

# Toward Symbolic Verification of Programs Handling Pointers

Sébastien Bardin

Alain Finkel

David Nowak

LSV, CNRS & ENS Cachan, France

{bardin, finkel, nowak}@lsv.ens-cachan.fr

## Programs Handling Pointers

- Pointers are useful but dangerous.
- They cannot always be avoided in critical systems.
- Verification is difficult because of **aliasing**.
- We aim at verifying that **segmentation fault** or **memory leak** will not happen under the following hypotheses:
  - we do not consider data;
  - we do not consider pointer arithmetic;
  - at first, we only consider linked lists.

# Verification of programs handling pointers

## Shape analysis

Sagiv, Reps and Wilhelm, POPL'99

## Pointer assertion logic

Jensen, Joergensen, Klarlund and Schwartzbach, PLDI '97

## Separation logic

Reynolds, Millennial Perspectives in Computer Science, 2000

O'Hearn, Reynolds and Yang, CSL'01

## pointer alias analysis, points-to analysis

Many many papers

## Model checking

No paper

## Model checking

- Model checking attempts to reply automatically to questions of the form:

Does my model  $\mathcal{M}$  satisfy my property  $\varphi$ ?

- In case  $\varphi$  is a safety property, this amounts to a **reachability** question in the model  $\mathcal{M}$ :

$$\text{Reachable states} \cap \text{Bad states} = \emptyset$$

# Infinite state systems

- A method to help termination of the model checking algorithm is needed.

- widening (overapproximation, terminates)

- **acceleration** (exact, semi-algorithm)

It consists in computing in one step the effect of an arbitrary number of executions of a transition.

- Acceleration techniques strongly depend on symbolic representation

- computable **canonical form**

- closure under **union**, union computable

- inclusion decidable

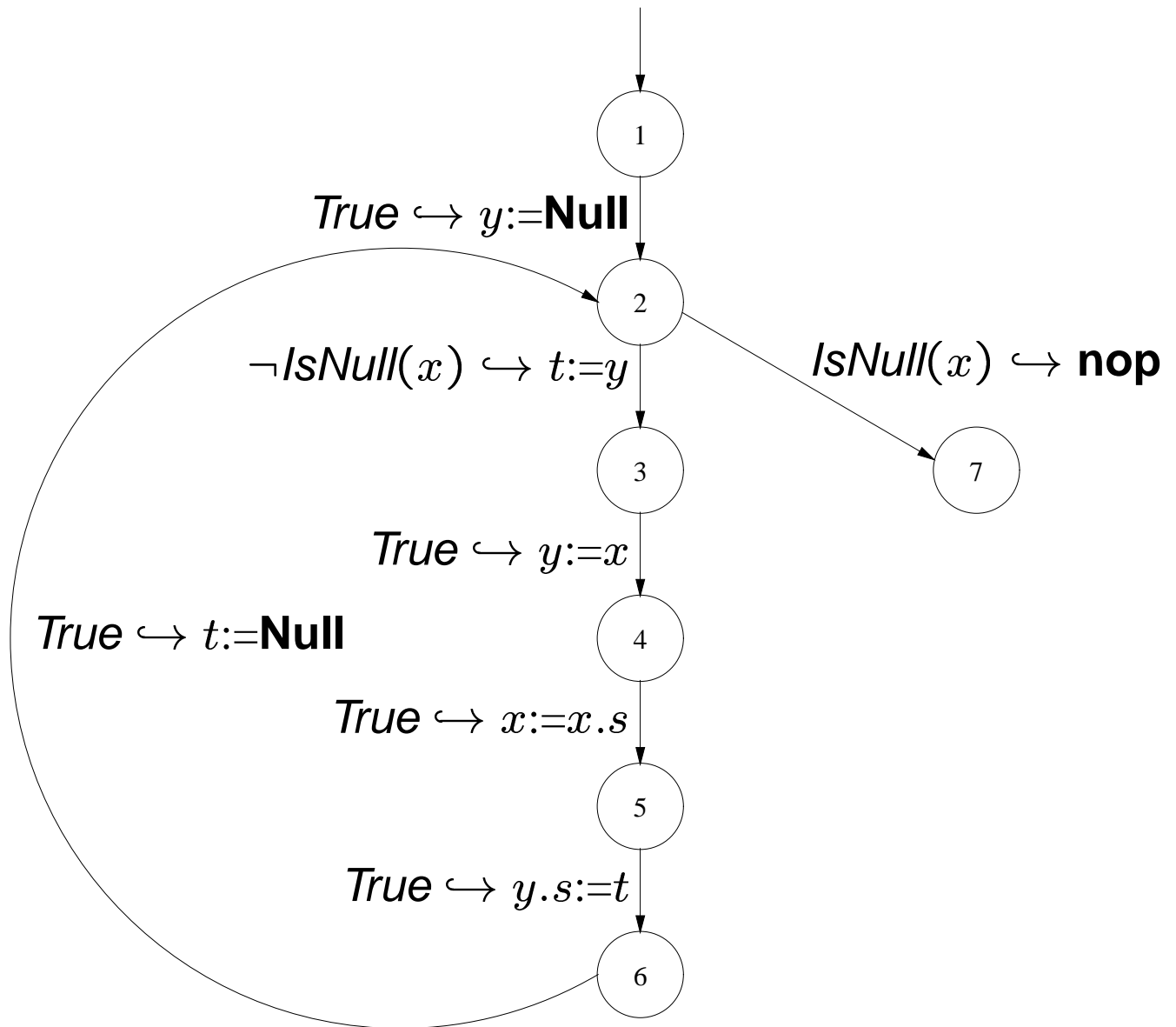
- efficiency

## An example of C program handling pointers

```
/* list.h */
typedef struct node
{
    struct node* n;
    int data;
}* List;

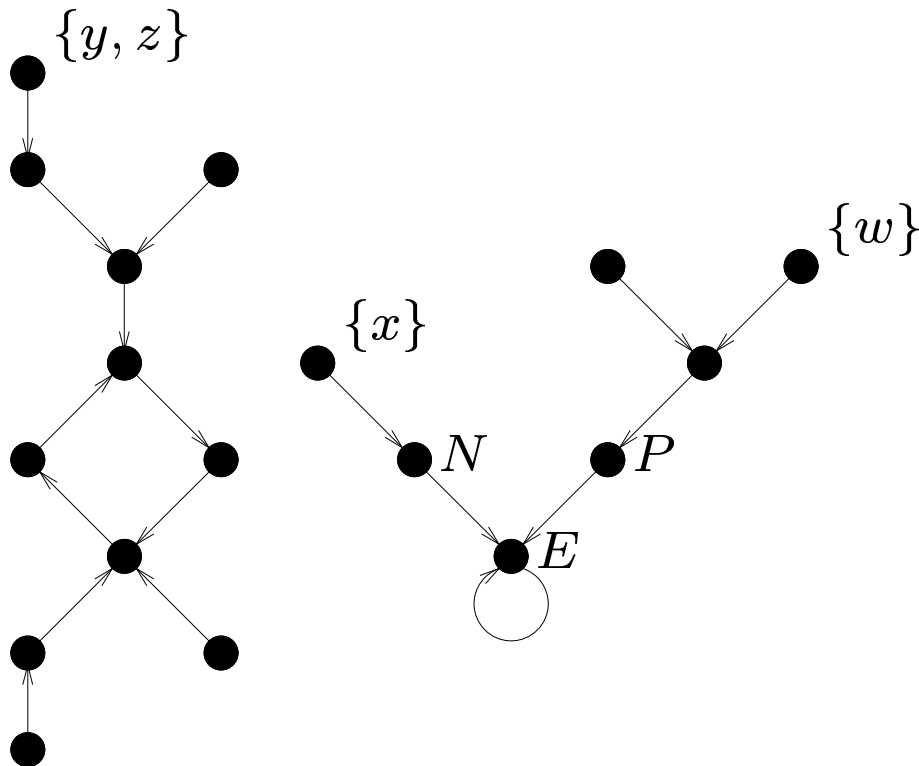
/* reverse.c */
#include ``list.h``
List reverse(List x) {
    List y,t;
    y = NULL;
    while (x!=NULL) {
        t=y;
        y=x;
        x=x->n;
        y->n=t;
        t=NULL;
    }
    return y;
}
```

# Pointer automaton



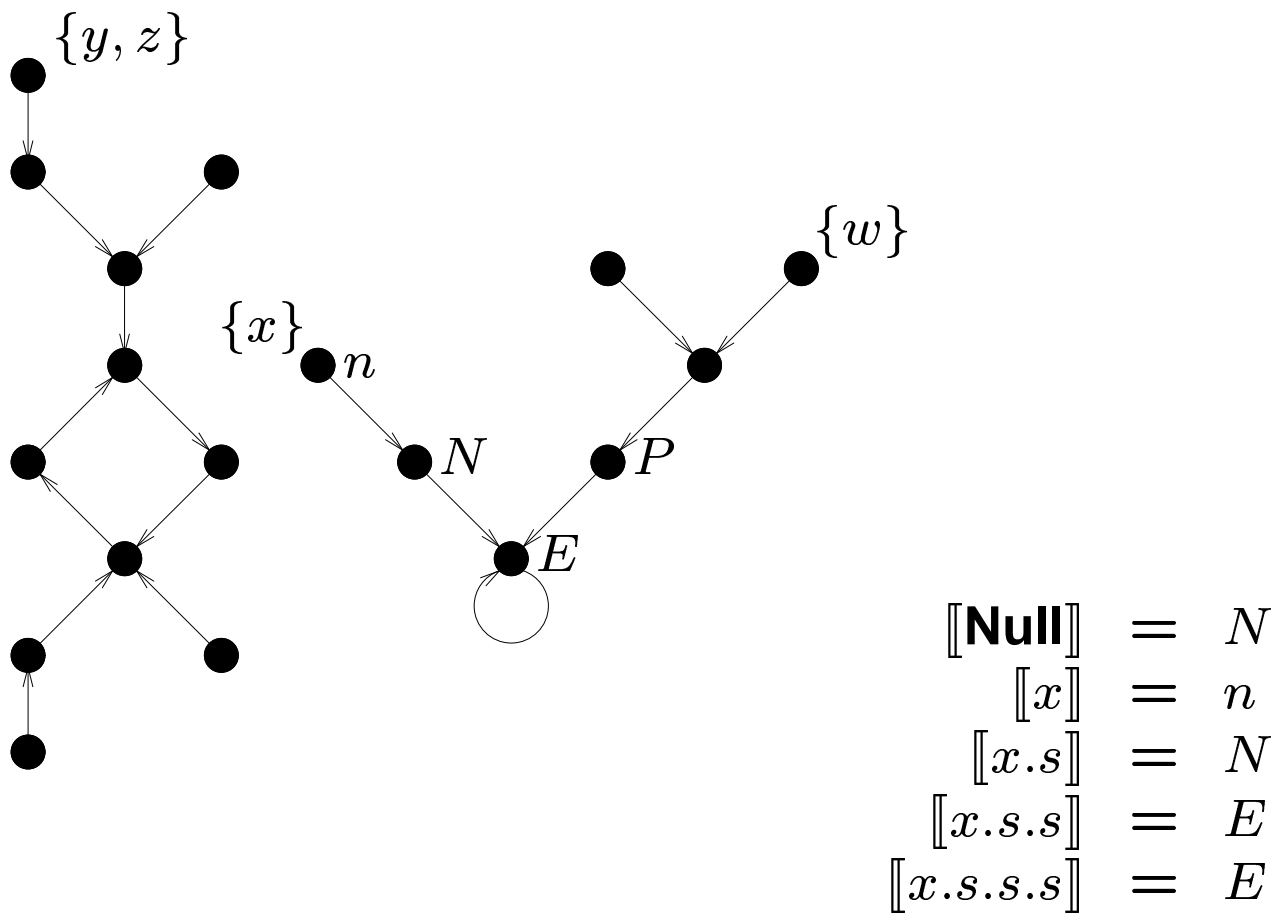
The semantics of a pointer automaton is given in terms of a transition system whose states are memory graphs.

A memory graph is either *SegF* or a graph such as



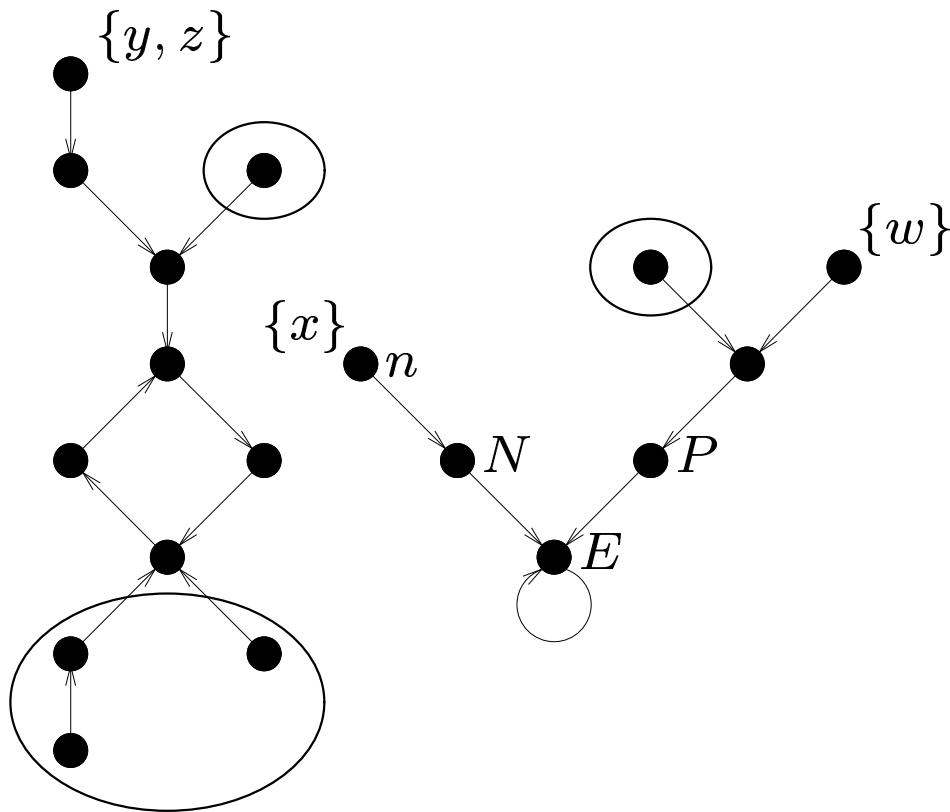
- Black points represent memory cells. Edges represent pointers.
- Each memory cell is labelled by the set of pointer variables which point to this cell.
- The output degree of each node is exactly 1: we only consider linked lists.
- Transition systems with memory graphs as states will be in general infinite.





- Here  $x$  is a well-formed linked list of length 1.
- $N$ ,  $P$  and  $E$  are special nodes which do not denote real memory cells:
  - $N$  (Null) denotes null pointer expressions such as **Null** or  $x.s$ .
  - $P$  (Pit) denotes deallocated pointer expressions such as  $w.s.s$ .
  - $E$  (Error) denotes meaningless pointer expressions such as **Null**. $s$ ,  $x.s.s$ ,  $x.s.s.s$  or  $w.s.s.s$ .

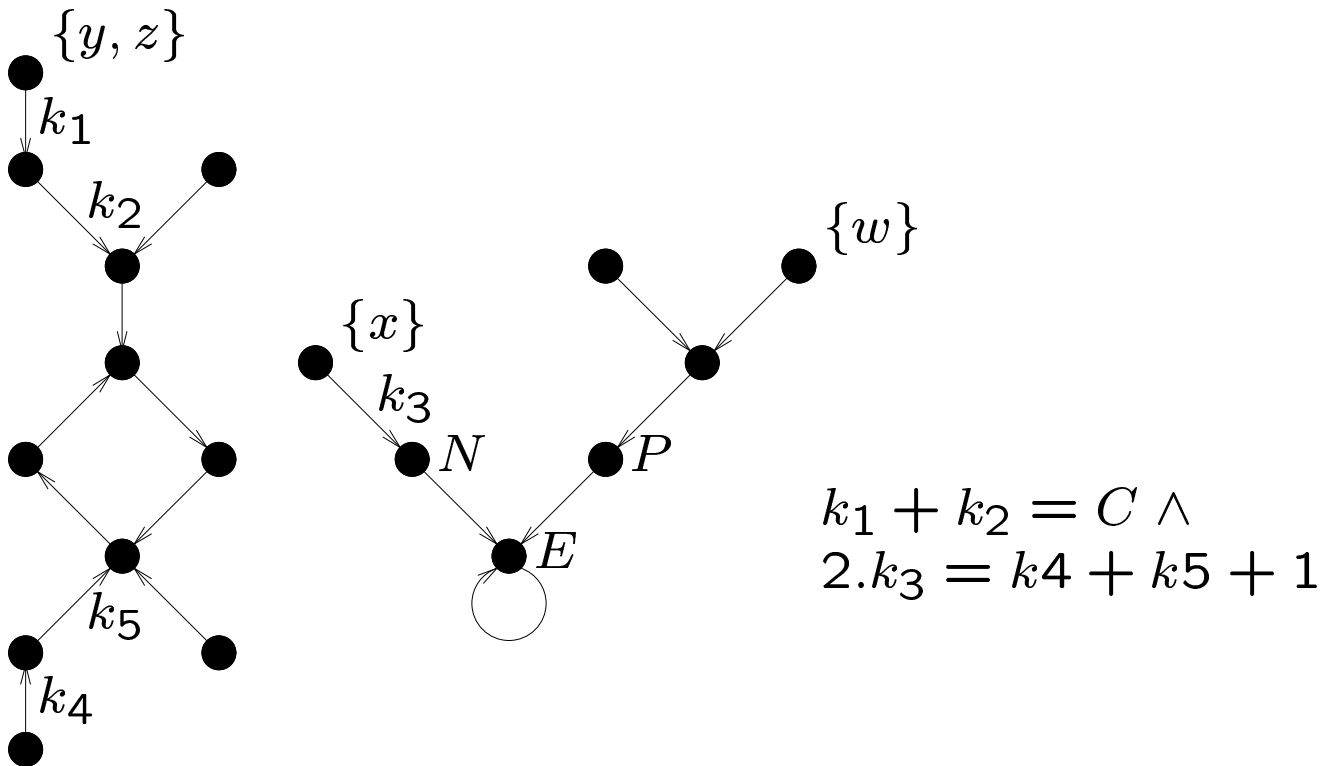
## Dead nodes



A **dead node** is a node which cannot be reached from a node labelled by a non-empty set of variables.

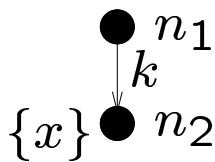
Presence of dead nodes means there is a **memory leak**.

An SMS is a finite set of atomic SMSs such as

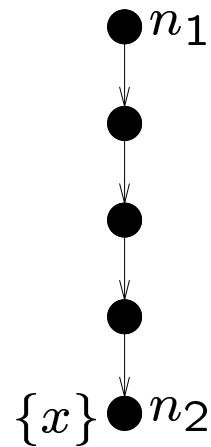


- Edges are labelled by counter variables which represent the number of pointers between the two nodes.
- Counters are constrained by a Presburger formula. Unconstrained counters are omitted.
- Counters labelling edges  $(N, E)$ ,  $(P, E)$  and  $(E, E)$  are implicitly equal to 1 (in all SMSs).
- An SMS  $M$  represents an infinite set  $\gamma(M)$  of memory graphs.

# Assignment



$$v(k) = 4$$



- An assignment satisfying a formula  $\phi$  is a valuation function  $v$  for counters such that  $\phi[k_i := v(k_i)]$  is true.
- The assignment of an SMS  $(G, \phi)$  w.r.t.  $v$  is the memory graph  $G'$  built from  $G$  where each edge labelled by a counter variable  $k$  is replaced by a chain of  $v(k)$  edges.

# Concretization

## Atomic SMSs

- $\gamma(G, \phi)$ , where  $G$  is not  $SegF$ , is the set of all possible assignments of  $(G, \phi)$ .
- $\gamma(SegF, \phi) = \begin{cases} \{SegF\} & \text{if } \phi \text{ is satisfiable} \\ \emptyset & \text{otherwise} \end{cases}$

## SMSs

- $\gamma(\{M_1, \dots, M_n\}) = \bigcup_{i=1}^n \gamma(M_i)$   
where  $M_1, \dots, M_n$  are atomic SMSs.

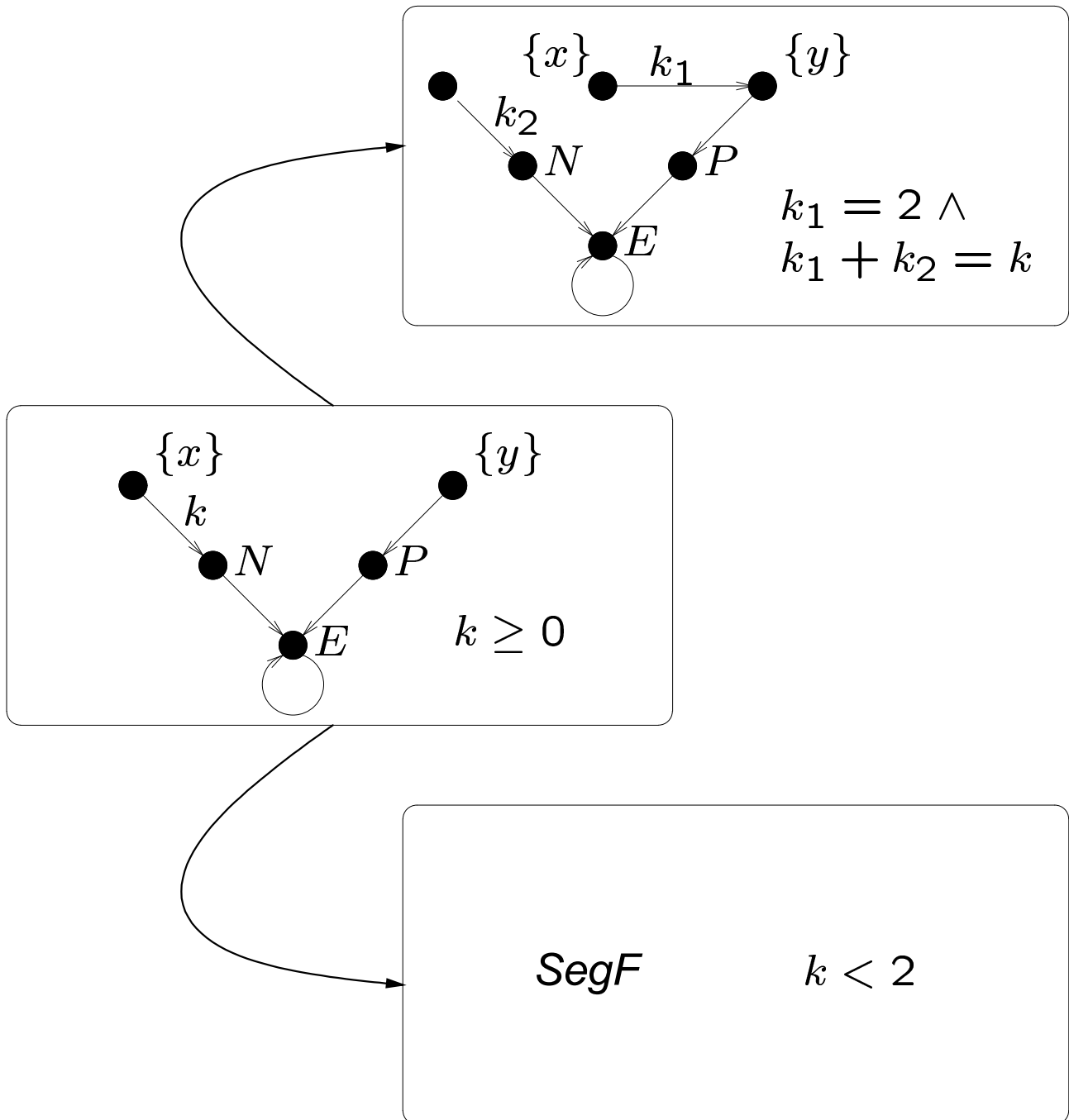
Union  $\sqcup$  of SMSs such that

$$\gamma(M_1 \sqcup M_2) = \gamma(M_1) \cup \gamma(M_2)$$

is defined the evident way.

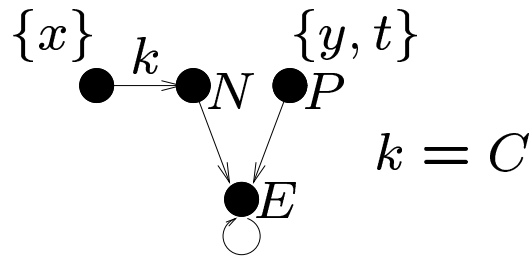
# Execution of pointer automata

Example: an execution of the instruction  $x.s.s:=y$

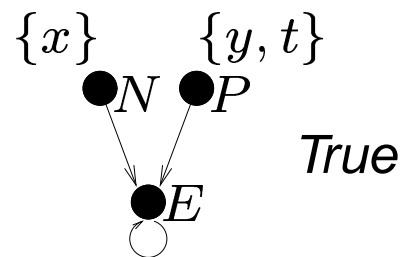
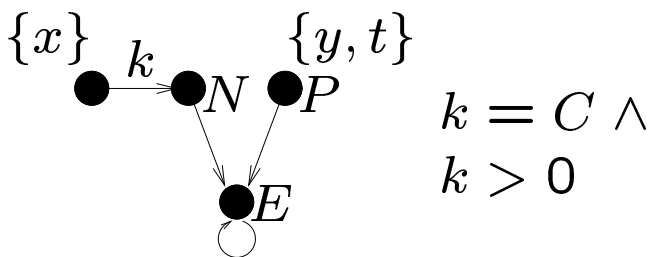


Each SMS  $M$  has a computable canonical form

An SMS



and its canonical form



An atomic SMS in canonical form is such that

- each counter is different from 0;
- only core nodes appear, i.e.
  - nodes  $N$ ,  $S$  and  $E$ ,
  - nodes labelled by a non empty set of variables,
  - nodes of input degree greater than or equal to 2.

An SMS in canonical form is a finite set of atomic SMSs in canonical form such that it does not contain isomorphic graphs.

## Inclusion

We define a decidable relation  $\sqsubseteq$  on SMSs such that

$$M_1 \sqsubseteq M_2 \Leftrightarrow \gamma(M_1) \subseteq \gamma(M_2)$$

It is defined on SMSs by:

- $(G, \phi) \sqsubseteq (G', \phi')$  iff  $G$  and  $G'$  are isomorphic and  $\phi \Rightarrow \phi'$  is valid.
- $(\text{Seg}F, \phi) \sqsubseteq (\text{Seg}F, \phi')$  iff  $\phi$  is not satisfiable or  $\phi'$  is satisfiable.
- $M_1 \sqcup M_2 \sqsubseteq M$  iff  $M_1 \sqsubseteq M$  and  $M_2 \sqsubseteq M$ .
- $M \sqsubseteq M_1 \sqcup M_2$  iff  $M \sqsubseteq M_1$  and  $M \sqsubseteq M_2$ .



## Undecidability results

**NoSegF** A state of the form  $(q, (\text{SegF}, \phi))$  where  $q$  is a control state and  $\phi$  is satisfiable is not reachable.

**NoMemLeak** A state  $(q, M)$  where  $q$  is a control state and  $M$  is a memory leak is not reachable.

*Theorem.* **NoSegF** and **NoMemLeak** are undecidable for pointer automata with at least 3 pointer variables.

## Future work

- We can check invariants (represented as SMSs) on pointer automata by computing one iteration. But it is difficult on realistic examples.
- We can try to isolate decidable subclasses. But we did not find realistic enough subclasses.
- We focus on acceleration techniques:
  - They can compute the set of reachable states.
  - They can compute invariants.
  - They have proved to be efficient on other models such as counter, clock or lossy channel systems.
- We will extend our symbolic representation to other structures than linked lists.

# Acceleration

