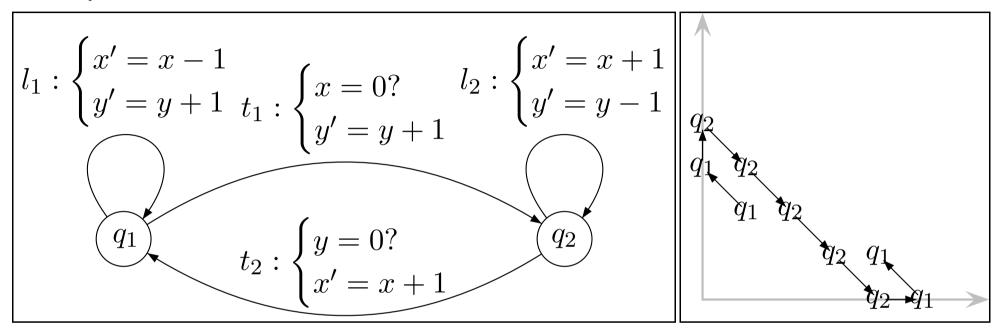
# Flat counter automata almost everywhere !

Jérôme Leroux and Grégoire Sutre

Vertecs Project, IRISA / INRIA, Rennes, FRANCE MVTsi Team, CNRS / LaBRI, Bordeaux, FRANCE

#### Counter-automata verification

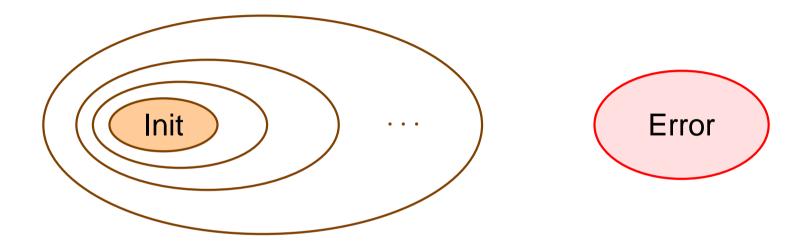
#### A simple counter-automata:



Counter-automata verification naturally appears in practice:  $\rightarrow$  Parametrized systems, system abstractions, communication protocols, and so on.

# Counter-automata reachability

Verification can often be reduced to the reachability problem.



An agorithm in general ?

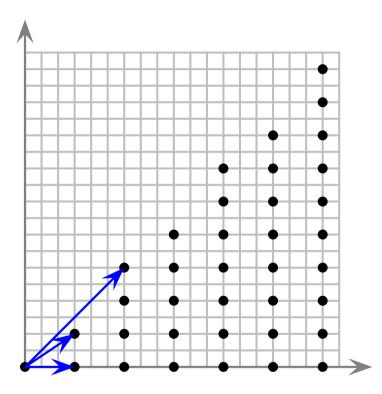
NO ! Because reachability is undecidable even for 2-counter automata.

However, there exist algorithms for subclasses of counter-automata.

Some of these algorithms use semilinear sets to symbolically represent and manipulate infinite subsets of  $\mathbb{Z}^n$ .

# Semilinear sets

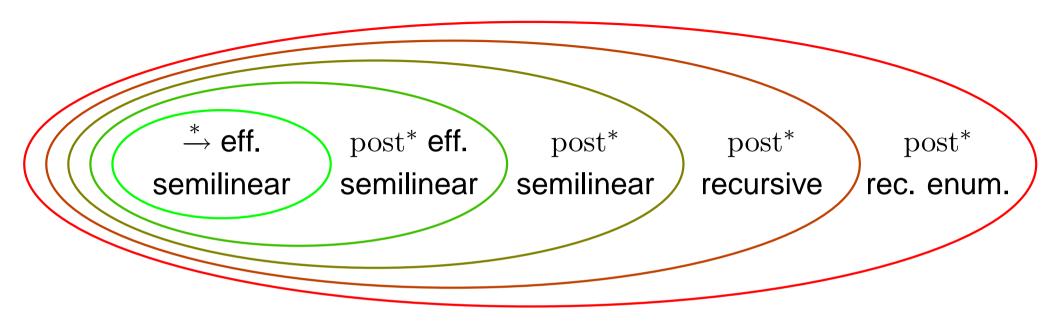
A semilinear set  $X \subseteq \mathbb{Z}^m$  is a finite union of linear sets  $b + \{p_1, \ldots, p_n\}^*$ .

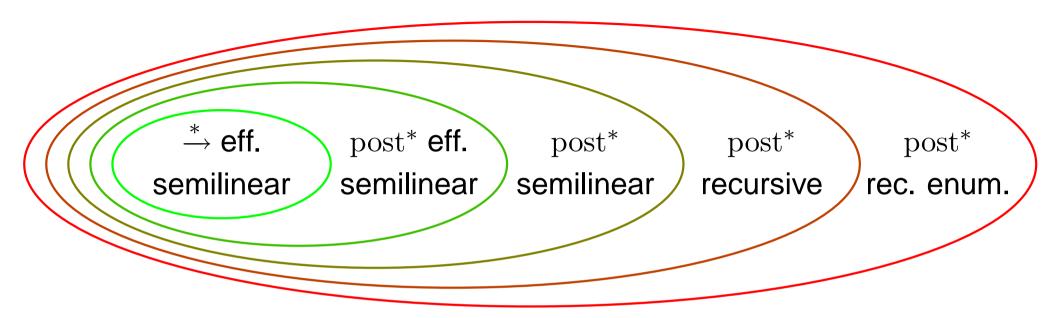


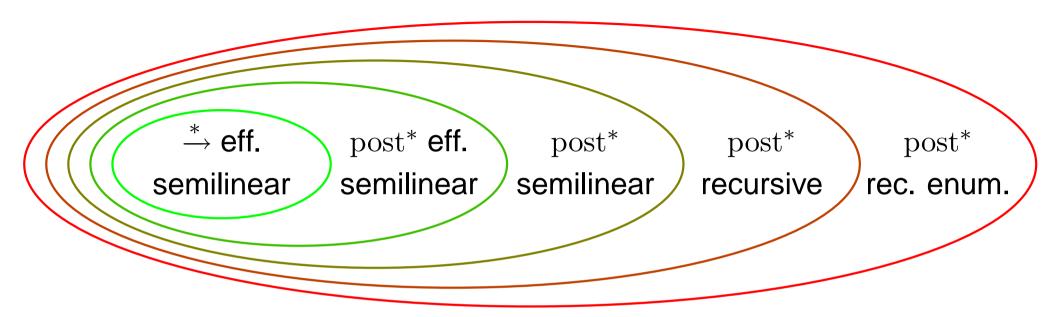
$$\{(0,0)\} + \{(3,0), (3,2), (6,6)\}^*$$

Recall that semilinear sets can be manipulated with:

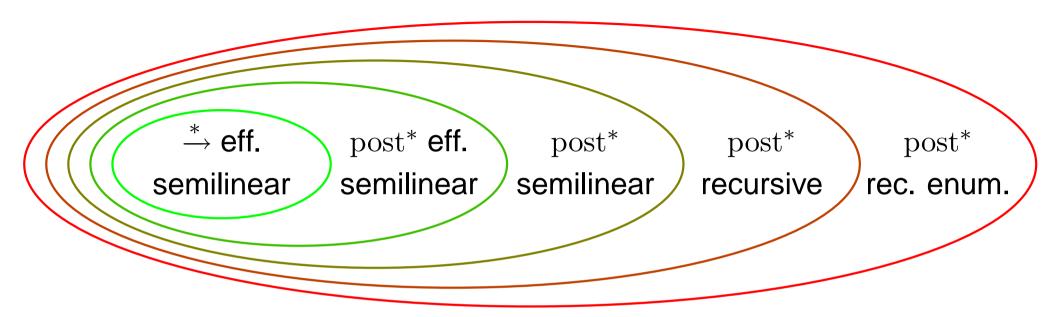
 $\longrightarrow$  Finite sets of basis and periods, Presburger formulas, digit vector automata.





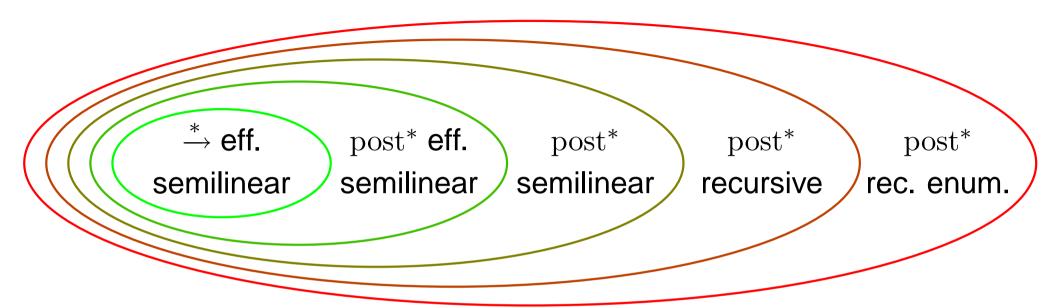






Lossy counter machines

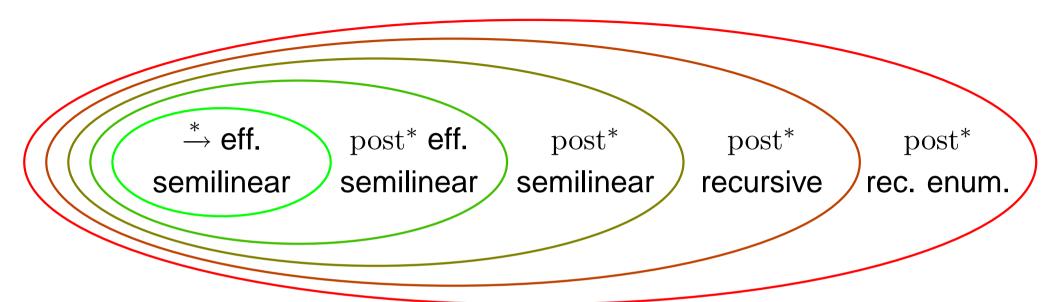




Lossy counter machines

Cyclic Petri nets Persistent/Conflict-free Petri nets Regular Petri nets Restricted 2-counter machines Lossy test-free counter machines

Petri nets

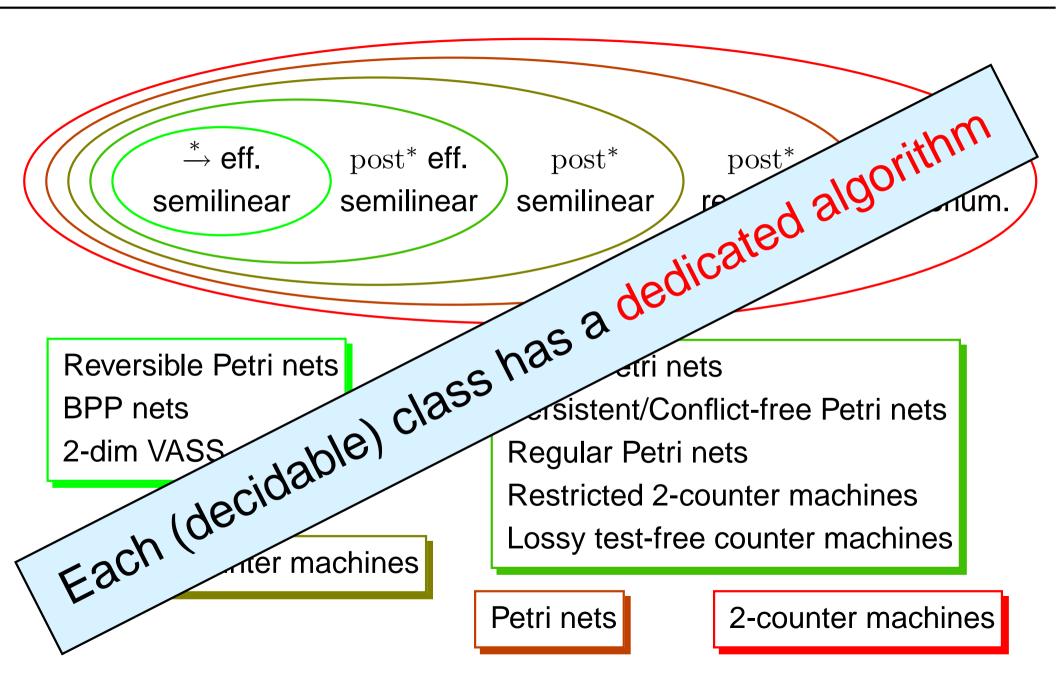


Reversible Petri nets BPP nets 2-dim VASS

Lossy counter machines

Cyclic Petri nets Persistent/Conflict-free Petri nets Regular Petri nets Restricted 2-counter machines Lossy test-free counter machines

Petri nets



# A generic accelerated algorithm

In practice counter automata are not exactly in a known subclass.  $\rightarrow$  we are interested in semi-algorithms for general classes.

**Input:** A counter automaton S.

**Output:** The global reachability relation  $\xrightarrow{*}$ .

let  $R \leftarrow Id$  and repeat forever

select one of the following tasks:

- if  $\xrightarrow{T} \cdot R \subseteq R$  return R
- select  $\pi \in T^*$  and  $R', R'' \subseteq R$ let  $R \leftarrow R \cup (R' \cdot \xrightarrow{\pi^*} \cdot R'')$
- select  $t \in T$  and  $R', R'' \subseteq R$ let  $R \leftarrow R \cup (R' \cdot \xrightarrow{t} \cdot R'')$

**Input:** An initialized counter automaton (S, I).

**Output:** The reachability set  $post^*(I)$ .

let  $X \leftarrow I$  and repeat forever select one of the following tasks:

- if  $post(T, X) \subseteq X$  return X
- select  $\pi \in T^*$  and  $X' \subseteq X$ let  $X \leftarrow X \cup \text{post}(\pi^*, X')$
- select  $t \in T$  and  $X' \subseteq X$

 $\texttt{let} \ X \leftarrow X \cup \texttt{post}(t, X')$ 

Implemented in tools: FAST, LASH, TReX.  $\longrightarrow$  Accelerated symbolic verification works well in practice.

# Completeness?

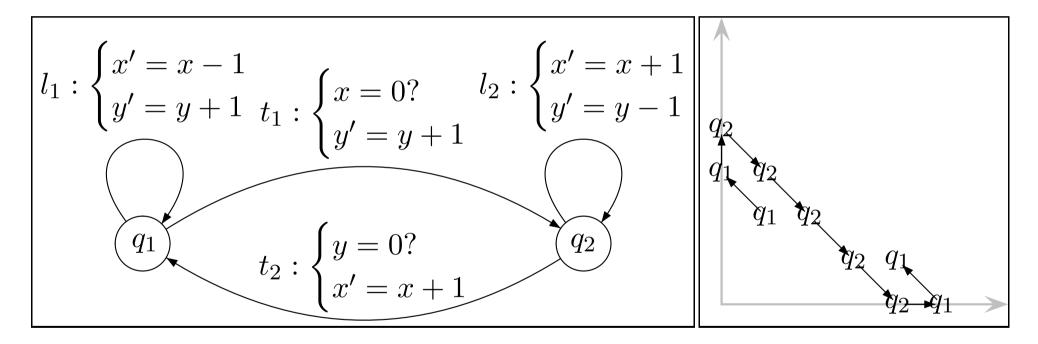
Algorithm does not terminate for non-semilinear counter automata

Does the accelerated algorithm terminate for every semilinear counter automaton?

# Completeness?

Algorithm does not terminate for non-semilinear counter automata

Does the accelerated algorithm terminate for every semilinear counter automaton? No!

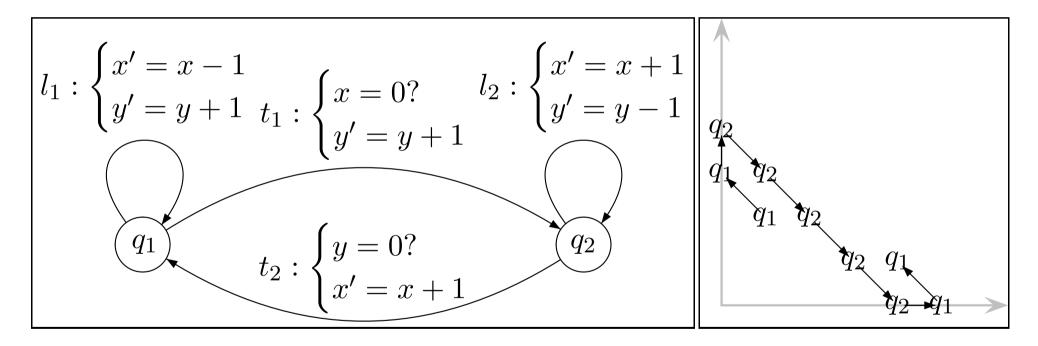


To obtain  $post^*(1,0)$ , we "need" the path:  $(l_1)^1 t_1(l_2)^2 t_2(l_1)^3 t_1(l_2)^4 \cdots$ 

# Completeness?

Algorithm does not terminate for non-semilinear counter automata

Does the accelerated algorithm terminate for every semilinear counter automaton? No!

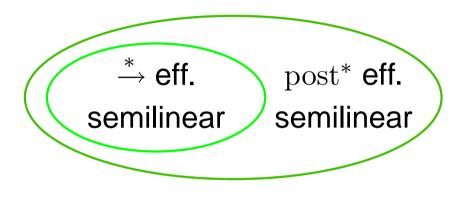


To obtain  $post^*(1,0)$ , we "need" the path:  $(l_1)^1 t_1(l_2)^2 t_2(l_1)^3 t_1(l_2)^4 \cdots$ 

Does the accelerated algorithm terminate for every known semilinear class of counter automata?

# Partial Completeness?

Does the accelerated algorithm terminate for every known semilinear class of counter automata?



Reversible Petri nets BPP nets Test-free 2-counter machines Cyclic Petri nets Persistent Petri nets Conflict-free Petri nets Regular Petri nets Reversal-bounded counter machines Lossy test-free counter machines

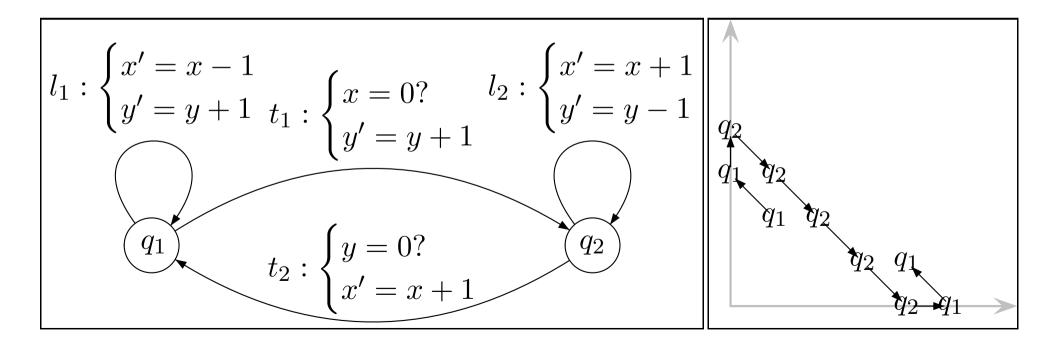
# Outline

# Flat counter automata almost everywhere !

- Introduction.
- $\Rightarrow$  Counter machines, acceleration, flatness.
  - Flat counter machines.
    - Reversal bounded counter machines.
    - Lossy/inserting counter machines.
    - Test-free 2-dim counter machines.
  - Flat Petri nets.
    - Cyclic and reversible Petri nets.
    - Persistent and Conflict-free Petri nets.
    - Regular Petri nets.
    - BPP-nets.
  - Conclusion.

- n counters (ranging over  $\mathbb{N}$ )
- Finite set of locations
- Finite set of transitions, labeled with guarded assignments
  - guards of the form  $\bigwedge x_i \succeq_i \mu_i$ , with  $\succeq_i \in \{=, \geq\}$
  - assignments of the form  $\bigwedge x'_i = x_i + \delta_i$ , with  $\delta_i \in \mathbb{Z}$

- n counters (ranging over  $\mathbb{N}$ )
- Finite set of locations
- Finite set of transitions, labeled with guarded assignments
  - guards of the form  $\bigwedge x_i \succeq_i \mu_i$ , with  $\succeq_i \in \{=, \geq\}$
  - assignments of the form  $\bigwedge x'_i = x_i + \delta_i$ , with  $\delta_i \in \mathbb{Z}$



- n counters (ranging over  $\mathbb{N}$ )
- Finite set of locations
- Finite set of transitions, labeled with guarded assignments
  - guards of the form  $\bigwedge x_i \succeq_i \mu_i$ , with  $\succeq_i \in \{=, \geq\}$
  - assignments of the form  $\bigwedge x'_i = x_i + \delta_i$ , with  $\delta_i \in \mathbb{Z}$
- Configurations:  $(q, x) \in Q \times \mathbb{N}^n$
- $(q, x) \xrightarrow{t} (q', x')$  when
  - control flows from q to q' along transition t
  - counters evolve according to the guarded assignment of transition t

- n counters (ranging over  $\mathbb{N}$ )
- Finite set of locations
- Finite set of transitions, labeled with guarded assignments
  - guards of the form  $\bigwedge x_i \succeq_i \mu_i$ , with  $\succeq_i \in \{=, \geq\}$
  - assignments of the form  $\bigwedge x'_i = x_i + \delta_i$ , with  $\delta_i \in \mathbb{Z}$
- Configurations:  $(q, x) \in Q \times \mathbb{N}^n$
- $(q, x) \xrightarrow{t} (q', x')$  when
  - control flows from q to q' along transition t
  - counters evolve according to the guarded assignment of transition t

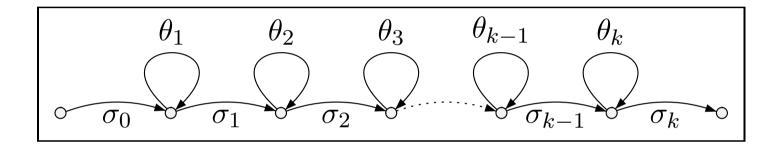
Initialized *n*-dim counter machine: (S, I)

 $\xrightarrow{\pi}$  and  $post(\pi, I)$  are naturally defined for any path  $\pi \in T^*$ .

Global reachability relation  $\xrightarrow{*}$  is  $\xrightarrow{T^*}$ . Reachability set  $post^*(I)$  is  $post(T^*, I)$ .

# Acceleration for counter machines

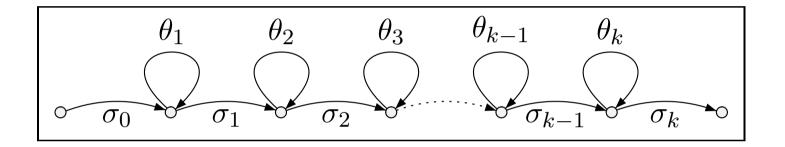
A semilinear path scheme  $\rho \subseteq T^*$  is a finite union of linear path schemes  $\sigma_0 \theta_1^* \sigma_1 \cdots \theta_k^* \sigma_k$ .



Thm[Finkel&Leroux'02, ...]: For any SLPS  $\rho$  in a counter machine S, the reachability subrelation  $\xrightarrow{\rho}$  is effectively semilinear.

# Flatness for counter machines (1/2)

A semilinear path scheme  $\rho \subseteq T^*$  is a finite union of linear path schemes  $\sigma_0 \theta_1^* \sigma_1 \cdots \theta_k^* \sigma_k$ .



A counter machine S is globally flat if  $\xrightarrow{*} = \xrightarrow{\rho}$  for some SLPS  $\rho$ . An initialized counter machine (S, I) is forward flat if  $post^*(I) = post(\rho, I)$  for some SLPS  $\rho$ .

 $\longrightarrow$  Global flatness implies forward flatness for any *I*. Converse false.

- $\xrightarrow{*}$  is effectively semilinear for any globally flat counter machine S
- post\*(*I*) is effectively semilinear for any semilinearly initialized forward flat counter machine (*S*, *I*)

# Flatness for counter machines (2/2)

Input: A counter automaton S.

**Output:** The global reachability relation  $\xrightarrow{*}$ .

let  $R \leftarrow Id$  and repeat forever select one of the following tasks:

- if  $\xrightarrow{T} \cdot R \subseteq R$  return R
- select  $\pi \in T^*$  and  $R', R'' \subseteq R$ let  $R \leftarrow R \cup (R' \cdot \xrightarrow{\pi^*} \cdot R'')$
- select  $t \in T$  and  $R', R'' \subseteq R$ let  $R \leftarrow R \cup (R' \cdot \xrightarrow{t} \cdot R'')$

**Input:** An initialized counter automaton (S, I). **Output:** The reachability set post\*(*I*).

let  $X \leftarrow I$  and repeat forever select one of the following tasks:

- if  $post(T, X) \subseteq X$  return X
- select  $\pi \in T^*$  and  $X' \subseteq X$ let  $X \leftarrow X \cup post(\pi^*, X')$
- select  $t \in T$  and  $X' \subseteq X$

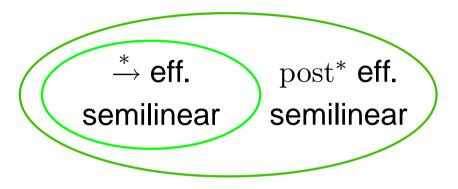
 $\texttt{let} \ X \leftarrow X \cup \texttt{post}(t, X')$ 

Thm: These semi-algorithms are correct, and they admit a terminating execution iff the counter machine is globally/forward flat.

 $\longrightarrow$  The exploration strategy should be "fair" to ensure termination

# Partial Completeness?

Are these known semilinear classes of counter automata flat?



Reversible Petri nets BPP nets Test-free 2-counter machines Cyclic Petri nets Persistent Petri nets Conflict-free Petri nets Regular Petri nets Reversal-bounded counter machines Lossy test-free counter machines

# Outline

# Flat counter automata almost everywhere !

- Introduction.
- Counter machines, acceleration, flatness.
- $\Rightarrow$  Flat counter machines.
  - Reversal bounded counter machines.
  - Lossy/inserting counter machines.
  - Test-free 2-dim counter machines.
  - Flat Petri nets.
    - Cyclic and reversible Petri nets.
    - Persistent and Conflict-free Petri nets.
    - Regular Petri nets.
    - BPP-nets.
  - Conclusion.

# Lossy/inserting counter machines

A counter machine S is called lossy (resp. inserting) when there are loss loops (resp. insertion loops) on each location and for each counter.

Thm: Every initialized lossy test-free counter machine is forward flat.

Key ideas:

- Karp&Miller's algorithm can be seen as a (deterministic) "refinement" of the generic accelerated  $post^*$  computation.
- This accelerated post\* semi-algorithm has a terminating execution iff the initialized counter machine is forward flat.

#### Thm: Every initialized inserting counter machine is forward flat.

Key ideas:

- As  $Min(post^*(I))$  is finite, we have  $post(\rho_m, I) = Min(post^*(I))$  for some finite SLPS  $\rho_m$ .
- Append insertion loops to  $\rho_m$ .

# Outline

# Flat counter automata almost everywhere !

- Introduction.
- Counter machines and acceleration.
- Flat counter machines.
  - Reversal bounded counter machines.
  - Lossy/inserting counter machines.
  - Test-free 2-dim counter machines.
- $\Rightarrow$  Flat Petri nets.
  - Cyclic and reversible Petri nets.
  - Persistent and Conflict-free Petri nets.
  - Regular Petri nets.
  - BPP-nets.
  - Conclusion.

Cyclic Petri nets

A Petri net is a test-free counter machine "without control location", i.e. such that  $Q = \{q_0\}$ .

An initialized Petri net (S, I) is called cyclic if  $I \subseteq post^*(X)$  for every  $X \subseteq post^*(I)$ .

Thm: Every cyclic initialized Petri net is forward flat.

Key idea:

- $post^*(I) = post^*(\{x_0\})$ , where  $x_0 \in I$ .
- $\operatorname{post}^*(I) = \operatorname{Min}(\operatorname{post}^*(\{x_0\})) + (\operatorname{Min}((\operatorname{post}^*(x_0) x_0) \cap \mathbb{N}^n))^*.$

# Reversible Petri nets

A Petri net S is called globally cyclic if  $\xrightarrow{*}$  is symmetric.

Thm: Every globally cyclic Petri net is globally flat.

Key idea:

- $\xrightarrow{*}$  is a congruence on  $\mathbb{N}^n$  and hence it is semilinear.
- Consider  $(x, x') + \{(p_1, p'_1), \dots, (p_k, p'_k)\} \subseteq \xrightarrow{*}$ .
- $x \xrightarrow{\pi_0} x'$  and  $x + p_i \xrightarrow{\pi_i} x' + p'_i \xrightarrow{\overline{\pi_i}} x + p_i$ .

• Take 
$$\rho = (\pi_1 \overline{\pi_0})^* \dots (\pi_k \overline{\pi_0})^* \cdot \pi_0$$
.

A Petri net S is called reversible if for every  $t \in T$ , there is  $t' \in T$  with  $\xrightarrow{t'} = (\xrightarrow{t})^{-1}$ .

Thm: Every reversible Petri net is globally flat.

# Persistent and conflict-free Petri nets

An initialized Petri net (S, I) is called persistent if for any  $x \in post^*(I)$ :

$$x \xrightarrow{t_1} \text{ and } x \xrightarrow{t_2} \implies x \xrightarrow{t_1 t_2}$$

Thm: Every semilinearly-initialized persistent Petri net is forward flat.

Key idea:

 Use the proof in [Landweber&Robertson'78] showing semilinearity of post\* for persistent Petri nets.

A Petri net S is called conflict-free if  $(S, Q \times \mathbb{N}^n)$  is persistent.

Thm: Every conflict-free Petri net is globally flat.

Key idea:

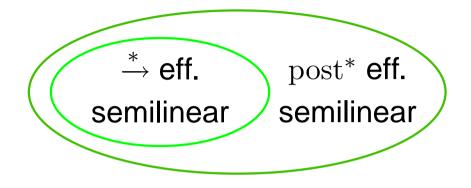
- Duplicate counters: the new counters remain unchanged (not used).
- Use the semilinear set  $I = \{(x, x') \in \mathbb{N}^{2n} \mid x = x'\}.$

# Outline

# Flat counter automata almost everywhere !

- Introduction.
- Counter machines, acceleration, flatness.
- Flat counter machines.
  - Reversal bounded counter machines.
  - Lossy/inserting counter machines.
  - Test-free 2-dim counter machines.
- Flat Petri nets.
  - Cyclic and reversible Petri nets.
  - Persistent and Conflict-free Petri nets.
  - Regular Petri nets.
  - BPP-nets.
- $\Rightarrow$  Conclusion.

# Summary



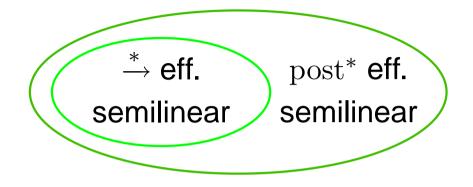
**Reversible Petri nets** 

**BPP** nets

Test-free 2-counter machines

Cyclic Petri nets Persistent Petri nets Conflict-free Petri nets Regular Petri nets Reversal-bounded counter machines Lossy test-free counter machines

# Summary



Reversible Petri nets Conflict-free Petri nets BPP nets

Test-free 2-counter machines

Cyclic Petri nets Persistent Petri nets Regular Petri nets Reversal-bounded counter machines Lossy test-free counter machines

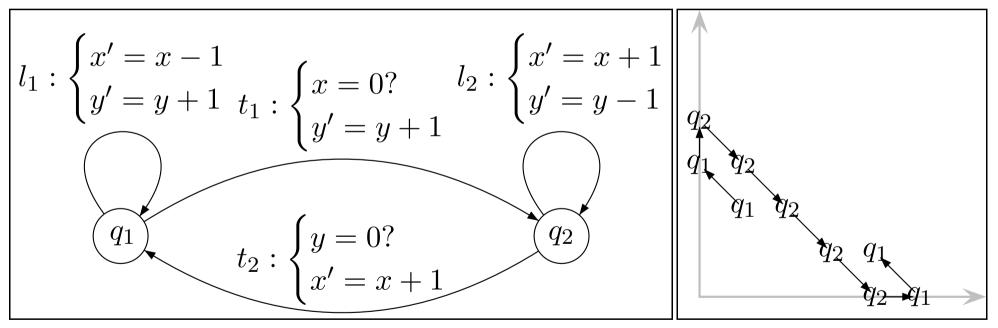
# globally flat

#### forward flat

# Future work

 $\rightarrow$  Flatness for subclasses of 2-counter machines Remark:  $post^*$  and  $pre^*$  are effectively semilinear of lossy 2-counter machines, but these counter machines are not flat in general.

 $\longrightarrow$  Extend acceleration techniques to compute  $post^*$  for:



→ Is global/forward flatness decidable for Petri nets ?

 $\longrightarrow$  Is flatness equivalent to semilinearity of  $\xrightarrow{*}$  /post\* for Petri nets ?



# Reversal-bounded (1/2)

Recall: *T* set of transitions,  $\delta : T \to \mathbb{Z}^n$  displacement labeling. Let  $\varphi_i^{\delta} : T^* \to \{+, -\}^*$  be the morphism defined by:

$$\varphi_i^{\delta}(t) = \begin{cases} + & \text{if } \delta(t)[i] > 0\\ \varepsilon & \text{if } \delta(t)[i] = 0\\ - & \text{if } \delta(t)[i] < 0 \end{cases}$$

Example:  $T = \{t_1, t_2, t_3\}$ ,  $\delta(t_1) = 3$ ,  $\delta(t_2) = 0$ , and  $\delta(t_3) = -1$ . Then  $\varphi_1^{\delta}(t_1t_2t_3t_3) = + - -$ .

An initialized counter machine (S, I) is called reversal-bounded if there exists  $r \in \mathbb{N}$  such that for any  $\pi \in T^*$ :

$$\operatorname{post}(\pi, I) \neq \emptyset \implies \varphi_i^{\delta}(\pi) \in (\{+\}^* \cup \{-\}^*)^{\leq r}$$

An counter machine S is called globally reversal-bounded if  $(S, Q \times \mathbb{N}^n)$  is reversal-bounded.

# Reversal-bounded (2/2)

Thm: Every initialized reversal-bounded counter machine is forward flat. Every globally reversal-bounded counter machine is globally flat.

Key ideas:

- Reduce to the case  $post(\pi, I) \neq \emptyset$  implies  $\varphi_i^{\delta}(\pi) \in \{+\}^* \cup \{-\}^*$ .
- Remove the intermediate guards along  $\pi$ . Example:  $T = \{t_1, t_2\}$  with  $\delta(t_1) = (1, -2)$  and  $\delta(t_2) = (2, -1)$ .
- Extract from the regular langage  $\mathcal{L}$  defined by the control graph, an SLPS  $\rho \subseteq \mathcal{L}$  such that  $\delta(\mathcal{L}) = \delta(\rho)$  with a variant of Parikh's theorem.

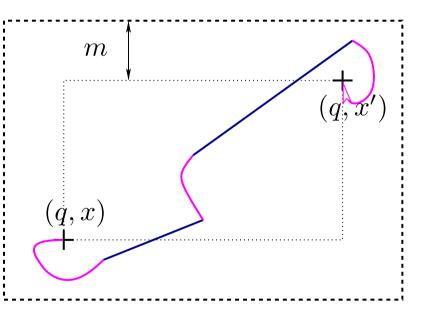
# Test-free 2-dim counter machines

A counter machine S is called test-free when  $\mu: T \to \{\geq\}^n$ .

Thm: Every test-free 2-dim counter machine is globally flat.

Key ideas:

• Every path  $\pi \in T^*$  can be re-ordered into a zigzag-free path:



- For large counter values, we obtain some kind of reversal-bounded counter machine.
- Split  $\mathbb{N}^n$  into four zones:  $\{[0, c], [c, \infty[\}^2 \text{ and show flatness for each.}\}$

# Regular Petri nets

A singly initialized Petri net  $(S, \{x_0\})$  is said regular if the following trace language  $\mathcal{L}$  is regular:

$$\mathcal{L} = \{ \pi \in T^* \mid \text{post}(\pi, \{x_0\}) \neq \emptyset \}$$

Thm: Every regular singly initialized Petri net is forward flat.

Key idea:

Extract from L an SLPS ρ ⊆ L such that δ(L) = δ(ρ) with a variant of Parikh's theorem.

# **BPP-nets**

A Petri net S is called a BPP-net if for any  $t \in T$ , we have:

 $\mu(t) = (0, \dots, 0, 1, 0, \dots, 0)$ 

Thm[Fribourg&Olsen'97]: Every BPP-net is globally flat.

Key idea: Let R be defined by  $t_1Rt_2$  iff  $\mu(t_1) + \delta(t_1) \ge \mu(t_2)$ .

- $post(t_1, \{x\}) \neq \emptyset$  implies  $post(t_1t_2, \{x\}) \neq \emptyset$  for any  $t_1Rt_2$ .
- Moreover if  $\theta = t_1 \dots t_n$  with  $t_1 R \dots R t_n R t_1$ , then  $\delta(\theta) \ge 0$ .
- Build an SLPS  $\rho = \theta_1^* \dots \theta_k^*$  where  $\theta_i \in T$  or  $\theta_i = t_1 \dots t_n$ with  $t_1, \dots, t_n$  2 by 2 distincts and  $t_1 R \dots R t_n R t_1$ .