Temporal Logics for Concurrent Recursive Programs: Satisfiability and Model Checking

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Motivation

- ▶ Verification of concurrent recursive systems against temporal logics.
- ► We make the verification generic wrt.
 - the models: capture Words, Trees, Nested Words, Mazurkiewicz traces

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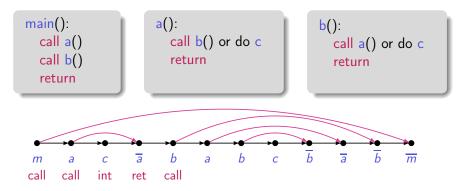
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 - the models: capture Words, Trees, Nested Words, Mazurkiewicz traces
 - ▶ the temporal logics: capture LTL, CTL, PDL (with $^{-1}$ and \cap), XPath.
 - the decidabillity proofs: extend results to both concurrent and recursive
 - the complexity bounds for verifying such concurrent recursive systems.

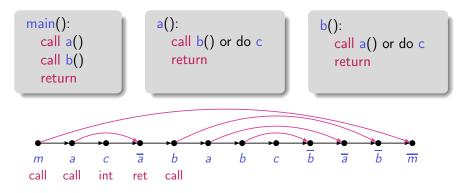
Main Tools

- 1. Linearizations of concurrent recursive behaviors: multiply nested words.
- 2. Tree encoding of multiply nested words.
- 3. Adaptation of existing results for trees.

Recursive Systems



Recursive Systems



Nested Words [Alur, Madhusudan 04–] : (V, act, type, succ, cr)

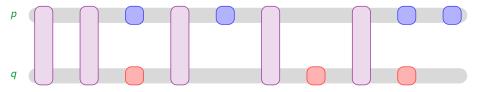
- V: set of nodes (events).
- act : $V \rightarrow Labels$
- type : $V \rightarrow \{\text{call}, \text{ret}, \text{int}\}.$
- succ $\subseteq V \times V$ is the linear successor.
- $cr \subseteq V \times V$ is the matching relation.

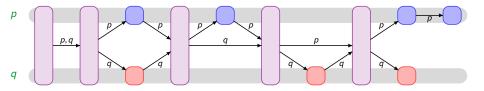
here, Labels = $\{a, b, c, m, r\}$. calls/returns may be unmatched

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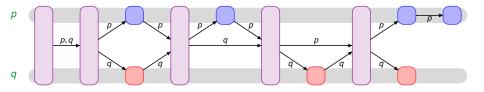




Mazurkiewicz Trace: (V, act, proc, <_p)

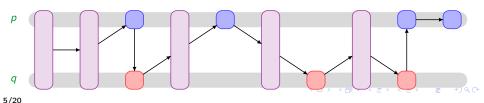
▶ proc : $V \rightarrow \{p, q\}$, and $<_p$ order on process p. Yield partial ordering:

- Two nodes sharing a process must be ordered.
- Two consecutive nodes must share a process.

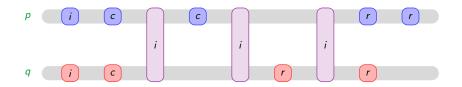


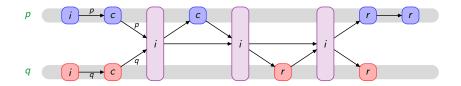
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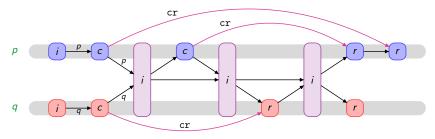
- ▶ proc : $V \rightarrow \{p, q\}$, and $<_p$ order on process p. Yield partial ordering:
 - Two nodes sharing a process must be ordered.
 - Two consecutive nodes must share a process.
- We use linearizations of such traces:





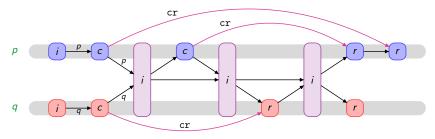




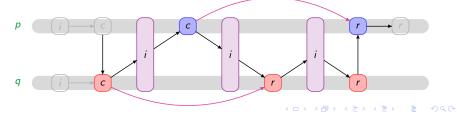


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- ► Nested traces: (V, act, proc, type, <_p, <_q, cr).
- Calls and returns local to one process.

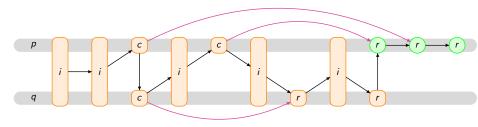


- ► Nested traces: (V, act, proc, type, <_p, <_q, cr).
- Calls and returns local to one process.
- \blacktriangleright \triangle Linearizations need not be nested words!



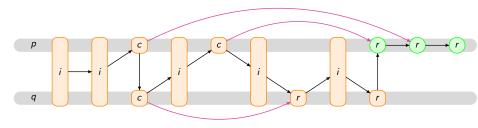
Phases

- ▶ We limit ourselves to *k*-phase nested traces.
- A trace is k-phase if
 - it has a linearization that can be split into k factors.
 - in each factor, only one single process can return.



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► For traces with unbounded phase, crossings of call-return edges of two stacks ~> encoding of the grid.

A generic model: Labeled structures

- Examples models: Words, Trees, Mazurkiewicz traces, Nested traces.
- Models = labeled graphs.
- Signature S = (Σ, Γ).

node labels Σ , edge labels Γ .

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- S-graph $G = (V, \lambda, v)$
- Node-labeling λ: V → 2^Σ, and Edge-labeling ν: (V × V) → 2^Γ.
 Graph induced u → v iff v(u, v) ≠ Ø well-founded and acyclic.

Node formulas
$$\varphi ::= \sigma | \neg \varphi | \varphi \lor \varphi | M(\underbrace{\varphi, \dots, \varphi}_{arity(M)}) | \exists \pi$$

Path expressions π ::= $?\varphi \mid \gamma \mid \gamma^{-1} \mid \pi \cup \pi \mid \pi \cap \pi \mid \pi \circ \pi \mid \pi^*$

- *M* is an MSO(S) modality.
- ► Captures LTL, CTL, PDL (with ∩ and converse), regular XPath, NWTL

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$$M = X(\alpha), \ \bigcup(\alpha, \beta)$$

[[X]](x, Y) = $\exists y (y \in Y \land \text{succ}(x, y))$
[[U]](x, Y, Z) = $\exists z (x \le z \land z \in Z \land \forall y (x \le y < z) \Rightarrow y \in Y)$

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- ► *M* is an MSO(S) modality.
- ► Captures LTL, CTL, PDL (with \cap and converse), regular XPath, NWTL EG $\alpha = \exists$ infinite path from the current node where α always holds.

$$\llbracket \mathsf{EG} \rrbracket(x, X) = \exists Y (Y \subseteq X \land x \in Y \land \forall z (z \in Y \to \exists z' (z' \in Y \land z \text{ succ } z')))$$

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 $M = X(\alpha), Y(\alpha), X^{cr}(\alpha), Y^{cr}(\alpha), \bigcup^{s}(\alpha, \beta), S^{s}(\alpha, \beta)$

Semantics

$$\varphi \quad ::= \quad \sigma \mid \neg \varphi \mid \varphi \lor \varphi \mid M(\underbrace{\varphi, \dots, \varphi}_{\operatorname{arity}(M)}) \mid \exists \pi \\ \pi \quad ::= \quad ?\varphi \mid \gamma \mid \gamma^{-1} \mid \pi \cup \pi \mid \pi \cap \pi \mid \pi \circ \pi \mid \pi^*$$

► A formula is evaluated in an S-graph $G = (V, \lambda, v)$. Node formula φ : $\llbracket \varphi \rrbracket_G \subseteq V$. Path formula π : $\llbracket \pi \rrbracket_G \subseteq V \times V$.

• $?\varphi$ is the set of pairs (x, x) where φ holds at x.

Semantics

A formula is evaluated in an δ-graph G = (V, λ, ν).
Node formula φ: [[φ]]_G ⊆ V. Path formula π: [[π]]_G ⊆ V × V.
?φ is the set of pairs (x, x) where φ holds at x.

Example: Process p is not allowed to call a new procedure when it is in the scope of an active procedure call from q.

MSO modalities over nested traces: NTrLTL

- Logic generalizing both NTrL on traces and NWTL on nested words.
- Ex. In the scope of the current procedure call p and with the same stack contents, there is a synchronizing action with process q.
 - X^{cr} : we are at a call position and φ holds at the corresponding return.

 $[[X^{cr}]](x,Y) = \exists y (cr(x,y) \land y \in Y)$

• $X_p \varphi$: φ holds at the next *p*-position,

 $[[X_{\rho}]](x,Y) = \exists y (\rho(y) \land x \prec y \land y \in Y \land \forall z (\rho(z) \land x \prec z \to y \preceq z))$

- ▶ Binary future modalities {EU, AU, EU^a, EU^s} and { $U_p, U_p^a, U_p^s | p \in Proc$ }.
- ▶ $\varphi AU \psi$: ∃ a future node satisfying ψ , and φ holds on nodes in between.

$$\llbracket AU \rrbracket (x, X_1, X_2) = \exists z (x \leq z \land z \in X_2 \land \forall y (x \leq y \prec z \to z \in X_1))$$

The satisfiability problem

Problem Nested-Trace-SAT parametrized by Proc, act, k, and a temporal logic *L* definable in MSO over nested traces.

Nested-Trace-Sat (\mathcal{L}, k)

- Instance: $\varphi \in Form(\mathscr{L})$
- Question: Is there $G \in Traces_k(Proc, Act)$ and node u such that $G, u \models \varphi$?

Theorem: Nested-Trace-Sat decidability [Bollig, Cyriac, Gastin, Z.]

The problem Nested-Trace-Sat(\mathcal{L}, k) is in 2EXPTIME. Intersection free fragment: Nested-Trace-Sat(\mathcal{L}^-, k) is EXPTIME-complete.

- Same holds for ordered ranked or unranked trees.
- Proof for nested traces: reduction to the case of trees.

Proof for trees

- 1. Precompile [Gastin, Kuske 05] MSO modalities into tree NFA [Rabin 69].
- 2. Inductively build an alternating 2-way tree automaton (A2A) equivalent to the input formula [Göller, Lohrey, Lutz 07].

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3. Reduce SAT to emptiness of A2A, eg [Vardi 98].

Outline of the proof for Nested Traces

- 1. Encode *k*-phase linearizations by binary trees.
- 2. Translate the formula to be checked on *k*-phase linearizations into an MSO formula on binary trees.

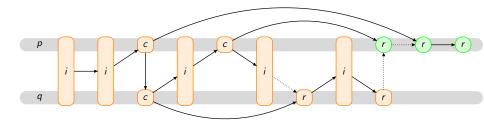
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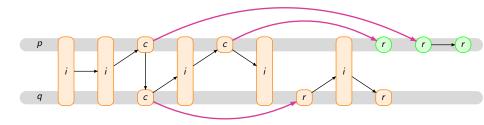
In the following, we fix the max phase number to k.

Encoding nested traces by trees



1. Remove edges leading to matched returns.

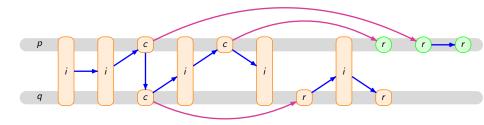
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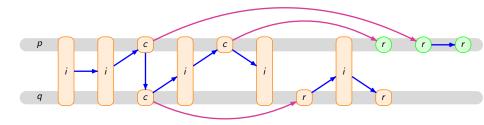
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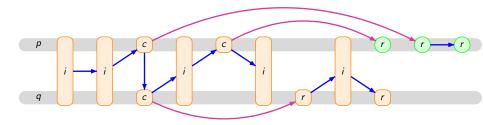


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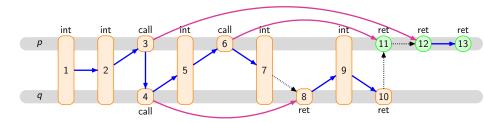
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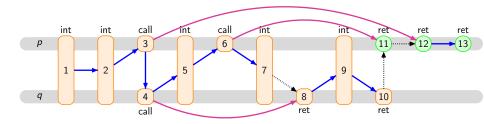
We get trees over an enlarged signature S'.

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From linearization w, tree t_k^w over extended signature S'.

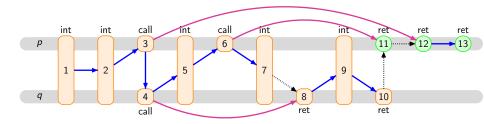
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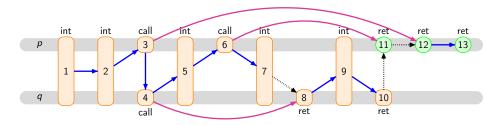
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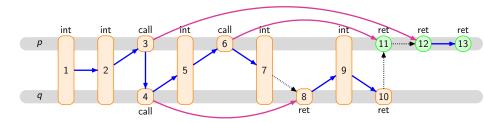
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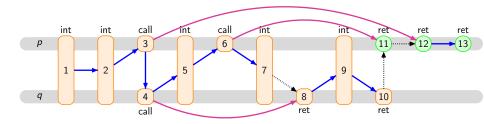


- From linearization w, tree t_k^w over extended signature S'.
- Branching nodes are calls.
- Erased edges may be recovered.
- Phase numbers increase along branches.

Lemma: k-phase trees are MSO-definable [La Torre, Madhusudan, Parlato] The set of tree encoding of k-phase nested traces is MSO(S')-definable.

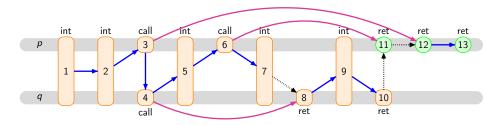


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- ▶ Need: express in MSO(S') the successor relation \lt of the linearization.
- ie, recover in MSO all dotted edges.

Lemma: Successor in linearization is expressible in MSO(S')

For all k-phase linearizations $w = (V, \lambda, \leq)$: $[[\operatorname{succ}_{\leq k}]]_{t_k^w} = \{(u, v) \in V^2 \mid u \leq v\}$. The length of $\operatorname{succ}_{\leq k}$ is exponential in k.

Proof: Induction on the "phase prefix m".

$$[[\operatorname{succ}_{\leq m}]]_{t_k^w} = \left\{ (u, v) \in V^2 \mid u < v, \ phase_w(u) \leq m, \ phase_w(v) \leq m \right\}$$

Distinguish cases:

- 1. the successor remains in the current phase.
- 2. the successor belongs to the next phase

$$\operatorname{succ}_{\leq m} = \operatorname{succ}_{\leq m-1} \cup \operatorname{succ}_{m,m} \cup \operatorname{succ}_{m-1,m}$$
(1)
(2)

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$$\operatorname{succ}_{\leq m} = \operatorname{succ}_{\leq m-1} \cup \operatorname{succ}_{m,m} \cup \operatorname{succ}_{m-1,m}$$

$$(1) \qquad (2)$$

- For (2), the successor is the first node of next phase *m*, hence a return.
- If it is unmatched: $?(m-1) \circ left \circ ?m$.
- If it is matched, find the most recent call whose return is in phase m

$$\operatorname{prev-call-ret}_{m} = (? \neg \exists (\operatorname{right} \circ ?m) \circ \operatorname{succ}_{\leq m-1}^{-1})^{*} \circ \operatorname{right} \circ ?m$$

Model Checking

- > The result goes through for model checking as well.
- ► The notion of concurrent recursive Kripke Systems.
- A CRK can be described by a path expression.

Further work

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- Expressive power, FO completeness?
- ► Handle dynamic creation of threads (eg, dynamic MSCs).

Further work

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Thank you!

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