## Some Remarks on Logic and Topology Richard Moot Richard.Moot@labri.fr

## Why Topology?

- Topology seems to be at the right level of abstraction (eg. when compared to geometry).
- Basically, we have regions, their complements (intended to model "outside"), their interiors (intended to model "inside") and frontiers.
- Rich and well-developed field of mathematics

## Why Topology?

• It allows us to model statements like:

 "the frontier between France and Spain runs through the Pyrénées"

 "France is the union of Continental France and Corsica, yet Continental France and Corsica are disconnected"

### Some Potential Problems

- Topology, being very general and very abstract, makes more distinctions than are useful when reasoning about real regions in space.
- Reasoning about topological spaces can be very complex.



- Find some nice, well-behaved regions in topological space.
- Find a language which is expressive enough to make topologically interesting statements, yet has reasonable computational complexity.

- A topology is a set X (the <u>universe</u>) and a collection τ of subsets of X (the <u>open sets</u>) such that:
- $\tau$  contains X and  $\varnothing$
- The union of any collection elements of  $\tau$  is in  $\tau$
- The intersection of any fir of elements of  $\tau$  is in  $\tau$

Sometimes it is useful to permit infinite intersections as well: in this case we will talk about an Alexandrov space or Alexandrov topology. An Alexandrov topology is isomorphic to specialization preorder on a set X, that is x <= y if and only if all open sets which contain x contain y as well.

This make the link between preorders (reflexive and transitive relations) and S4 (with a reflexive and transitive accessibility relation R).

- The <u>complement</u> of a subset A of X, which we will note by A' is defined as X \ A.
- The complement of an open se <u>closed</u>.

Some people write A° for the complement of a set. In order to avoid confusion with the closure of a set, I will write A' for the complement and A<sup>-</sup> for the closure.

 A set can be both closed and open (specifically, both X and Ø are bo closed and open in any topology)

Some people like the word "clopen" for a set which is both closed and open. I don't. It is very widely used, though.

• a set can also be neither closed nor open.

•  $(A \cup B)' = A' \cap B'$ 

•  $X \setminus (A \cup B) = X \setminus A \cap X \setminus B$ 

•  $\forall x x \in X \land x \notin (A \cup B) \Leftrightarrow$  $x \in X \land x \notin A \land x \notin B$ 

de Morgan law for union and complement

•  $(A \cup B)' = A' \cap B'$ 

•  $X \setminus (A \cup B) = X \setminus A \cap X \setminus B$ 

•  $\forall x x \in X \land \neg(x \in (A \cup B)) \Leftrightarrow$  $x \in X \land x \notin A \land x \notin B$ 

- $(A \cup B)' = A' \cap B'$
- $X \setminus (A \cup B) = X \setminus A \cap X \setminus B$
- $\forall x x \in X \land \neg(x \in A \lor x \in B)) \Leftrightarrow$  $x \in X \land x \notin A \land x \notin B$

•  $(A \cup B)' = A' \cap B'$ 

•  $X \setminus (A \cup B) = X \setminus A \cap X \setminus B$ 

•  $\forall x x \in X \land \neg(x \in A) \land \neg(x \in B)) \Leftrightarrow$  $x \in X \land x \notin A \land x \notin B$ 

#### • $(A \cap B)' = A' \cup B'$

• A'' = A

All of this is basic set theory We have, in essence, a boolean algebra.

- Given a set A, the <u>interior</u>  $A^{\circ}$  of A is the union of all open sets O such that O  $\subseteq A$ .
- Given a set A, the <u>closure</u>  $A^-$  of A is the intersection of all closed sets C such that  $A \subseteq C$ .
- Evidently, we have  $A^{\circ} \subseteq A \subseteq A^{-}$

• Evidently, we have  $A^{\circ} \subseteq A \subseteq A^{-}$ 

- if A is open then  $A^{\circ} = A$
- if A is closed then  $A^- = A$
- The boundary of A, δA is defined as A<sup>-</sup> \ A<sup>o</sup>

## Open and Closed Sets

| General  | Ao | $\subseteq$ | A | $\subseteq$ | $A^{-}$        |
|----------|----|-------------|---|-------------|----------------|
| Open     | Ao | =           | A | $\subseteq$ | $A^{-}$        |
| Closed   | Ao | $\subseteq$ | A | =           | A <sup>-</sup> |
| "Clopen" | Ao | -           | A | =           | A <sup>-</sup> |

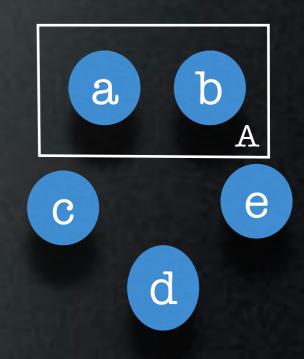
Classically, first examples in topology are about intervals on the real line...

 $A = [0,1> A^{\circ} = <0,1> A^{\circ} = <0,1]$  $A^{-} = [0,1] \delta A = \{0,1\}$  $A' = <-\infty,1> \cup [0,\infty>$ 

 $X = \{a, b, c, d, e\}$ 

 $\tau = \{ \emptyset, X, \{a\}, \{c,d\}, \{a,c,d\}, \{b,c,d,e\} \}$  Open sets  $\tau' = \{ \emptyset, X, \{b,c,d,e\}, \{a,b,e\}, \{b,e\}, \{a\} \}$  Closed sets

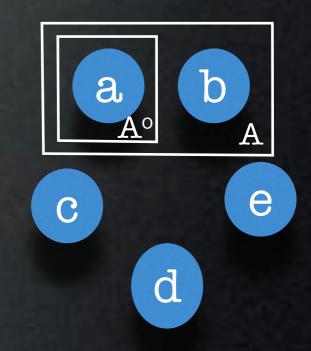
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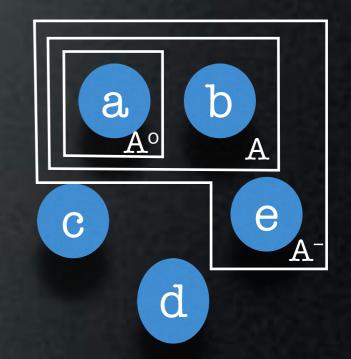
 $A = \{a,b\}$  $A^{o} = \{a\} \cup \emptyset = \{a\}$ 



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A = {a,b}  $A^{\circ} = \{a\} \cup \emptyset = \{a\}$  $A^{-} = X \cap \{a,b,e\} = \{a,b,e\}$ 

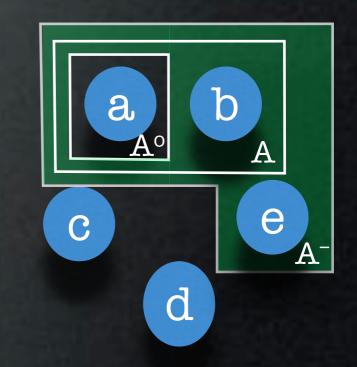


 $X = \{a,b,c,d,e\}$ 

 $\tau = \{ \emptyset, X, \{a\}, \{c,d\}, \{a,c,d\}, \{b,c,d,e\} \}$  Open sets  $\tau' = \{ \emptyset, X, \{b,c,d,e\}, \{a,b,e\}, \{b,e\}, \{a\} \}$  Closed sets

**Π**δΑ

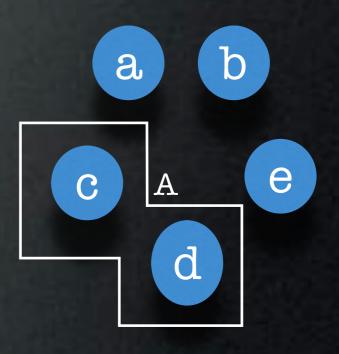
A = {a,b} A<sup>o</sup> = {a}  $\cup \emptyset$  = {a} A<sup>-</sup> = X  $\cap$  {a,b,e} = {a,b,e}  $\delta A$  = {a,b,e}  $\setminus$  {a} = {b,e}



 $X = \{a,b,c,d,e\}$ 

 $\tau = \{\emptyset, X, \{a\}, \{c,d\}, \{a,c,d\}, \{b,c,d,e\}\} \}$  $\tau' = \{\emptyset, X, \{b,c,d,e\}, \{a,b,e\}, \{b,e\}, \{a\}\} \}$ 

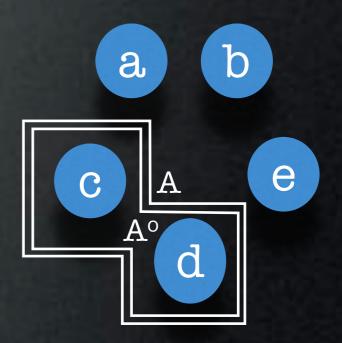
 $A = \{c,d\}$ 



 $X = \{a,b,c,d,e\}$ 

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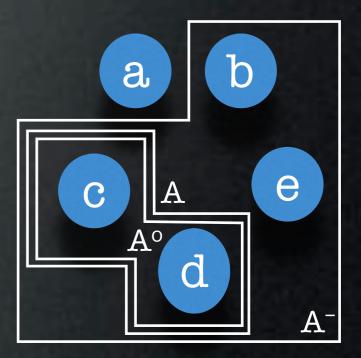
 $A = \{c,d\}$  $A^{o} = \{c,d\} \cup \emptyset = \{c,d\}$ 



 $X = \{a,b,c,d,e\}$ 

 $\tau = \{\emptyset, X, \{a\}, \{c,d\}, \{a,c,d\}, \{b,c,d,e\}\} \}$  $\tau' = \{\emptyset, X, \{b,c,d,e\}, \{a,b,e\}, \{b,e\}, \{a\}\} \}$ 

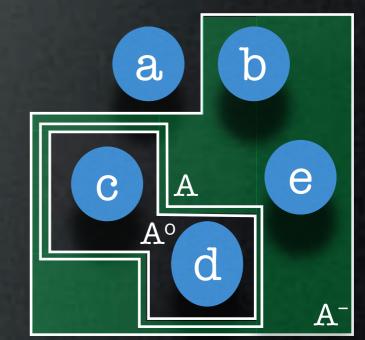
A = {c,d} A<sup>o</sup> = {c,d}  $\cup \emptyset = {c,d}$ A<sup>-</sup> = X  $\cap {b,c,d,e} = {b,c,d,e}$ 



 $X = \{a,b,c,d,e\}$ 

 $\tau = \{\emptyset, X, \{a\}, \{c,d\}, \{a,c,d\}, \{b,c,d,e\}\} \}$  $\tau' = \{\emptyset, X, \{b,c,d,e\}, \{a,b,e\}, \{b,e\}, \{a\}\} \}$ 

 $A = \{c,d\}$   $A^{\circ} = \{c,d\} \cup \emptyset = \{c,d\}$   $A^{-} = X \cap \{b,c,d,e\} = \{b,c,d,e\}$   $\delta A = \{b,c,d,e\} \setminus \{c,d\} = \{b,e\}$ 



 $\mathbf{X} = \mathbb{R}^{2}$ 

 $\tau = \{ \emptyset, \mathbb{R}^2, <0, 0 > -<1, 2 > , <0, 2 > -<3 - 3 > , <1, 1 > -<2, 2 > , ... \}$ 

Х

• Open rectangles

on  $\mathbb{R}^2$ 

generate one of the

standard topologies

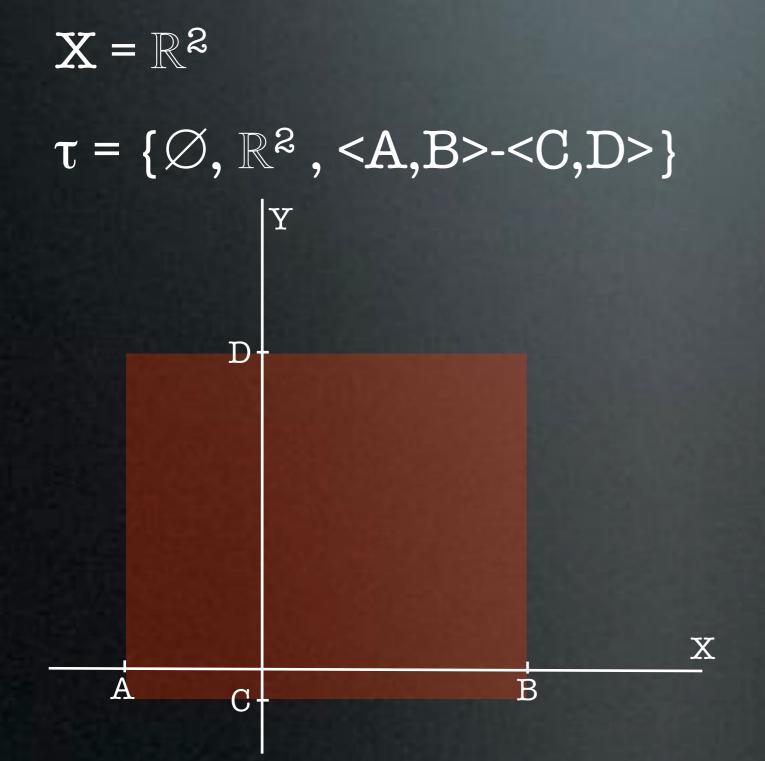
• As an example, the

rectangles are part

following open

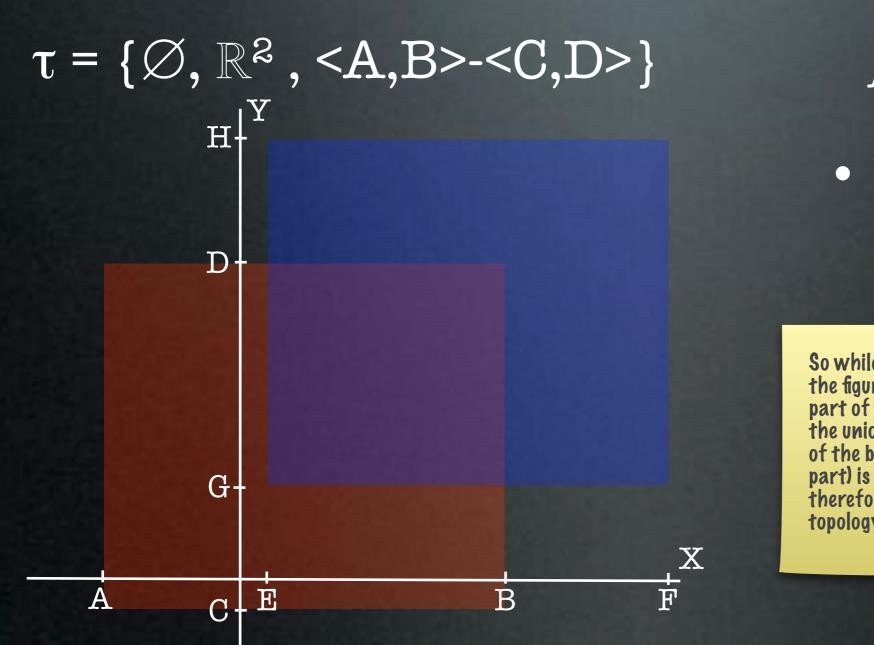
of this standard

topology.



#### A < C, B < D

- Open rectangles generate one of the standard topologies on  $\mathbb{R}^2$
- However, even the general definition of open sets listed above does not form a topology (why?)



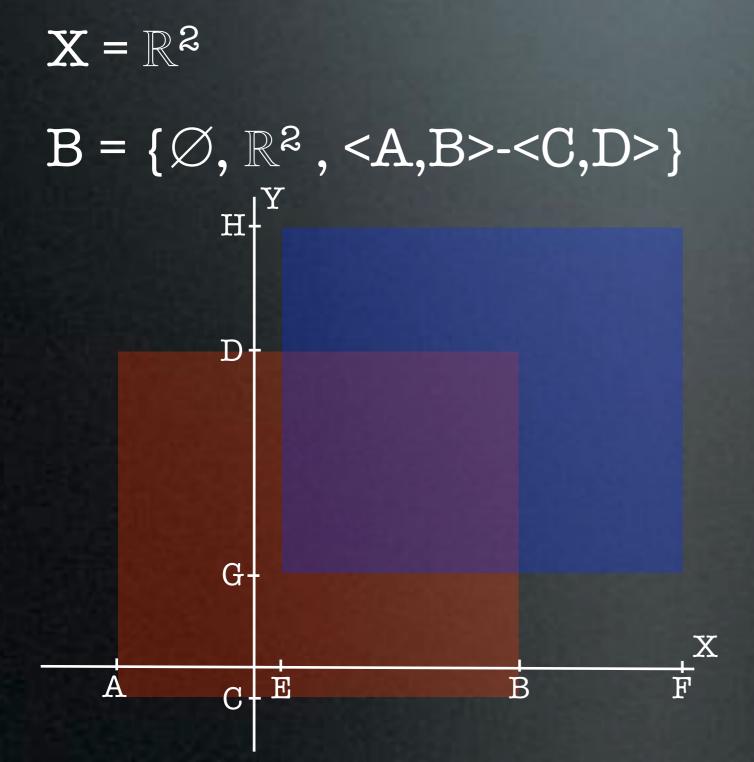
 $\mathbf{X} = \mathbb{R}^{\mathcal{Z}}$ 

#### A < B, C < D

• When we have two open rectangles, their intersection is either an open

So while the purple part of the figure to the right is a part of the defined topology, the union (that is, the union of the blue, purple and red part) is not a rectangle and therefore not a part of the topology as defined above. or empty.

their ot an open



A < B, C < D

 We say a collection of open sets B is a base (basis) for a topology if any element of τ is the union of elements of B

## Reminder Bases

- Bases allow us to give a compact way to describe topologies.
- Some topological properties can also be verified directly on the base elements.

## Regular Closed Sets

# Regular closed

B

Not reg. closed

• A is <u>regular closed</u> iff A = A<sup>o–</sup>

 roughly speaking, this means no "loose points" and no "hanging lines"

A

## Regular Closed Sets

#### Regular closed

#### Not reg. closed



- A is regular closed
   iff A = A<sup>o-</sup>
- roughly speaking, this means no "loose points" and no "hanging lines"

Ao

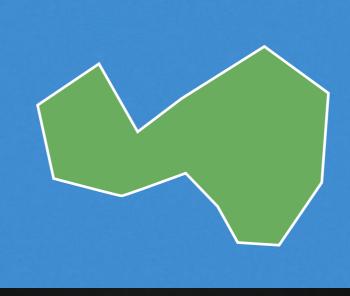
## Regular Closed Sets

# <section-header><section-header>

A 0-

=A

#### Not reg. closed



 $\mathrm{B}^{\mathrm{o}}$ 

≠B

A is <u>regular closed</u>
 iff A = A<sup>o-</sup>

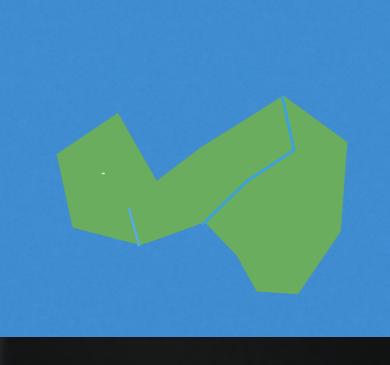
 roughly speaking, this means no "loose points" and no "hanging lines"

Note, this does not show that Aois necessarily regular closed, I will come to that in a few slides.

## Regular Open Sets

#### Regular open

#### Not reg. open



B

• A is regular open iff  $A = A^{-0}$ 

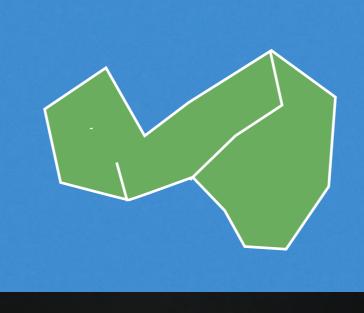
 roughly speaking, this means no "holes" and no "cracks"

A

## Regular Open Sets



#### Not reg. open



 $B^-$ 

A is regular open ightarrow $iff A = A^{-O}$ 

 roughly speaking, this means no "holes" and no "cracks"

 $A^{-}$ 

## Regular Open Sets

#### Regular open

#### Not reg. open



- A is regular open iff  $A = A^{-0}$
- roughly speaking, this means no "holes" and no "cracks"

A<sup>-0</sup> <u>=A</u>

B-₀ ≠B

Again, this does not suffice to show that A-o is regular open.

### Regular Sets

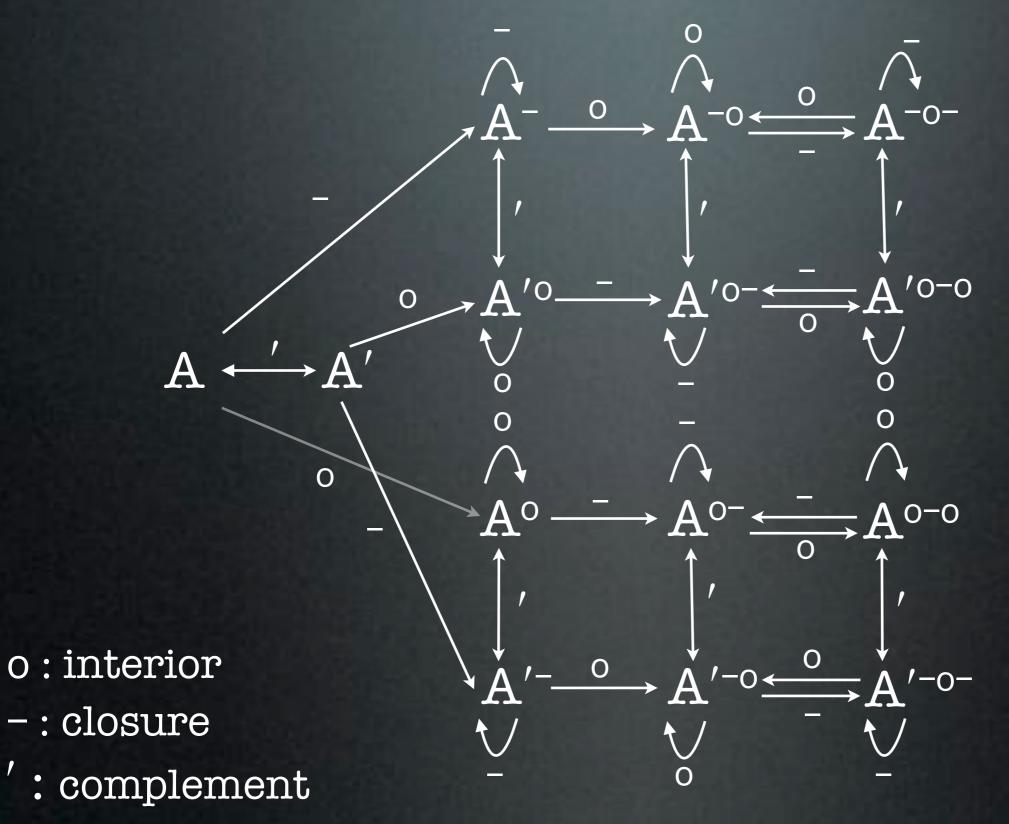
- Suppose A is a regular open set, that is  $A = A^{-0}$ .
- Thus we have, for its complement A' that A' = A<sup>-o'</sup> = A<sup>-'-</sup> = A'<sup>o-</sup>
- In addition, we have  $A^- = A^{-o-}$
- In other words, both A' and A<sup>-</sup> regular closed.

Similar remarks hold for regular closed sets. Given a regular closed set A, both its complement and its interior are regular open.

- Given a region variable A, how many (potentially) different regions can we construct using the closure, interior and complement relations?
- Our possibilities are limited by the fact that a double complement is the identity function and that the closure and interior operations are idempotent.

- Equivalences
  - $\mathbf{A}^{\prime\prime} = \mathbf{A}$
  - $A^{\circ\circ} = A^{\circ}$
  - $A^{--} = A^{-}$
  - $A^{o-o-} = A^{o-}$
  - $A^{-0-0} = A^{-0}$

- Non-equivalent
  - A
  - A<sup>-</sup>, A<sup>o</sup>
  - A<sup>-0</sup>, A<sup>0-</sup>
  - A<sup>-o-</sup>, A<sup>o-o</sup>
- and their negations



Note: there are examples where all these 14 regions are different.

A

 $-0 \leftarrow 0 \qquad A^{-0-}$ 

Ο

'-0-

- o:interior
- -: closure
  - : complement

#### Regular Closed

- o:interior
- -: closure
  - : complement

Regular Closed

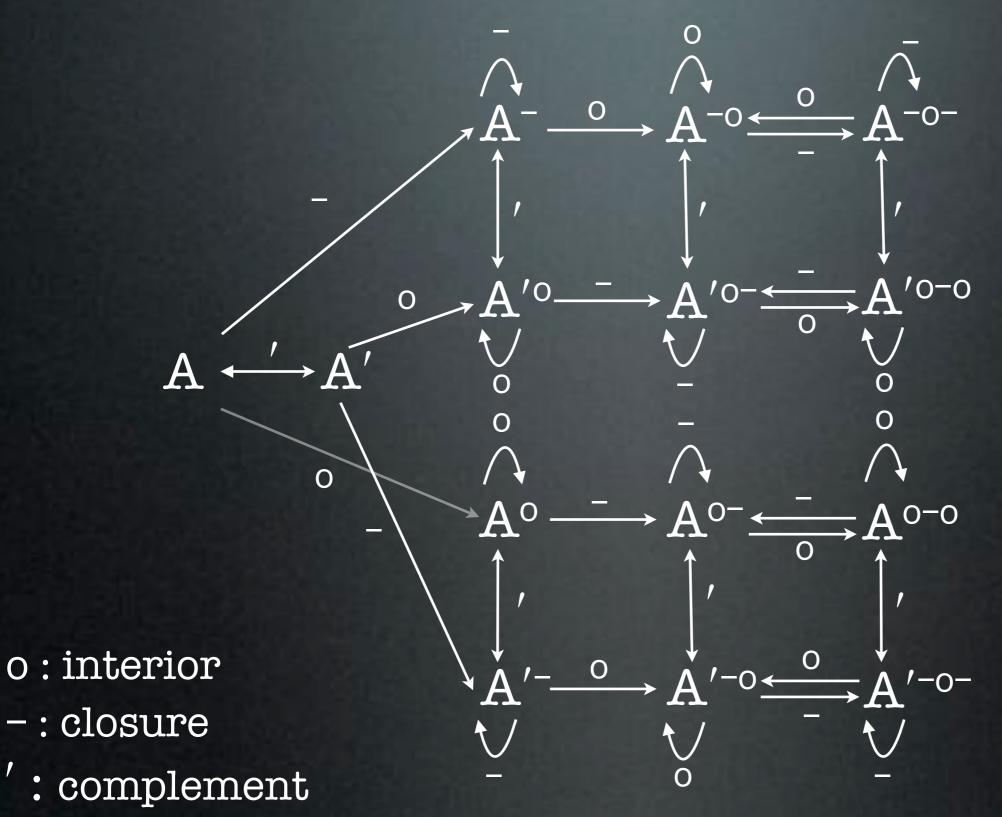
0-0

′-0-

 $\cap$ 

-0

 $\bigcap$ 



 $\rightarrow A^{-0} \xrightarrow{0}$ 

0

′−0

A

Regular open

.′0-0

0-0

- o:interior
- -: closure
  - : complement

 $A^{-0} \xrightarrow{0} A^{-0^{-1}}$ 

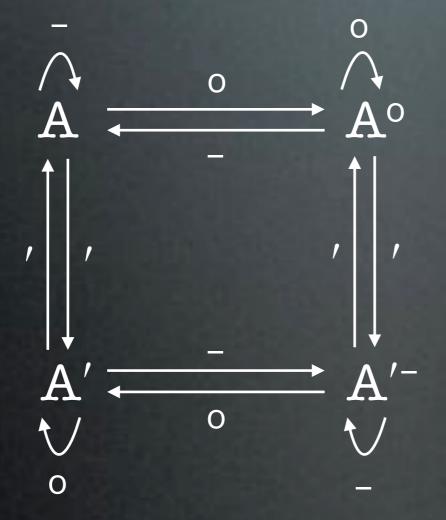
Ο

′0-0

Regular open

- o:interior
- -: closure
  - : complement

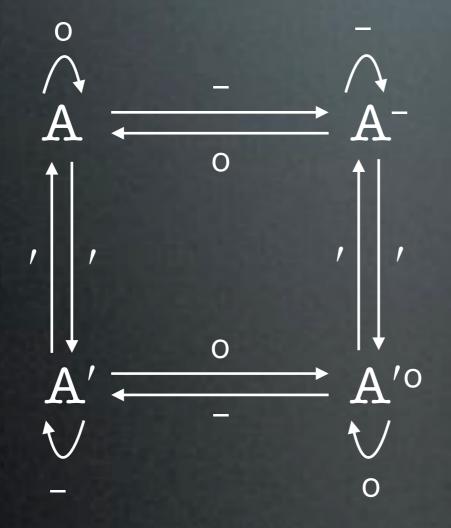
### Regular closed regions



A regular closed = $_{def}$ A = A<sup>o-</sup>

- -: closure
- o:interior
- ': complement

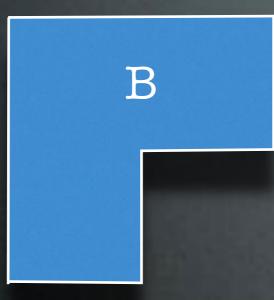
### Regular open regions

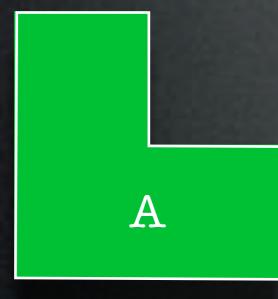


A regular open = $_{def}$ A = A<sup>-0</sup>

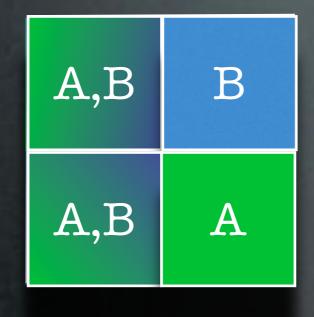
- -: closure
- o:interior
- ': complement

- We have seen that the regular closed and regular open sets reduce the combinatorics of the closure, interior and complement relations on a single region.
- What we have not looked at yet is how the regular closed and open sets combine with unions and intersections.





- A is the union of the closed rectangles
   [0,0]-[1-2] and
   [0-1][1-2]
- B is the union of the closed rectangles
   [0-0]-[1-1] and
   [0-1]-[2-2]



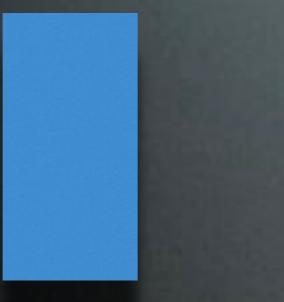
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#### $A \cap B$



- The intersection of two regular closed sets (though closed) is not necessarily <u>regular</u> closed.
- Therefore we define the intersection of two regular closed sets as (A∩B)<sup>0-</sup>

#### A∩B<sup>o</sup>



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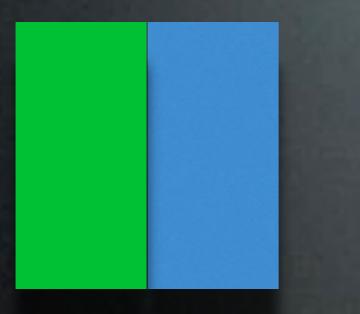
#### A∩B<sup>o−</sup>



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#### Union

#### $A \cup B$



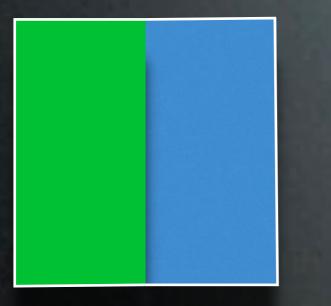
#### A∪B = <0,0>-<1,2> ∪ <1,0>-<2,2>

 Likewise, the union of two regular open sets (though open) is not necessarily regular open.

 Therefore we define the union of two regular open sets as (A∪B)<sup>-0</sup>

#### Union





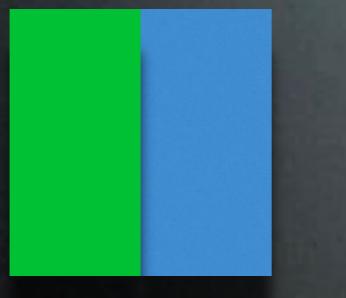
#### $(A \cup B)^{-} = [0,0] - [2,2]$

 Likewise, the union of two regular open sets (though open) is not necessarily regular open.

 Therefore we define the union of two regular open sets as (A∪B)<sup>-0</sup>

#### Union

#### $(A \cup B)^{-0}$



#### $(A \cup B)^{-0} = <0,0>-<2,2>$

 Likewise, the union of two regular open sets (though open) is not necessarily regular open.

 Therefore we define the union of two regular open sets as (A∪B)<sup>-0</sup>

#### Boolean operations

Regular Open Regions Regular Closed Regions

- $RO(p) = p^{-0}$
- $RO(\neg A) = X \setminus RO(A)^{-1}$
- $RO(A \land B) =$  $RO(A) \cap RO(B)$
- RO(AvB) = $(RO(A) \cup RO(B))^{-0}$

- $\operatorname{RC}(p) = p^{o^-}$
- $RC(\neg A) = X \setminus RC(A)^{O}$
- $RC(A \land B) =$  $(RC(A) \cap RC(B))^{o^{-}}$

• RC(AvB) = $RC(A) \cup RC(B)$ 

The combinations listed here give us a way to produce boolean combination of regular closed regions. They are in fact a sublanguage of S4u describing regions terms. This will be useful later, when we will use it to move from RCC8 to BRCC8 by changing from regular close atoms to formulas of RC.

#### Interior

These rules should remind us of something...

- $A^{O} \leq A$
- $A^{O} = A^{OO}$
- $\top = \top^{O}$
- $A^0 \cap B^0 = (A \cap B)^0$

Closure

- $A \leq A^{-}$
- $A^{--} = A^{-}$
- ⊥ = ⊥
- $(A \cup B)^- = A^- \cup B^-$

#### Interior

- $A^{O} \leq A$
- $A^{O} = A^{OO}$
- $\top = \top^{O}$
- $A^0 \cap B^0 = (A \cap B)^0$

#### S4

- $\Box A \vdash A$
- $\square A \vdash \square \square A$
- T H T
- $\Box A \land \Box B \vdash \Box (A \land B)$
- $\Box(A \land B) \vdash \Box A \land \Box B$

You will note in the following that I sometimes switch rather freely from the "modal logic" notation with diamonds and boxes to the "topology notation" with interiors and closures. I trust this will not lead to confusion.

#### Closure

S4

- $A \leq A^{-}$
- $A^{--} = A^{-}$
- ⊥<sup>−</sup> = ⊥
- $(A \cup B)^{-} = A^{-} \cup B^{-}$

•  $A \vdash \Diamond A$ •  $\Diamond \Diamond A \vdash \Diamond A$ •  $\Diamond \bot \vdash \bot$ •  $\Diamond (A \lor B) \vdash \Diamond A \lor \Diamond B$ •  $\Diamond A \lor \Diamond B \vdash \Diamond (A \lor B)$ 

#### Interior

S4

- $A^{O} \leq A$
- $A^0 = A^{00}$
- $\top = \top^{O}$
- $A^{0} \cap B^{0} = (A \cap B)^{0}$

Of course, the logical rules for the exponentials of linear logic are just the rules for **S4** as well!

- !A ⊢A
- $|A \vdash ||A$
- T H ! T
- $!A \land !B \vdash !(A \land B)$
- $!(A \land B) \vdash !A \land !B$

### Logic and Topology

- The relation between S4 and topology was first noted by Tarski (1938) McKinsey & Tarski (1944)
- However, its application to spatial reasoning is fairly new (see references: the earliest I found are from the mid 90s)

### Modeling

- Let's turn to some possible applications.
- How would we model a statement like "the interior of region A and the interior of region B have a non-empty intersection"?
- First try:  $\neg(\Box A \land \Box B \leftrightarrow \bot)$

### Modeling

- First try:  $\neg(\Box A \land \Box B \leftrightarrow \bot)$
- This formula is equivalent to  $\Box A \land \Box B$
- Let's construct a model of this formula.

Of course this will fail, but it will be instructive to see why land to see what form the models of these kinds of formulas take)

Of course, this is just one of many possible models! In particular, this is a model where A union B is

Remark: none of Answer: No! If we add an arrow from 1 to 2, transitivity would s are di force us to add an arrow from 1 to 7 The model seems very as well and then A would no longer not equal to the universe simple. This is no hold at all states accessible from 1. accident. we can always  $\{A', B\}$ construct a model with depth 1 and at most two arrows leaving any point. 4 2 4 6 B ∎ 3  $\{A^{-}, A, A^{\prime -}\}$  $\{B^{-},B,B^{\prime -}\}$  $\{A^{-},A,A^{\prime-},$  $B^{-}, B, B^{\prime -}\}$ 3 1 5  $\{A^{\circ},A\}$  $\{A^{\circ},A,B^{\circ},B\}$  $\{B^{\circ},B\}$ 

Question: can we add arrow from 1

to 2?

Reminder: A- means there is an arrow to a state where A holds. A<sup>o</sup> means all arrows lead to a state where A holds.

7

6

5

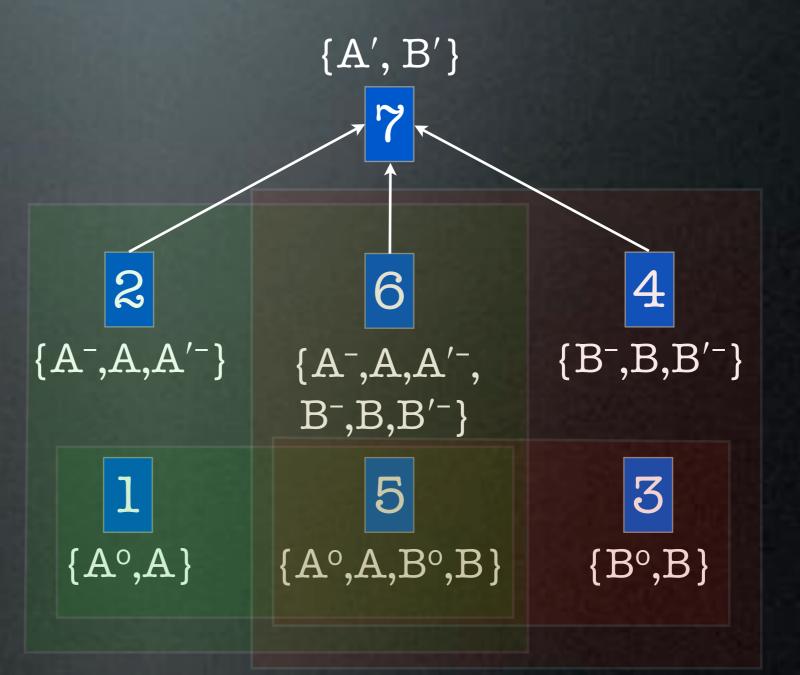
2

A

Now, in order for the formula  $A^{\circ} \wedge B^{\circ}$  to hold, it has to be true at every point.

This means that for every point and every point we can reach from this point by following an arrow both A and B must hold.

Let's look at point 7.

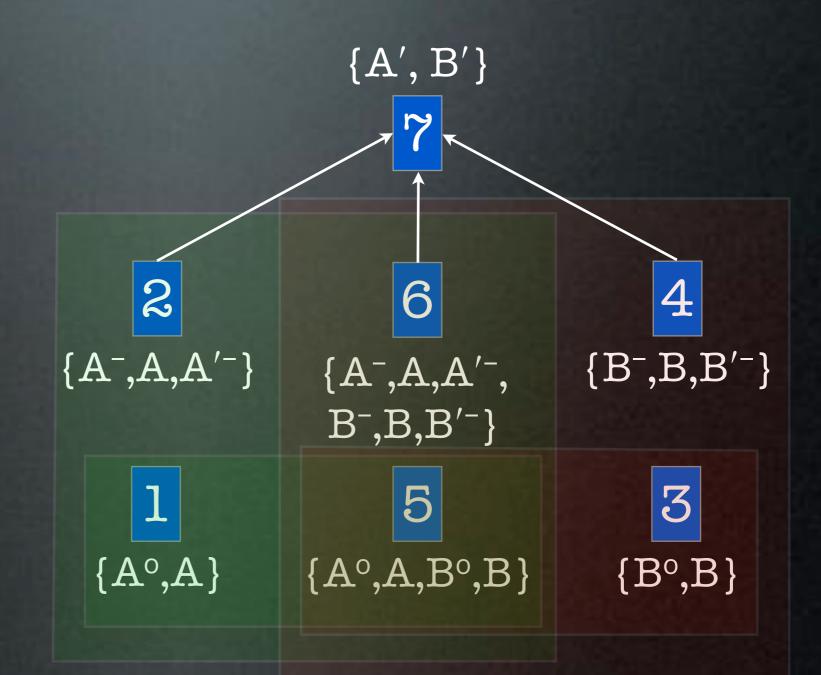


The only point we can reach from point 7 is point 7 itself.

Neither A nor B holds at point 7.

Therefore, this model is a countermodel to  $A^{\circ} \wedge B^{\circ}$ 

What went wrong?



We want to state that  $A^{\circ} \wedge B^{\circ}$  is true at at least one point in the model.

This would correctly model the fact that this intersection is not empty

 ${A', B'}$ 2 6 4  $\{A^{-}, A, A^{\prime -}\}$  $\{B^{-},B,B^{\prime -}\}$  $\{A^{-},A,A^{\prime-},$  $B^{-}, B, B^{\prime -}\}$ ] 3 5  $\{A^{\circ},A\}$  $\{A^{\circ},A,B^{\circ},B\}$  $\{B^{\circ},B\}$ 

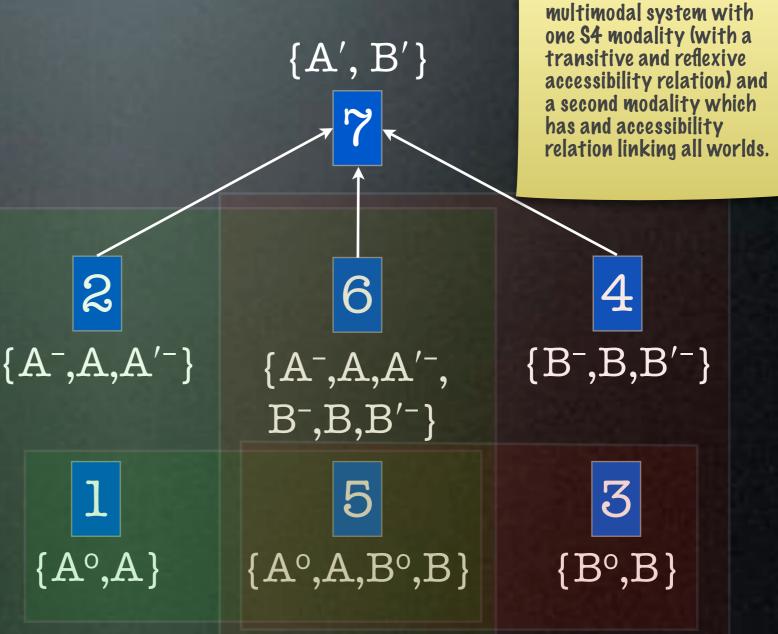
However standard cannot e this.

At least not if we want to keep the current interpretation of the connectives, with its advantage of being very close to the topological operators. We want to preserve this and add as little as possible.

A solution is to add a universal modality to S4, giving the system S4<sub>u</sub>

A formula ∀F is true if for all points in the model the formula F is true.

A formula  $\exists F$  is true is F holds at at least one point.



 $S4_{11}$ 

So we have "true everywhere" for the universal quantifier and "true somewhere" for the existential quantifier. Their negations are "false somewhere" (not forall) and "false everywhere" (not exists)

- In other words, ∀F will mean |F| = X and ∃F will mean |F| ≠ Ø
- The negated forms are interpreted as expected: ¬∀F will mean |F| ≠ X and ¬∃F will mean |F|=∅
- In the following, I will often use formulas containing "F ≠ Ø", "F ≠ "F = Ø", "F = X".

This is a slight abuse of notation, but, in my opinion, it makes the formulas a lot easier to read!

# S4u - Language

- We can restrict ourselves without loss of generality to formulas without nested occurrences of the universal/existential modality (see eg. Aiello & van Benthem).
- This is because a formula ∃F or ∀F is true globally.
- That is to say, we can replace a formula  $F[\exists G]$  by the equivalent formula  $(\exists G \land F[\top]) \lor \neg(\exists G \land F[\bot])$

### S4u - Language

 In other words, we can say that the formulas of S4<sub>u</sub> are of the following form:

 $F = F \land F$   $| F \lor F$   $| \neg F$   $| \forall S$   $| \exists S$  | S

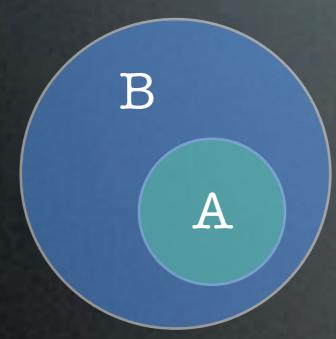
• Where S is a "normal" S4 formula.

## $S4_u$ - Examples

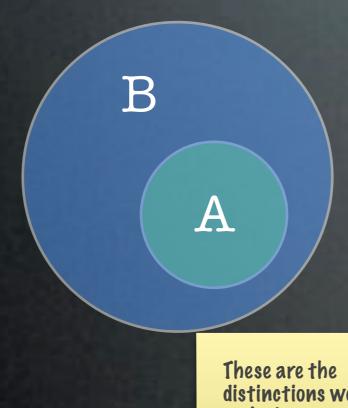
• Ja

∃□a
∃(-□a ∧ ◇a)
-∀a

- a is not empty
- a has a non-empty interior
  the frontier of a is not
- the trontier of a is not empty
- a is not the universe (there is a point ouside of a)



- Define  $A \subseteq B$  as  $\forall (\neg A \lor B)$  or  $\neg A \lor B = X$  or  $A \rightarrow B = X$
- Define A ⊈ B as
  ¬∀(¬A∨B) or
  ¬A∨B ≠ X or
  A→B ≠ X
- Define  $A \subset B$  as  $A \subseteq B \land B \not\subseteq A$

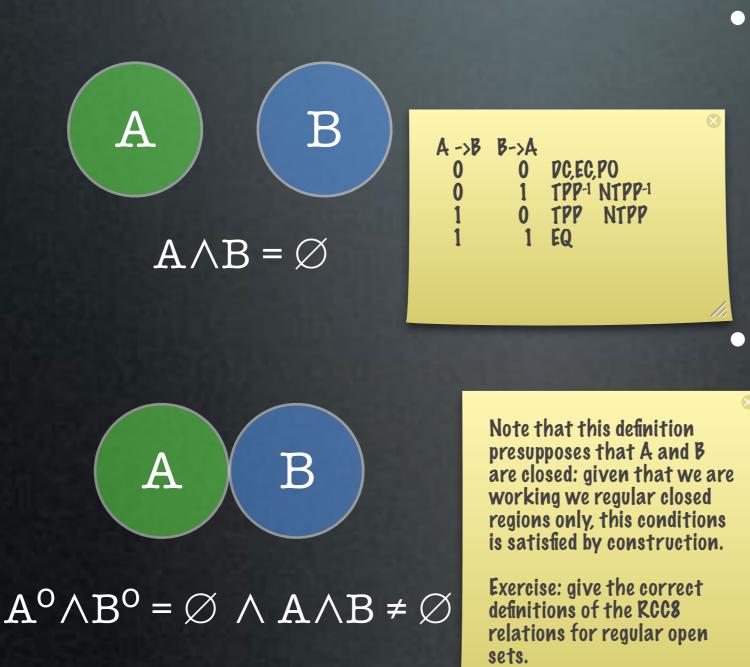


 The subset relation gives us a fairly crude way of partitioning the different possible relations
 between a region A and a region B

1.  $A \subseteq B \land B \subseteq A$ 2.  $A \subseteq B \land B \not\subseteq A$ 3.  $A \not\subseteq B \land B \subseteq A$ 4.  $A \not\subseteq B \land B \not\subseteq A$ 

These are the distinctions we can make in mereology. By adding some topologically interesting information, we obtain a system of mereotopology.

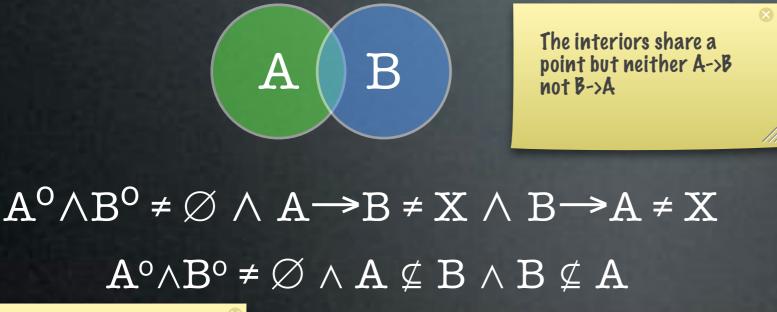
#### S4<sub>u</sub> expressivity $A = a^{\circ}$ and $B = b^{\circ}$



• Define DC(A,B) as  $\neg \exists (A \land B),$ which is equivalent to  $A \land B = \emptyset$ 

• Define EC(A,B)as  $\neg \exists (A^{\circ} \land B^{\circ}) \land \exists (A \land B), \text{ or}$  $A^{\circ} \land B^{\circ} = \emptyset \land \land A \land B \neq \emptyset$ 

### S4<sub>u</sub> expressivity $A = a^{\circ}$ and $B = b^{\circ}$



Both A ->B and B->A. The remaining cases are therefore A->B and not B->A (-B/\A) and B->A and not A->B (-A/\B)



 $A \leftrightarrow B = X$  $A \subseteq B \land B \subseteq A$ 

• Define PO(A,B) as  $\exists (A^{\circ} \land B^{\circ}) \land$  $\neg (A \subseteq B) \land \neg (B$  $\subseteq A)$  or  $A^{\circ} \land B^{\circ} \neq$  $\varnothing \land \neg (A \subseteq B) \land$  $\neg (B \subseteq A)$ 

• Define EQ(A,B)as  $A \subseteq B \land B \subseteq$ A.

#### S4<sub>u</sub> expressivity $A = a^{0^{-}}$ and $B = b^{0^{-}}$

 $\neg A \lor B^{o} = X \land \neg A \land B \neq \emptyset$  $A \subseteq B^{o} \land B \not\subseteq A$ 

B

A

B

 $\neg A \lor B = X \land \neg A \land B \neq \emptyset \land A \land \neg (B^{\circ}) \neq \emptyset$  $A \subseteq B \land A \nsubseteq B^{\circ} \land B \nsubseteq A$ 

A

- Define
   NTPP(A,B) as
   ¬A∨B<sup>0</sup> = X ∧
   ¬A∧B ≠ ∅
- Define TPP(A,B)

   as ¬A∨B = X ∧
   A∧¬(B<sup>0</sup>) ≠ ∅ ∧
   ¬A∧B ≠ ∅

A ->B and -(B->A) and -(A->B°)

#### S4<sub>u</sub> expressivity $A = a^{\circ}$ and $B = b^{\circ}$

 $\neg B \lor A^{o} = X \land \neg B \land A \neq \emptyset$  $B \subseteq A^{o} \land A \not\subseteq B$ 

A

B

B

A

Define
 NTPP<sup>-1</sup>(A,B) as
 NTPP(B,A)

 Define TPP<sup>-1</sup>(A,B) as TPP(B,A)

 $\neg B \lor A = X \land \neg B \land A \neq \emptyset \land B \land \neg (A^{\circ}) \neq \emptyset$  $B \subset A \land B \nsubseteq A^{\circ}$ 

- We have shown that there are formulas defining the RCC8 relations in S4<sub>u</sub>
- A natural question is: are there any useful things we can express in S4<sub>u</sub> which are not expressible in RCC8?

# S4<sub>u</sub> expressivity

- In RCC8, we apply the 8 relations only to region variables, which we assume to be regular closed, ie. A = a<sup>o-</sup> and B = b<sup>o-</sup> for a and b atomic.
- If instead we allow regular closed <u>formulas</u>, which use <u>boolean</u> <u>combinations of regions</u>, then we can express more.
- The resulting calculus is sometimes called BRCC8 (B for Boolean)

• EQ(UnionEuropéene, PaysBaysvBelgiquevFrancev...) We can use equality statements to specify that a region is exactly the union of a number of other regions. In RCC8 we can only specify that each of the different regions is a part of (tangential or not) a superregion but not the inverse.

- EQ(Aquitaine, Dordogne v Gironde v Landes v LotEtGaronne v PyrénéesAtlantiques)
- TPP(Pyrénées, FrancevEspagnevA
- EC(France^Pyrénées,Espagne^Pyr

These two statements capture the fact that France and Spain are connected by means of the Pyrénées. This a stronger than the RCC8 statements PO(France, Pyrénées) PO(Espagne, Pyrénées) EC(France, Espagne)

- EC(Andorre,France^Pyrénées)
- EC(Andorre,Espagne^Pyrénées)
- NTPP(Andorre, Pyrénées)
- EQ(France, FranceContinentalvCorse)
- DC(FranceContinental,Corse)

We can state that a region denoted by a certain variable is discontinuous. This is impossible in RCC8

- Besides BRCC8, there is another way to model regions and their interactions in S4<sub>u</sub>.
- To see how, remember that the formula ¬□A ∧ ◇A denotes the frontier of A, □A denotes the interior of A and ¬◇A denotes the exterior of A (that is, the complement of the closure)

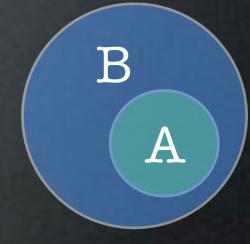
# S4<sub>u</sub> expressivity

- To see how, remember that the formula ¬□A ∧ ◇A denotes the frontier of A, □A denotes the interior of A and ¬◇A denotes the exterior of A (that is, the complement of the closure)
- In addition ¬∃A means region A is empty, whereas ∃A means it is not empty.

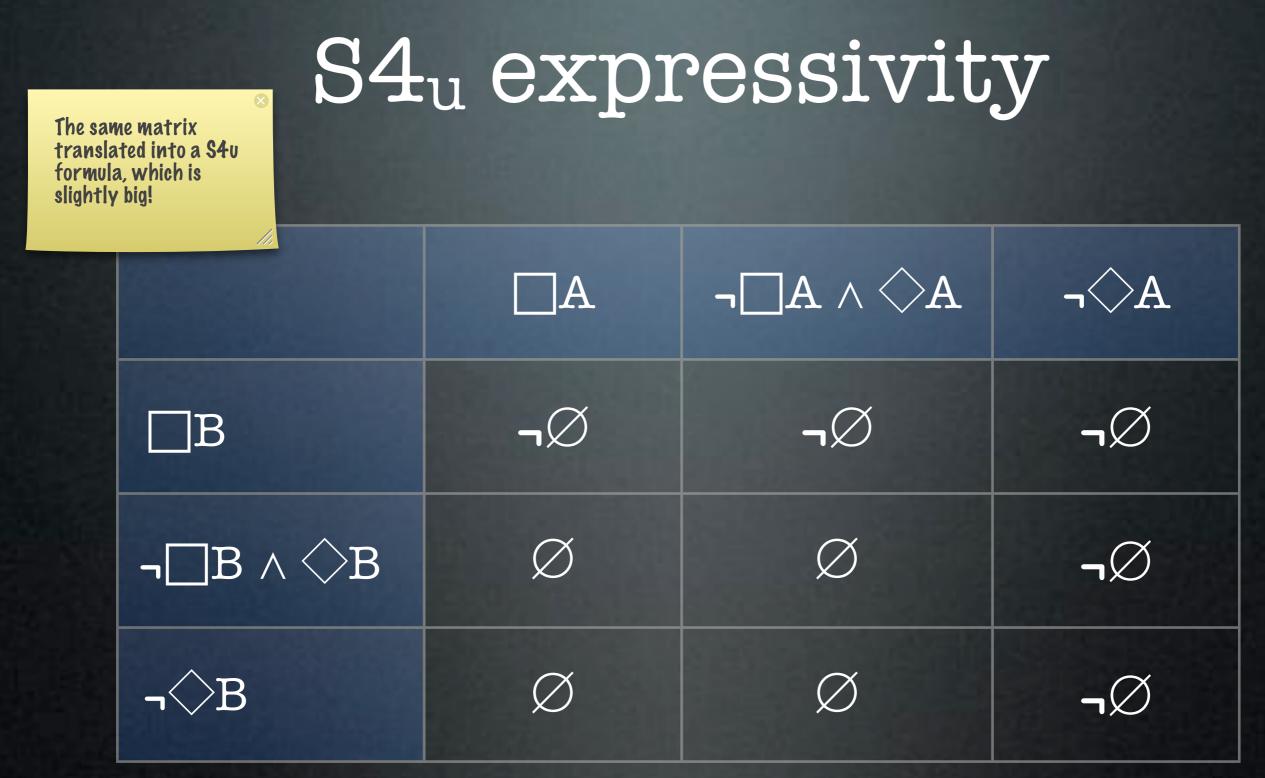
- Egenhofer and colleagues, have created a taxonomy of topological possibilities (under certain hypotheses about the regions under consideration) specifying whether each of the 3 divisions of the topological space (interior, frontier, exterior) introduced by two different regions is empty or not.
- In the case of regions "without holes" this gives the same 8 relations as RCC8; without this restriction, the 9-intersection model makes more distinctions.

# S4<sub>u</sub> expressivity

|    | Ao         | δΑ         | A′ |
|----|------------|------------|----|
| Bo | <b>-</b> Ø | <b>-</b> Ø | ٦Ø |
| δB | Ø          | Ø          | ٦Ø |
| B′ | Ø          | Ø          | ٦Ø |



The NTPP relation (nontangential proper part) of RCC8 shown as a 9-



 $\begin{array}{c} \exists (\Box A \land \Box B) \land \exists (\neg \Box A \land \diamondsuit A \land \Box B) \land \exists (\neg \diamondsuit A \land \Box B) \land \\ \neg \exists (\Box A \land \neg \Box B \land \diamondsuit B) \land \neg \exists (\neg \Box A \land \diamondsuit A \land \neg \Box B \land \diamondsuit B) \land \exists (\neg \diamondsuit A \land \neg \Box B \land \diamondsuit B) \land \\ \neg \exists (\Box A \land \neg \diamondsuit B) \land \neg \exists (\neg \Box A \land \diamondsuit A \land \neg \diamondsuit B) \land \exists (\neg \diamondsuit A \land \neg \bigtriangleup B) \land \\ \end{array}$ 

The partial overlap relation (PO) from RCC8

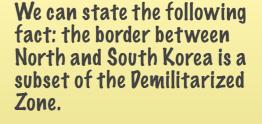
|                  | ΠA | $\neg \Box A \land \diamondsuit A$ | ¬◇A |
|------------------|----|------------------------------------|-----|
| B                | ٦Ø | ٦Ø                                 | ٦Ø  |
| <b>¬</b> □B ∧ ◇B | ٦Ø | ٦Ø                                 | ٦Ø  |
| <b>¬◇</b> B      | ٦Ø | ٦Ø                                 | ٦Ø  |

 $\begin{array}{c} \exists (\Box A \land \Box B) \land \exists (\neg \Box A \land \Diamond A \land \Box B) \land \exists (\neg \Diamond A \land \Box B) \land \\ \exists (\Box A \land \neg \Box B \land \Diamond B) \land \exists (\neg \Box A \land \Diamond A \land \neg \Box B \land \Diamond B) \land \exists (\neg \Diamond A \land \neg \Box B \land \Diamond B) \land \\ \exists (\Box A \land \neg \Diamond B) \land \exists (\neg \Box A \land \Diamond A \land \neg \Diamond B) \land \exists (\neg \Diamond A \land \neg \Diamond B) \\ \end{array}$ 

 ∀((NorthKorea ∧ SouthKorea) → DemilitarizedZone)

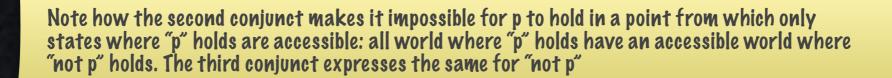
• 
$$\exists p \land \forall (p \rightarrow \bigcirc \neg p) \land \forall (\neg p \rightarrow \bigcirc p)$$

A tiny model for the above formula



The second is very strange: p is not empty and all points of p are boundary points.

Note however, that p is not regular closed (p's interior is the empty set)



¬p ← p

1

## $S4_u$ complexity

- The complexity of S4<sub>u</sub> is the same as the complexity of S4: it is PSPACE complete.
- Many interesting fragments (all have have seen: RCC8, BRCC8 and 9-I, at least for atomic formulas) have <u>simpler models</u> <u>than S4</u> and are NP complete (see eg. Gabelaia e.a.).

# Going Further

- It seems natural to interpret our regions in an Euclidian space: this would give us a natural distance metric.
- Convex hulls seem useful for many purposes.
- Integration with temporal logic has been investigated (but there is surely more to be done!)
- Is there a good way to strike a balance between expressivity and computational complexity?

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