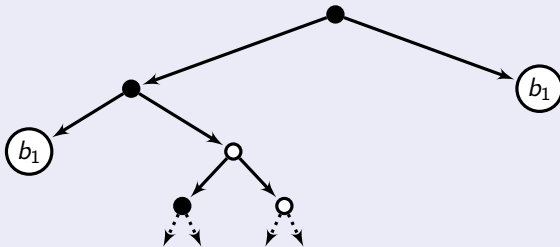


## Definition

Given an automaton  $\mathcal{A}$  and a marked factor  $F$ , the  $\mathcal{A}$ -type  $[F]_{\mathcal{A}}$  is the set of triples of the form

$$\left( \begin{array}{l} R(\text{root}) \\ \{ \text{InfOcc}(R|\pi) : \pi \text{ branch of } F \} \\ \{ (F(w), R(w), \text{Occ}(R|w)) : w \text{ leaf of } F \} \end{array} \right)$$

over all possible partial runs  $R$  of  $\mathcal{A}$  on  $F$ .

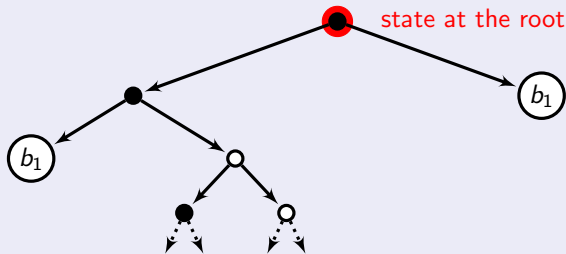


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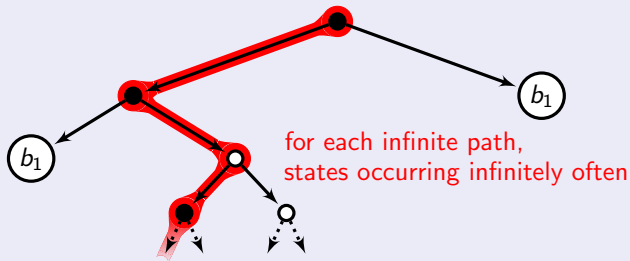


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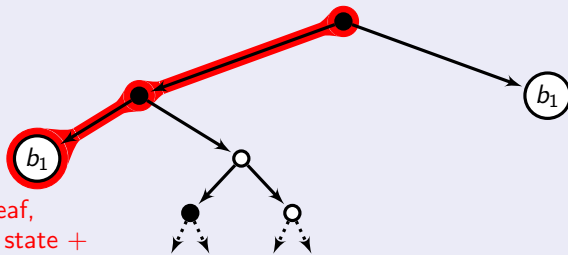


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over all possible partial runs  $R$  of  $\mathcal{A}$  on  $F$ .



for each leaf,  
marker + state +  
states along access path

## Proposition

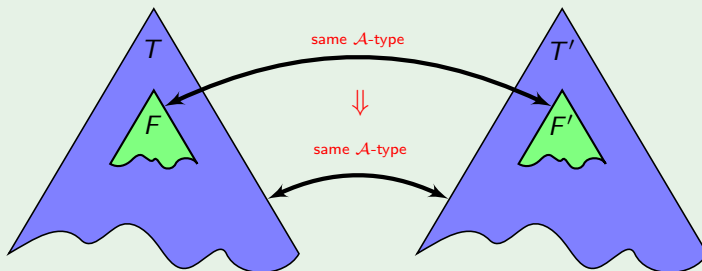
The equivalence relation induced by  $\mathcal{A}$ -types is *compatible with second-order tree substitutions*.

## Intuitive explanation

Consider a tree  $T$  and a factor  $F$  inside it.

Take  $F'$  such that  $[F']_{\mathcal{A}} = [F]_{\mathcal{A}}$  and let  $T' = T[[F/F']]$ .

Then  $[T']_{\mathcal{A}} = [T]_{\mathcal{A}}$ .



## Remarks

We shall see that  $\mathcal{A}$ -types capture the concept of **indistinguishability** of trees w.r.t. the automaton  $\mathcal{A}$ .

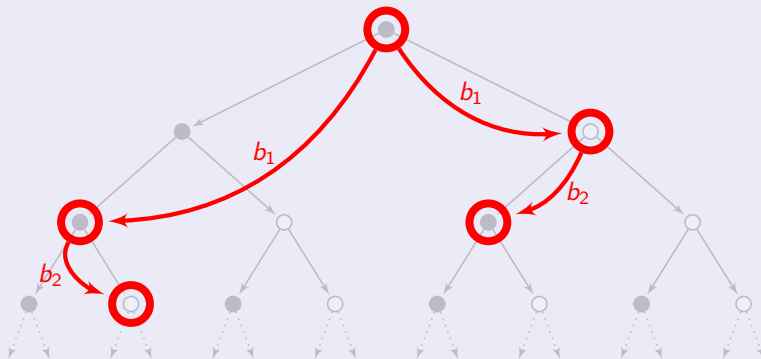
Moreover, the amount of information stored in an  $\mathcal{A}$ -type is **bounded**.

This implies that:

- there exist *only finitely many*  $\mathcal{A}$ -types (equivalently, the automaton  $\mathcal{A}$  can distinguish between only finitely many classes of trees),
- we can see each  $\mathcal{A}$ -type as a *color*,
- we can arrange the  $\mathcal{A}$ -types of the factors of a tree  $T$  in a colored tree structure  $\vec{T}$ , called the  **$\mathcal{A}$ -contraction**.

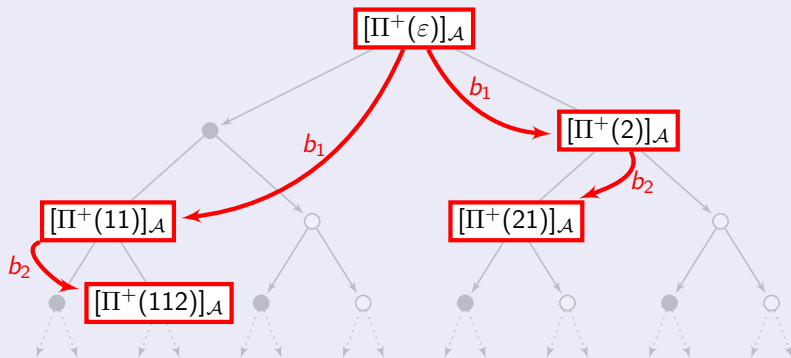
## Definition

Given a tree  $T$ , an automaton  $\mathcal{A}$ , and a factorization  $\Pi$  of  $T$ , the  $\mathcal{A}$ -**contraction**  $\vec{T}$  of  $T$  is the tree obtained from  $\Pi$  by coloring each vertex  $v$  with the  $\mathcal{A}$ -type  $[\Pi^+(v)]_{\mathcal{A}}$ .



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## Remark

In the general case, a contraction can be a **non-deterministic** tree.

In order to reason by means of Rabin automata, we need to identify contractions with suitable deterministic trees.

## Definition

An  $\mathcal{A}$ -contraction is said to be **valid** if it is **bisimilar to a deterministic tree**.

From now on, we restrict ourselves to *valid contractions only*...

## Theorem (Main result)

Given a (valid)  $\mathcal{A}$ -contraction  $\vec{T}$  of  $T$ , we can build a suitable automaton  $\vec{\mathcal{A}}$ , running on  $\vec{T}$ , such that

$$\vec{T} \in \mathcal{L}(\vec{\mathcal{A}}) \quad \Leftrightarrow \quad T \in \mathcal{L}(\mathcal{A}).$$

## Proof idea

Define  $\vec{\mathcal{A}}$  in such a way that it *mimics* the computations of  $\mathcal{A}$  on  $T$  at a “coarser level”:

- the input alphabet of  $\vec{\mathcal{A}}$  is the set of all  $\mathcal{A}$ -types
- the states of  $\vec{\mathcal{A}}$  encode the finite amount of information processed by  $\mathcal{A}$  up to a certain point,
- the transitions of  $\vec{\mathcal{A}}$  compute new states by “merging” the information of the current state with the information provided by the input symbol (i.e., the  $\mathcal{A}$ -type of the current factor).

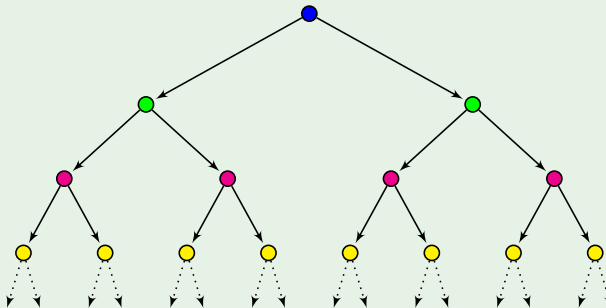
## Application example

Let  $T$  be a tree with *homogeneously-colored levels*,

and  $\Pi$  the factorization of  $T$  with  $\text{Dom}(\Pi) = \text{Dom}(T)$ .

Consider now the marked factors at each level: *their  $\mathcal{A}$ -types uniquely depends on the color of the level they belong to.*

$\Rightarrow$  The  $\mathcal{A}$ -contraction  $\vec{T}$  of  $T$  is bisimilar to a colored line  $L$ .

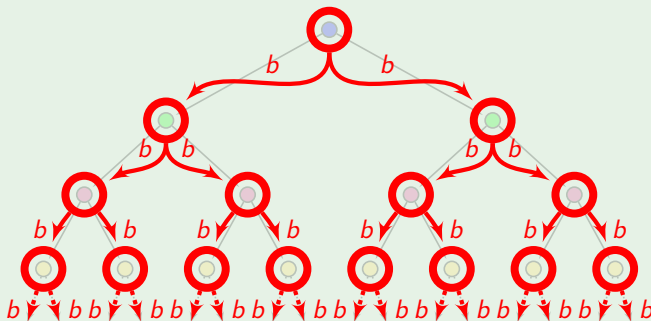


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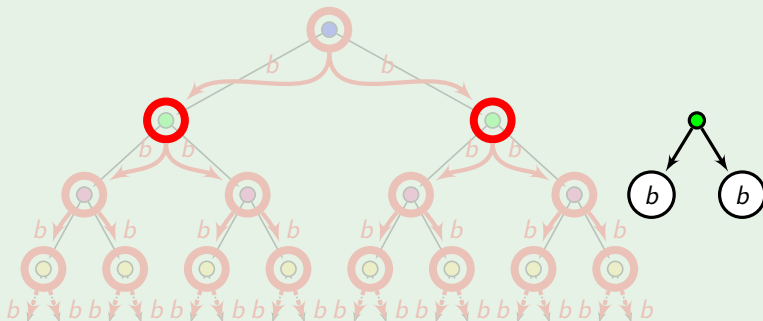


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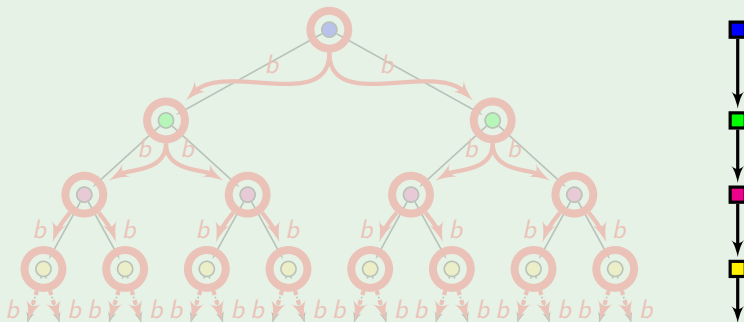
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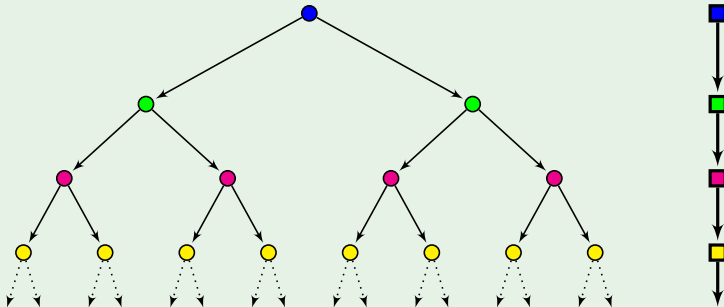
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## Application example

In this way we proved a simplified version of [Muchnik's Theorem](#):

$Acc_T$  is reducible to  $Acc_L$ .



One can also **iterate reductions** in order to show that the acceptance problem of a tree  $T$  is decidable ...

### Example

Consider the problem of deciding if  $T \in \mathcal{L}(\mathcal{A})$ :

If  $T$  has an  $\mathcal{A}$ -contraction  $\vec{T}$ , and

$\vec{T}$  has a *regular*  $\vec{\mathcal{A}}$ -contraction  $\vec{\vec{T}}$

Then we can decide if  $\vec{\vec{T}} \in \mathcal{L}(\vec{\vec{\mathcal{A}}})$ ,  $\vec{T} \in \mathcal{L}(\vec{\mathcal{A}})$ , and  $T \in \mathcal{L}(\mathcal{A})$ .



## Definition

It comes natural to define a

**hierarchy of reducible trees:**

- **rank 0 trees** := **regular trees**
- **rank  $n + 1$  trees** := trees enjoying a **rank  $n$   $\mathcal{A}$ -contraction**,  
for any automaton  $\mathcal{A}$ .

## Corollary

*The acceptance problem of any reducible tree is decidable.*

## Theorem

*Rank  $n$  trees are closed under the following operations:*

- **rational colorings**

*specified by regular path expressions,  
in a similar way to inverse rational mappings  
(alternative specifications in terms of Mealy tree automata)*

- **rational colorings with bounded lookahead**

*rational colorings extended with the facility of inspecting the  
subtree issued from current position, up to bounded depth*

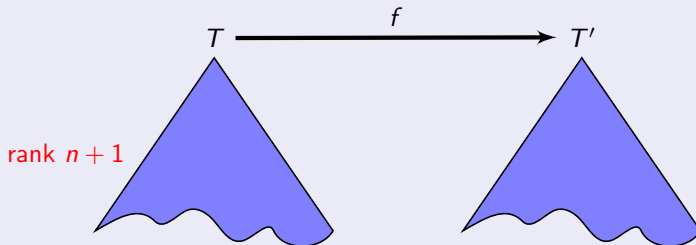
- **regular tree morphisms**

*specified by a tuple of regular trees  $F_{c_1}, \dots, F_{c_k}$   
and mapping an input tree  $T$  to  $T \llbracket c_1/F_{c_1}, \dots, c_k/F_{c_k} \rrbracket$*

⇒ **top-down tree transducers with bounded lookahead**  
*equivalent to functional compositions of rational colorings  
with bounded lookahead and regular tree morphisms.*

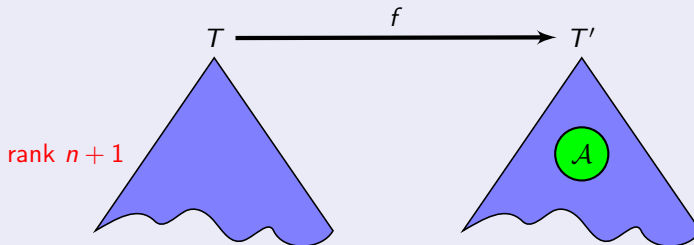
## Proof idea

By **induction on the rank  $n$**  of the tree  $T$  (case  $n = 0$  is trivial...).



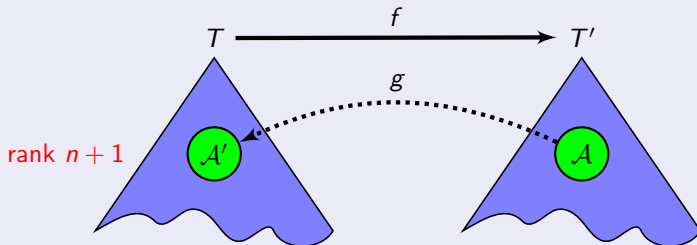
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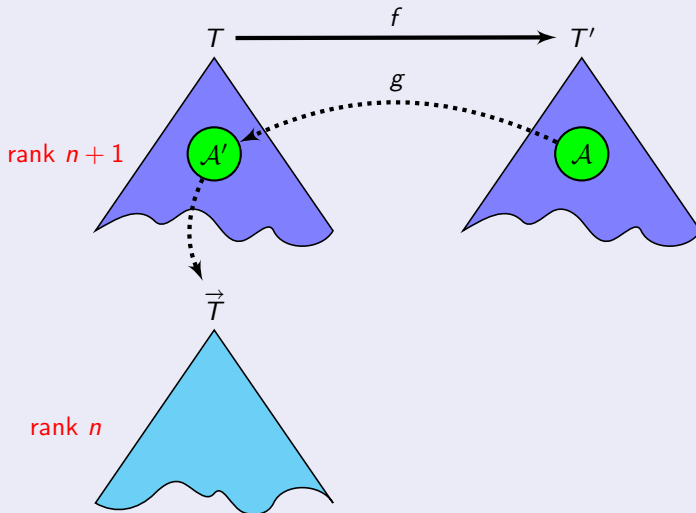
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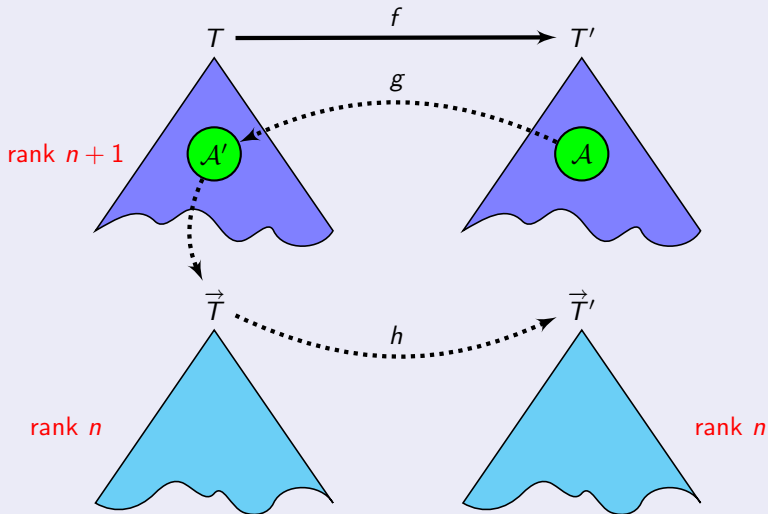
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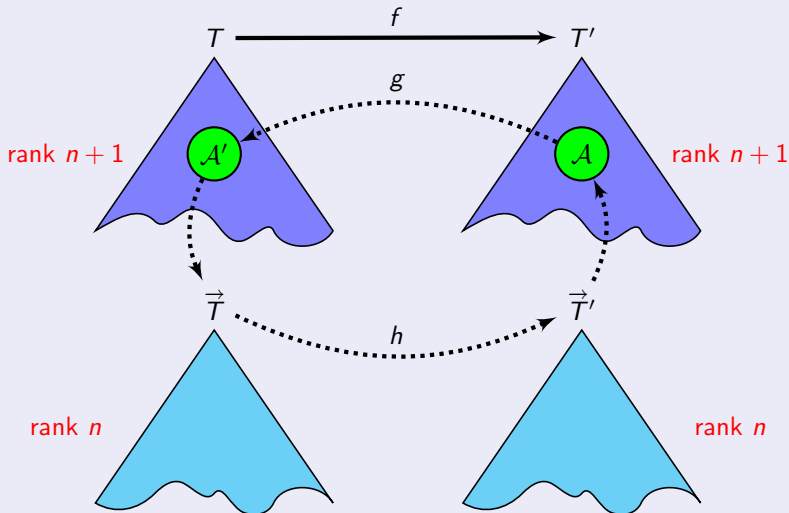
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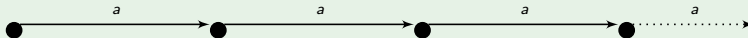
## Theorem

The class of reducible trees is closed under the operation of **unfolding with backward edges and loops** *BackUnfolding*.

More precisely, for every  $n \in \mathbb{N}$ ,  
*if  $T$  is a rank  $n$  tree, then  $\text{BackUnfolding}(T)$  is a rank  $n + 1$  tree.*

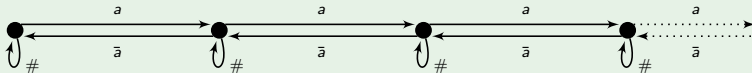
## Proof by example

As a simple case, consider the **semiinfinite line**  $L$  (a rank 0 tree).  
We have to show that  $T = \text{BackUnfolding}(L)$  is a rank 1 tree.



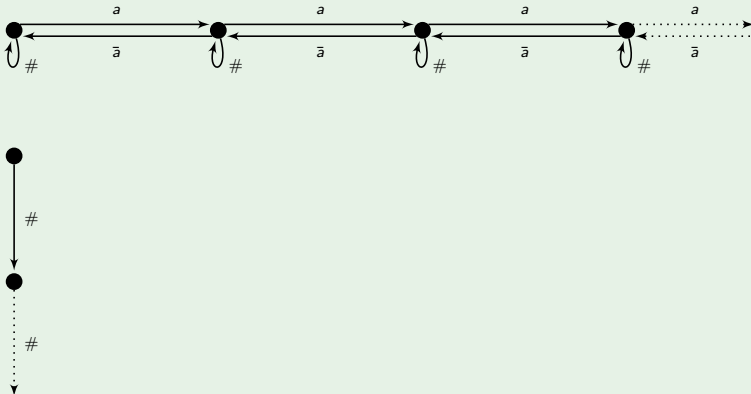
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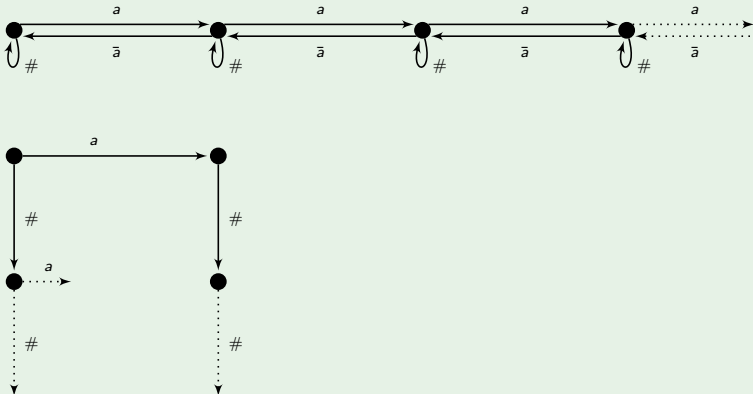
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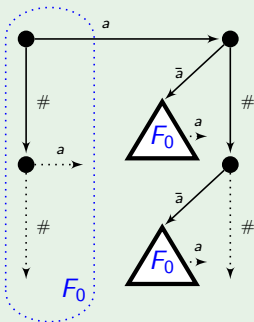
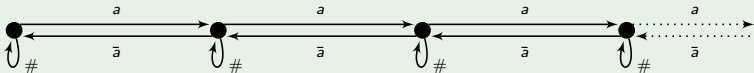
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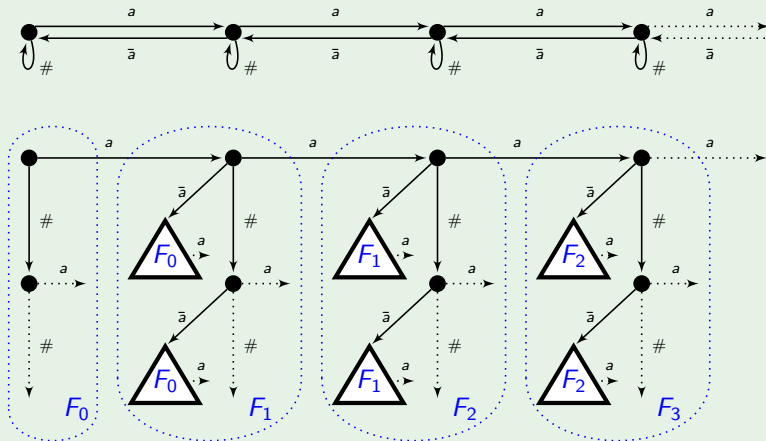
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## Proof by example

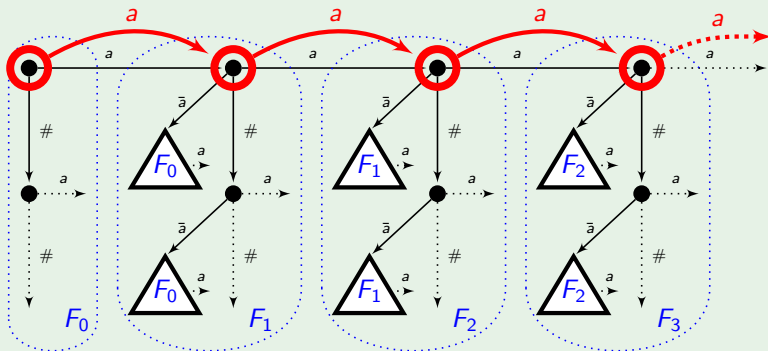
As a simple case, consider the **semiinfinite line**  $L$  (a rank 0 tree).  
 We have to show that  $T = \text{BackUnfolding}(L)$  is a rank 1 tree.



## Proof by example

Let  $\Pi$  be the factorization of  $T$  such that  $\text{Dom}(\Pi) = a^*$ . Every marked factor is obtained from its predecessor via a **substitution**:

$$F_{n+1} = \text{Unfolding} \left( \begin{array}{c} \textcircled{x} \xrightarrow{a} \bullet \xrightarrow{a} \textcircled{a} \\ \xleftarrow{\bar{a}} \quad \uparrow \\ \quad \quad \quad \# \end{array} \right) \llbracket x / F_n \rrbracket.$$

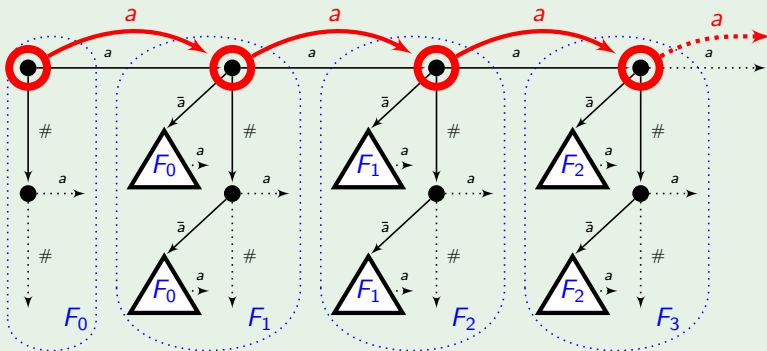




## Proof by example

⇒ The sequence of the  $\mathcal{A}$ -types  $t_n := [F_n]_{\mathcal{A}}$  of the marked factors can be recursively characterized as follows:

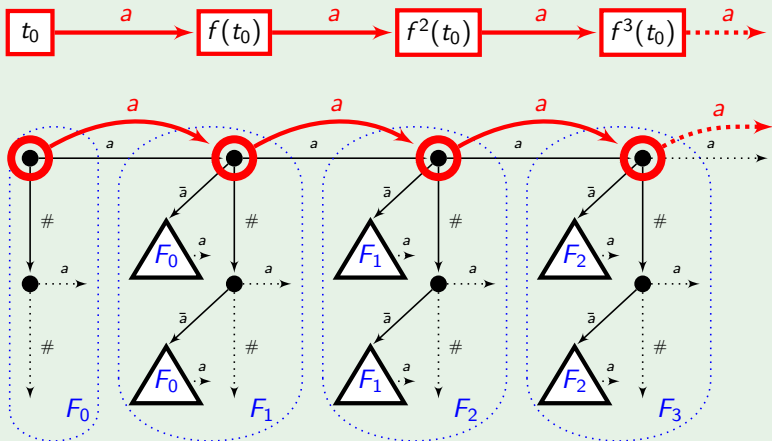
$$\begin{cases} t_0 = [F_0]_{\mathcal{A}} \\ t_{n+1} = f(t_n) \quad (\text{for a suitable function } f) \end{cases}$$



## Proof by example

$\Rightarrow$  The  $\mathcal{A}$ -contraction  $\vec{T}$  of  $T = \text{BackUnfolding}(L)$  is a *rational coloring* of  $L$ , thus a rank 0 tree.

$\Rightarrow T$  is a rank 1 tree.



## Corollary

Reducible trees contain the deterministic trees obtained from regular trees via **unfoldings** and **inverse finite mappings** (see *Caucal '02*).

## Proof idea

Exploit the following facts:

- ① given an inverse finite mapping  $g^{-1}$  and a tree  $T$ , there is an inverse finite mapping  $h^{-1}$  that **preserves bisimilarity** and such that  $Unfolding(g^{-1}(T)) = h^{-1}(BackUnfolding(T))$  (e.g., for every label  $a$ , define  $h(a) := g(a)[\varepsilon/\#]$ ),
- ②  $h^{-1}$  can be implemented by a top-down tree transducer with bounded lookahead (see *Colcombet and Löding '04*),
- ③ reducible trees are closed under transducers with bounded lookahead and unfoldings with backward edges and loops.

### Open problem / Conjecture

Generalize closure properties of reducible trees to **rational colorings with rational lookahead**.

⇒ This would allow us to capture all the deterministic trees in the **Caucal hierarchy**.

Other open problems:

- to establish whether the hierarchy of reducible trees is *strictly increasing* or not,
- to generalize the approach towards *colored graphs*.