Embodied Cognition

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INRIA (French National Institute for Research in Computer Science and Control) is a public research establishment entirely dedicated to information and communication sciences.

Organization

- 8 research centers
- 174 team-projects
- 3150 scientists



Research themes

- Life Sciences & Environment
- Algorithmic, Programing, Software & Architectures
- Applied Mathematics, Computation & Simulation
- Perception, Cognition & Interaction
- Computational Sciences for Biology, Medicine & the Environment



Cortex is a project whose goals are to design numerical and adaptive models in interaction with biology and medical science.

Current organization

- 10 permanent sciencists
- 3 post-docs
- 10 phD students
- 2 assistants
- 2 engineers

Research themes

- Microscopic level: spiking neurons and networks
- Mesoscopic level: dynamic neural fields
- Brain Signal Processing
- Connectionist parallelism
- The embodiment of cognition

Researches

http://www.loria.fr/~rougier/research/index.html

Computational Neuroscience

I'm trying to understand the emergence of global cognitive functions on the basis of numerical and distributed computations

- Dynamic Neural Fields
- Visual Attention
- Asynchronous computing
- Self-organization

How to reach me

I will be at NII until December 28th, come and visit me if you want to talk (office 1218 on 12th floor). Or send me an email at Nicolas.Rougier@loria.fr

Outlook

Lecture 1: Embodied cognition

This lecture proposes to look back at (almost) 60 years of Artificial Intelligence researches in order to address the question of what has been accomplished so far towards our understanding of intelligence and cognition

Lecture 2: Visual attention

This lecture proposes to review current psychological and physiological data related to visual attention as well as anatomical and physiological data related to the oculomotor control.

Lecture 3: Dynamic neural fields

This lecture introduces main concepts related to computational neuroscience and introduced dynamic neural field theory.

Lecture 4: Models of visual attention

This lecture will introduce models relying on dynamic neural fields and show how covert and overt attention can emerge from such a substratum.

Outlook

1 Introduction

2 A Short history of artificial intelligence

3 The action perception Loop

4 Embodied cognition

A short history of artificial intelligence

An old dream comes true ?



An old dream comes true ?



In 1997, Deep Blue super computer (IBM) beat world chess champion Gary Kasparov. Today (2010), Nao (Aldebaran) would not even be able to compete with a one-year old baby.

What is Artificial Intelligence ?

The science of making machines do things that would require intelligence if done by humans.

Marvin Minsky, Semantic Information Processing, 1968.

- What is machine ?
- What is intelligence ?
- What tasks require some form of intelligence ?
- What kind of humans do we consider ?

What is Artificial Intelligence ?

Weak A.I. hypothesis

According to weak AI, the principal value of the computer in the study of the mind is that it gives us a very powerful tool.

J. Searle, "Minds, Brains and Programs", 1980.

Strong A.I. hypothesis

According to strong AI, the computer is not merely a tool in the study of the mind; rather, the appropriately programmed computer really is a mind.

J. Searle, "Minds, Brains and Programs", 1980.

What is Artificial Intelligence ?

What were the main problems to be solved ?

- Deduction, reasoning, problem solving
- Knowledge representation
- Planning
- Learning
- Natural language processing
- Motion and manipulation
- Perception

A brief history of A.I.

Whitehead & Russe Principia Mathematica Cambridge University Press 4cCullochs & Pitt A Logical Calculus of Ideas Immanent in Nervous Activity g Bulletin of Mathematical Biophysics. The Organization of Behavior : A Neuropsychological Theory Computing Machinery and Intelligence. g ДC С Review of Psychology and Philosophy Wiley, New York 1956 port on a general problem-solving program. The Perceptron: A Probabilistic Model for Information Storage International Conference on Information Processing. g 5 and Organization in the Brain, Psychological Review, 65:6 Perceptrons First International Joint Conference on Artificial Intelligence Excitatory and inhibitory interactions in localized populations of model neurons. Biophysic Journal, 12 Adaptation in Natural and Artificial Systems University of Michigan Press. 6 ELIZA - A Computer Program For the Study of Natural Language Communication Between Man And Machine Dynamics of pattern formation in lateral inhibition type neural fields. Biological Cybernetics, 27. g Communications of the ACM 9:1. Self-organized formation of topologically correct feature maps 8 g Biological Cybernetics, 43. Learning representations by back-propagating errors Nature, 323 Rumelhart & McLelland Parallel Distributed Computing Cambridge. Laird Newell & Rosenbloom 9 8 SOAR : an architecture for general iintelligence ĸ Artificial Intelligence, 33:1.

Different philosophies



Symbolic

Sub-Symbolic

Statistical

Different approaches

The Physical Symbol System Hypothesis

A physical symbol system has the necessary and sufficient means for general intelligent action. By "necessary", we mean that any system that exhibits general intelligence will prove upon analysis to be a physical symbol system. By "sufficient" we mean that any physical system of sufficient size can be organized further to exhibit general intelligence.

Newell & Simon, 1976

The Connectionnist hypothesis

The implicit assumption [of the symbol manipulating research program] is that it is relatively easy to specify the behavior that we want the system to perform, and that the challenge is then to design a device or mechanism which will effectively carry out this behavior... [I]t is both easier and more profitable to axiomatize the *physical system* and then investigate this system analytically to determine its behavior, than to axiomatize the *behavior* and then design a physical system by techniques of logical synthesis.

Rosenblatt, 1962

Eliza, the computer therapist (Weizenbaum, 1966)

Eliza: How do you do. Please state your problem. I need a definition of A.I. Eliza: What would it mean to you if you got a definition of A.I. ? It would help me to finish my lecture. Eliza: Your lecture ? Yes, I'm a researcher. Eliza: Is it because you are a researcher that you came to me ? Yes, because I need this definition. Eliza: You seem to be quite positive. Not so much, because I still don't have the definition of A.I. Eliza: Is that the real reason ? Of course it is !

The symbol grounding problem



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"La Trahison des images", Magritte, 1929. "La Trahison des images", Magritte, 1929.

How can the semantic interpretation of a formal symbol system be made intrinsic to the system, rather than just parasitic on the meanings in our heads?

S.Harnad, The Symbol Grounding Problem, 1990.

The frame problem

Once upon a time there was a robot, named R1 by its creators. Its only task was to fend for itself. One day its designers arranged for it to learn that its spare battery, its precious energy supply, was locked in a room with a time bomb set to go off soon. R1 located the room, and the key to the door, and formulated a plan to rescue its battery. There was a wagon in the room, and the battery was on the wagon, and R1 hypothesized that a certain action which it called PULLOUT (Wagon, Room, t) would result in the battery being removed from the room. Straightaway it acted, and did succeed in getting the battery out of the room before the bomb went off. Unfortunately, however, the bomb was also on the wagon. R1 knew that the bomb was on the wagon in the room, but didn't realize that pulling the wagon would bring the bomb out along with the battery. Poor R1 had missed that obvious implication of its planned act.

Daniel C. Dennet, Cognitive Wheels: The Frame Problem of AI, 1987.

The action perception loop

Acting on the world



The agent perceives the external world through perceptions (camera, sensors, etc.) and may act onto it using a set of actions (actuators, motors, etc.).

The symbolic approach

Action/Perception loop

- World model
- Initial state
- Set of actions
- Goal state

Agent/Action

• Dynamic

- Uncertain
- Noisy

World/Perception

- Noisy
- Continuous
- Unknown



The subsumption architecture (Rodney Brooks, 1986)



Elephants Don't Play Chess

- The world is its own best representation
- A set of simple of independent behaviors
- Behaviors layered on top of each other

Braitenberg vehicles



Simple architecture

- Two sensors (light detectors)
- Two actuators (wheel motors)
- \rightarrow 4 different behaviors (aggression, love, foresight and optimism)

Embodied cognition

What is cognition ?

What are the questions ?

- What are the minimal mechanisms that lead to some form of cognition ?
- What is/are the right biological level(s) of description ?
 - Molecule ? (→ neurotransmitters)
 - Organelle ? (→ axons, dendrites, synapses)
 - Cell ? (→ neurons, glial cells)
 - Tissue ? (→ nervous tissue)
 - Organ ? (\rightarrow brain)
- How do we identify a satisfactory answer ?

What is cognition ?

To sit still and think or...



What is cognition ?

Learning Attention Feedpdate Regulation trateg formus Attack Afert Localization Learning Motivation Emotion Control Learning



Embodied cognition

Many fields

Neurology, psychology, philosophy, linguistics, computer science, etc.

Many forms

Abstraction, generalization, specialization, knowledge, decision, etc.

Many expressions

Perception, action, emotions, memory, language, etc.

Reclaiming the body



We ignored the fact that the biological mind is, first and foremost, an organ for controlling the biological body. Minds make motions, and they must make them fast — before the predator catches you, or before your prey gets away from you. Minds are *not* disembodied logical reasoning devices.

A.Clark, Being there: putting brain, body, and world together again, 1997.

Reclaiming the body



- Embodiment of an organism simultaneously limits and prescribes the types of cognitive processes that are available to it.
- Cognition is deeply rooted in the bodys interaction with the world
- Behavior is goal-directed or motivated

Affordance theory (Gibson, 1977)

Considering a lift

- For a human being, it is a way to go from one floor to the other
- For a wheeled robot, it is also a way to go from one floor to the other

Considering a stair

- For a human being, it is a way to go from one floor to the other
- For a wheeled robot, it is quick and certain death

Body helps cognition



The very nature of the body can simplify most control systems

Conclusion

Philosophy

What is cognition ?

Neuroscience

What are the mechanisms and cerebral structures that cause cognition ?

Computer science

How to build a computational cognitive model ?



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