

Lattice walks confined to the positive octant

Mireille Bousquet-Mélou

Alin Bostan, INRIA Saclay

Manuel Kauers, RISC Linz

Steve Melczer, Simon Fraser University, Vancouver



The question

Let $\mathcal{S} \subset \mathbb{Z}^3$ be a finite set of steps in the 3D space.

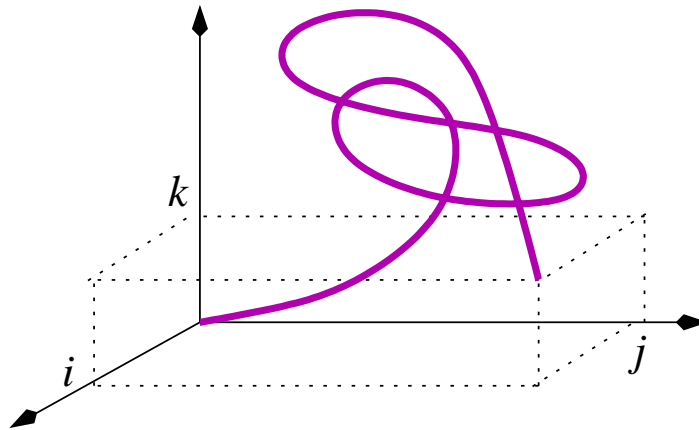
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Consider walks that start from $(0, 0, 0)$, take their steps in \mathcal{S} , and are **confined to the positive octant** $\{(i, j, k) : i \geq 0, j \geq 0, k \geq 0\}$.



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Questions

- Determine $o(n)$, the number of such walks that have length n
- or $o(i, j, k; n)$, the number of such walks that have length n and end at position (i, j, k)
- or the associated 4-variable generating function:

$$O(x, y, z; t) = \sum_{i, j, k, n \geq 0} o(i, j, k; n) x^i y^j z^k t^n$$

- or the **nature** of this generating function.

A hierarchy of formal power series

- The formal power series $A(t)$ is **rational** if it can be written

$$A(t) = \frac{P(t)}{Q(t)}$$

where $P(t)$ and $Q(t)$ are polynomials in t .

- The formal power series $A(t)$ is **algebraic** (over $\mathbb{Q}(t)$) if it satisfies a (non-trivial) polynomial equation:

$$P(t, A(t)) = 0.$$

- The formal power series $A(t)$ is **D-finite** if it satisfies a (non-trivial) linear differential equation:

$$P_k(t)A^{(k)}(t) + \cdots + P_0(t)A(t) = 0.$$

+ extension to several variables + closure properties

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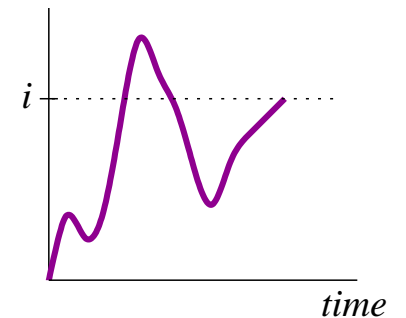
- or the **nature** of this generating function.

Lattice paths confined to convex cones

- **Dimension 1:** walks confined to a half-line

The generating function $H(x; t)$ is **always algebraic**

[Gessel 80], [Labelle-Yeh 90], [mbm-Petkovšek 00],
[Duchon 00], [Banderier-Flajolet 02]

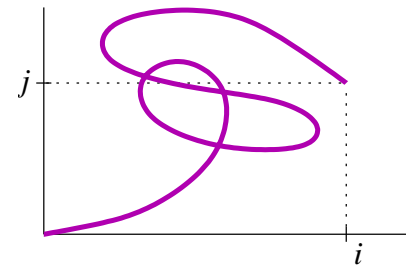


- **Dimension 2:** walks confined to the positive quadrant

The generating function $Q(x, y; t)$ is sometimes algebraic, sometimes D-finite, sometimes non-D-finite.

Complete classification for walks with “small” steps:

$$\mathcal{S} \subset \{\bar{1}, 0, 1\}^2$$

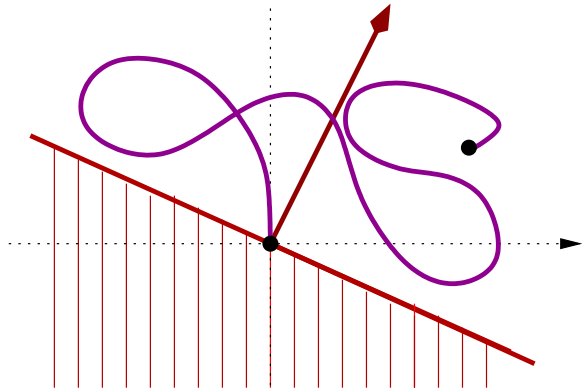


Bernardi, Bostan, MBM, Cori, Denisov, Dulucq, Fayolle, Gessel, Gouyou-Beauchamps, Guy, Janse van Rensburg, Johnson, Kauers, Koutschan, Krattenthaler, Kurkova, Kreweras, Melczer, Mishna, Niederhausen, Petkovšek, Prellberg, Raschel, Rechnitzer, Sagan, Salvy, Viennot, Wachtel, Wilf, Yeats, Zeilberger...

Why just *positive* cones?

In 2D, a convex rational cone is either:

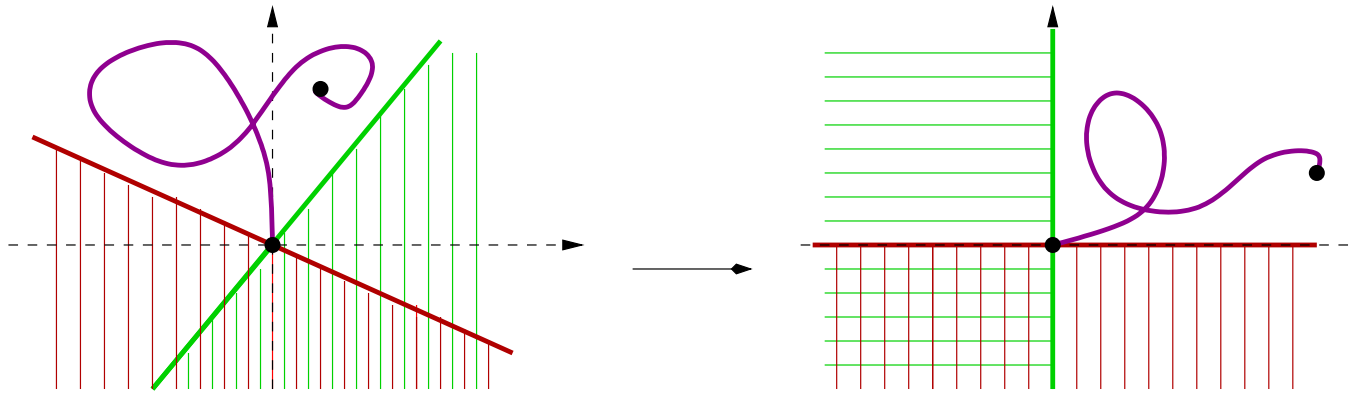
- a half-plane



⇒ equivalent to a
(weighted) model of
walks on a half-line

⇒ algebraic

- or a linear deformation of the quadrant



⇒ equivalent to a quadrant model

3D walks in an octant — Small steps

Let $\mathcal{S} \subset \{\bar{1}, 0, 1\}^3 \setminus \{(0, 0, 0)\}$ be a set of **small** steps in the 3D space.

Questions

- Determine $o(n)$, or $o(i, j, k; n)$ (number of walks)
- or the associated generating function:

$$O(x, y, z; t) = \sum_{i, j, k, n \geq 0} o(i, j, k; n) x^i y^j z^k t^n.$$

There are “only” 2^{26} such problems!

~~Specific question~~

~~Ad hoc solution~~ →

Systematic approach

The number of interesting distinct models

Remove

- models in which all steps are non-negative (rational GF)
- models in which one positivity condition implies the other two
(\sim walks in a half-space \Rightarrow algebraic GF)
- models in which one step is never used

and declare **equivalent** models that only differ by a permutation of the coordinates.

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Proposition: one is left with $11\,074\,225 \simeq 2^{23.4\dots}$ distinct models.

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Proposition: one is left with 11 074 225 $\simeq 2^{23.4\dots}$ distinct models.

With at most 6 steps:

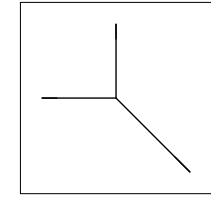
$$73 u^3 + 979 u^4 + 6425 u^5 + 28071 u^6 + O(u^7)$$

We focus on the 35 548 models with at most 6 steps.

I. Some useful tools

**I.1. A step-by-step construction,
and the associated functional equation**

A functional equation: example in 2D



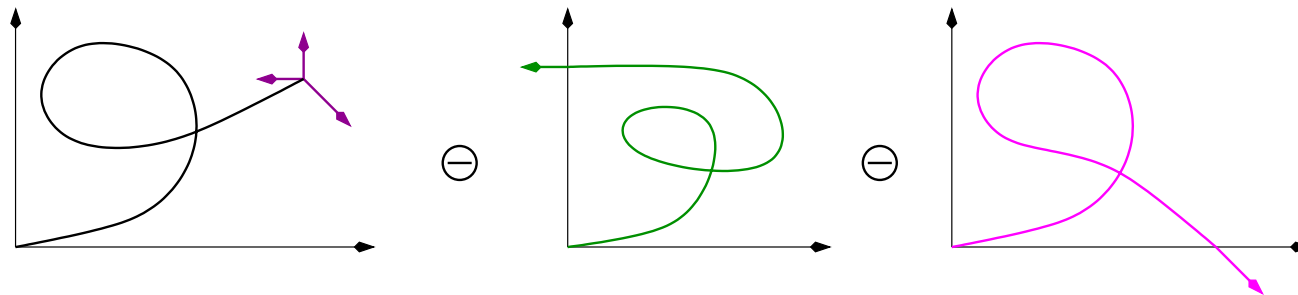
Example: $\mathcal{S} = \{N, W, SE\}$

Generating function:

$$Q(x, y; t) = \sum_{i, j, n \geq 0} q(i, j; n) x^i y^j t^n$$

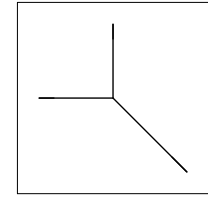
Functional equation:

$$Q(x, y; t) \equiv Q(x, y) = 1 + tyQ(x, y) + t \frac{Q(x, y) - Q(0, y)}{x} + tx \frac{Q(x, y) - Q(x, 0)}{y}$$



A linear **discrete** partial differential equation

A functional equation: example in 2D



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or, with $\bar{x} = 1/x$ and $\bar{y} = 1/y$,

$$(1 - t(y + \bar{x} + x\bar{y}))Q(x, y) = 1 - t\bar{x}Q(0, y) - tx\bar{y}Q(x, 0),$$

or

$$\boxed{(1 - t(y + \bar{x} + x\bar{y}))xyQ(x, y) = xy - tyQ(0, y) - txQ(x, 0)}$$

We call $K(x, y) = (1 - t(y + \bar{x} + x\bar{y}))$ the **kernel** of the equation.

A functional equation: example in 3D

- Take $\mathcal{S} = \{\bar{1}\bar{1}\bar{1}, \bar{1}\bar{1}1, \bar{1}10, 100\}$. The functional equation reads

$$\begin{aligned} O(x, y, z) = & 1 + t(\bar{x}\bar{y}\bar{z} + \bar{x}\bar{y}z + \bar{x}y + x)O(x, y, z) \\ & - t\bar{x}(y + \bar{y}z + \bar{y}\bar{z})O(0, y, z) - t\bar{x}\bar{y}(z + \bar{z})O(x, 0, z) - t\bar{x}\bar{y}\bar{z}O(x, y, 0) \\ & + t\bar{x}\bar{y}(z + \bar{z})O(0, 0, z) + t\bar{x}\bar{y}\bar{z}O(0, y, 0) + t\bar{x}\bar{y}\bar{z}O(x, 0, 0) \\ & - t\bar{x}\bar{y}\bar{z}O(0, 0, 0). \end{aligned}$$

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- Equivalently,

$$\begin{aligned} K(x, y, z)xyzO(x, y, z) = & xyz - tyz(y + \bar{y}z + \bar{y}\bar{z})O(0, y, z) - tz(z + \bar{z})O(x, 0, z) \\ & - tO(x, y, 0) + tz(z + \bar{z})O(0, 0, z) + tO(0, y, 0) + tO(x, 0, 0) - tO(0, 0, 0) \end{aligned}$$

where the kernel is

$$K(x, y, z) = 1 - t(\bar{x}\bar{y}\bar{z} + \bar{x}\bar{y}z + \bar{x}y + x).$$

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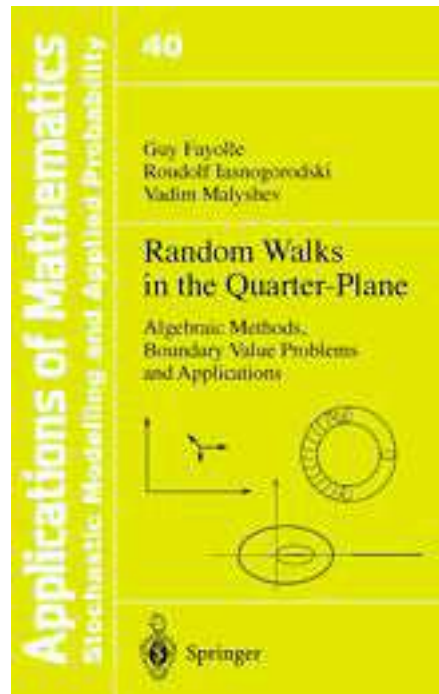
$$K(x, y, z) = 1 - t(\bar{x}\bar{y}\bar{z} + \bar{x}\bar{y}z + \bar{x}y + x).$$

\Rightarrow Determine $O(x, y, z; t)$ up to a large order (in t) and try to guess if it is algebraic or D-finite (order $\simeq 50$ and degree $\simeq 3000$ is not unusual).

I. Some useful tools

I.2. The group of the walk

[Fayolle et al. 99]



What is this group? A 2D example

When $\mathcal{S} = \{N, W, SE\}$, the kernel reads

$$K(x, y) = 1 - tS(x, y) \quad \text{with} \quad S(x, y) = \bar{x} + y + x\bar{y}.$$

Observation: $S(x, y)$ (and thus $K(x, y)$) is left unchanged by the rational transformations

$$\Phi : (x, y) \mapsto (\bar{x}y, y) \quad \text{and} \quad \Psi : (x, y) \mapsto (x, x\bar{y}).$$

They are involutions, and generate a finite group G :

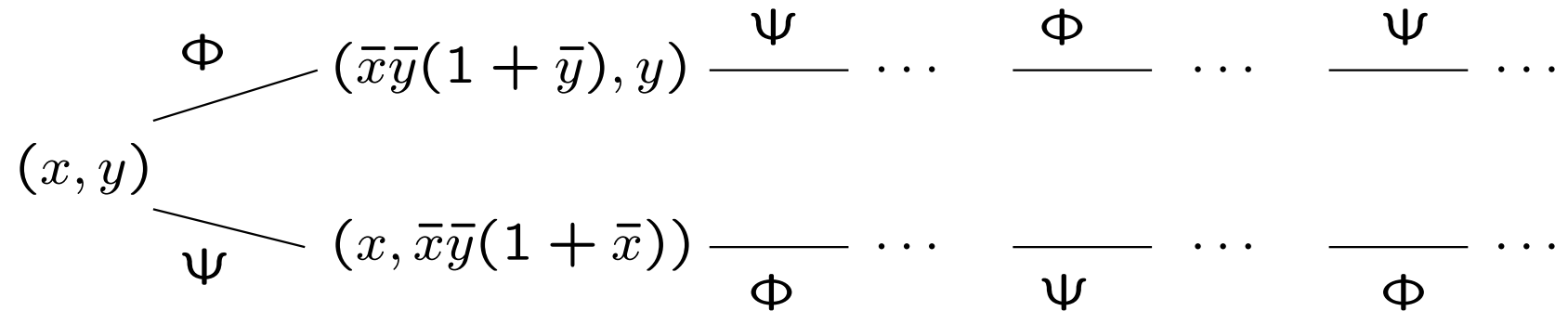
$$\begin{array}{ccccc}
 & & \Phi & & \Psi & & & & \Phi & & \\
 & & \nearrow & & \text{---} & & \searrow & & & & \\
 & & (\bar{x}y, y) & & (\bar{x}y, \bar{x}) & & & & (\bar{y}, \bar{x}) & & \\
 (x, y) & & & & & & & & & & \\
 & & \searrow & & \text{---} & & \nearrow & & & & \\
 & & (x, x\bar{y}) & & (\bar{y}, x\bar{y}) & & & & & & \\
 & & \Psi & & \Phi & & \Psi & & & &
 \end{array}$$

The group is not always finite

- If $\mathcal{S} = \{S, W, SW, NE\}$:

$$\Phi : (x, y) \mapsto (\bar{x}\bar{y}(1 + \bar{y}), y) \quad \text{and} \quad \Psi : (x, y) \mapsto (x, \bar{x}\bar{y}(1 + \bar{x}))$$

seem to generate an infinite group



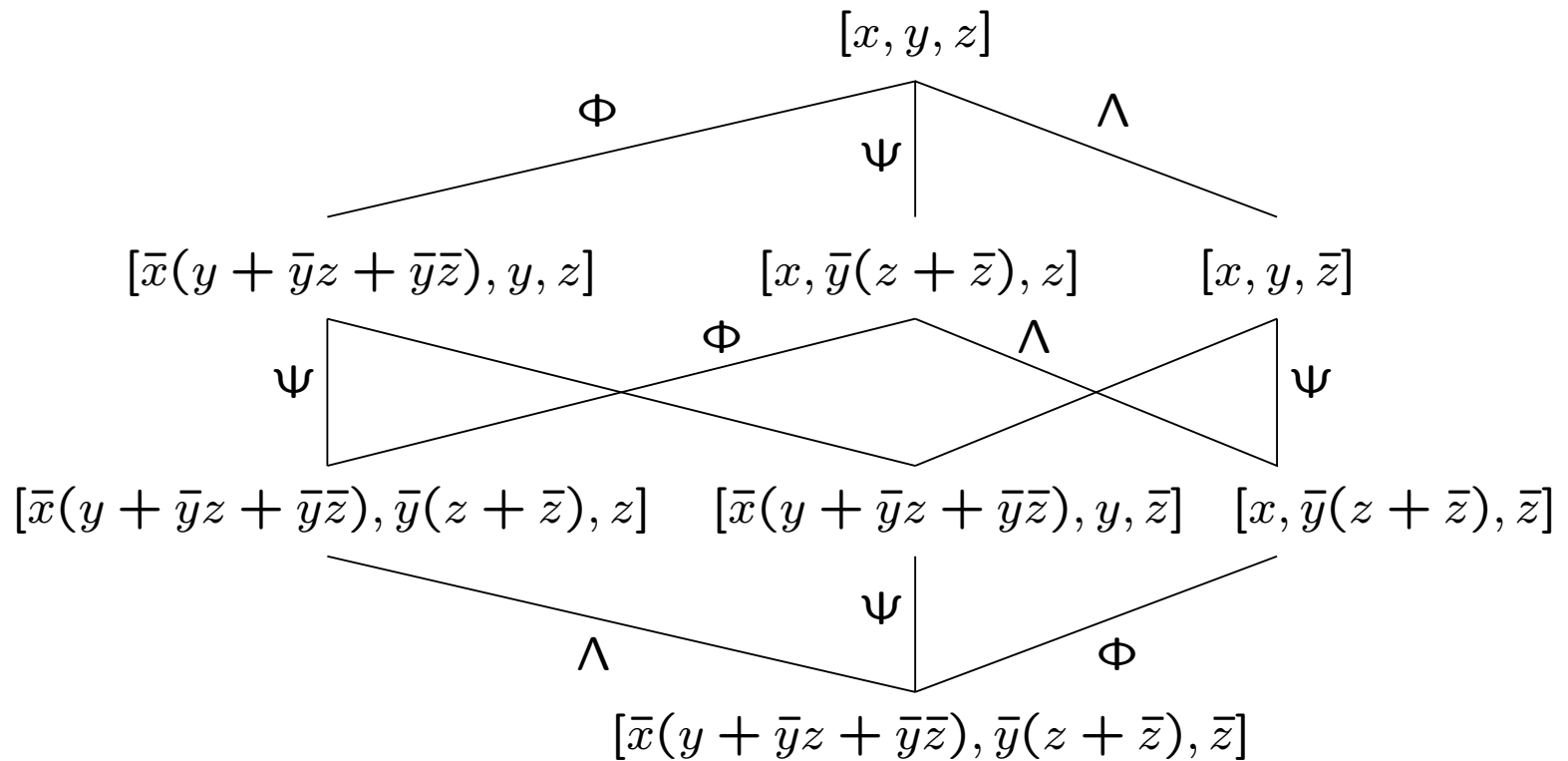
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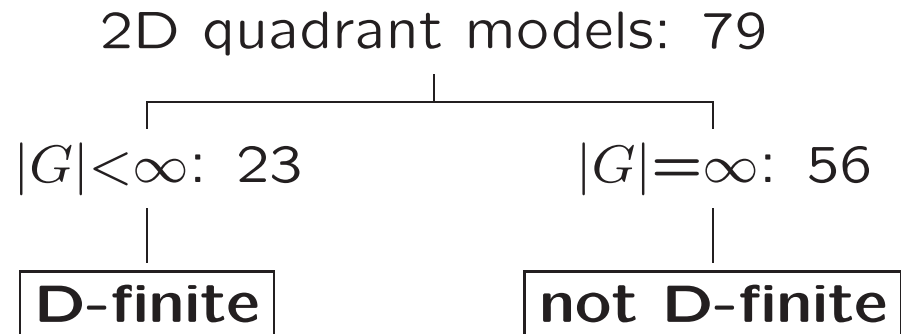
$$K(x, y, z) = 1 - t(\bar{x}\bar{y}\bar{z} + \bar{x}\bar{y}z + \bar{x}y + x).$$

- The group is generated by

$$[x, y, z] \xrightarrow{\Phi} [\bar{x}(y + \bar{y}z + \bar{y}\bar{z}), y, z], \quad [x, y, z] \xrightarrow{\Psi} [x, \bar{y}(z + \bar{z}), z], \quad [x, y, z] \xrightarrow{\Lambda} [x, y, \bar{z}].$$



Relevance of the group size: Classification of quadrant walks with small steps



I. Some useful tools

I.3. Models with a finite group:

The orbit equation

The orbit equation: when $\mathcal{S} = \{N, W, SE\}$

- The equation reads

$$K(x, y) \quad xyQ(x, y) = xy - txQ(x, 0) - tyQ(0, y) \quad \text{with } K(x, y) = 1 - t(y + \bar{x} + x\bar{y}).$$

- The orbit of (x, y) under G is

$$(x, y) \xleftrightarrow{\Phi} (\bar{x}y, y) \xleftrightarrow{\Psi} (\bar{x}y, \bar{x}) \xleftrightarrow{\Phi} (\bar{y}, \bar{x}) \xleftrightarrow{\Psi} (\bar{y}, x\bar{y}) \xleftrightarrow{\Phi} (x, x\bar{y}) \xleftrightarrow{\Psi} (x, y).$$

- All transformations of G leave $K(x, y)$ invariant. Hence

$$\begin{aligned} K(x, y) \quad xyQ(x, y) &= xy - txQ(x, 0) - tyQ(0, y) \\ K(x, y) \quad \bar{x}y^2Q(\bar{x}y, y) &= \bar{x}y^2 - t\bar{x}yQ(\bar{x}y, 0) - tyQ(0, y) \end{aligned}$$

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The orbit equation: when $\mathcal{S} = \{N, W, SE\}$

- All transformations of G leave $K(x, y)$ invariant. Hence

$$\begin{aligned}
 K(x, y) \quad xyQ(x, y) &= xy - txQ(x, 0) - tyQ(0, y) \\
 K(x, y) \quad \bar{x}y^2Q(\bar{x}y, y) &= \bar{x}y^2 - t\bar{x}yQ(\bar{x}y, 0) - tyQ(0, y) \\
 K(x, y) \quad \bar{x}^2yQ(\bar{x}y, \bar{x}) &= \bar{x}^2y - t\bar{x}yQ(\bar{x}y, 0) - t\bar{x}Q(0, \bar{x}) \\
 \dots &= \dots \\
 K(x, y) \quad x^2\bar{y}Q(x, x\bar{y}) &= x^2\bar{y} - txQ(x, 0) - tx\bar{y}Q(0, x\bar{y}).
 \end{aligned}$$

⇒ Form the alternating sum of the equation over all elements of the orbit:

$$\begin{aligned}
 K(x, y) \left(xyQ(x, y) - \bar{x}y^2Q(\bar{x}y, y) + \bar{x}^2yQ(\bar{x}y, \bar{x}) \right. \\
 \left. - \bar{x}\bar{y}Q(\bar{y}, \bar{x}) + x\bar{y}^2Q(\bar{y}, x\bar{y}) - x^2\bar{y}Q(x, x\bar{y}) \right) = \\
 xy - \bar{x}y^2 + \bar{x}^2y - \bar{x}\bar{y} + x\bar{y}^2 - x^2\bar{y}.
 \end{aligned}$$

The orbit equation in general

For all models with a finite group,

$$\sum_{g \in G} \text{sign}(g) g(xyQ(x, y; t)) = \frac{1}{K(x, y; t)} \sum_{g \in G} \text{sign}(g) g(xy),$$

where

$$g(A(x, y)) := A(g(x, y))$$

- The right-hand side is a rational series, called the **orbit sum**.

Example:

$$\begin{aligned} & xyQ(x, y) - \bar{x}y^2Q(\bar{x}y, y) + \bar{x}^2yQ(\bar{x}y, \bar{x}) \\ & - \bar{x}\bar{y}Q(\bar{y}, \bar{x}) + x\bar{y}^2Q(\bar{y}, x\bar{y}) - x^2\bar{y}Q(x, x\bar{y}) = \\ & \frac{xy - \bar{x}y^2 + \bar{x}^2y - \bar{x}\bar{y} + x\bar{y}^2 - x^2\bar{y}}{1 - t(y + \bar{x} + x\bar{y})}. \end{aligned}$$

I. Some useful tools

I.4. Models with a finite group: Extracting the main generating function in the orbit equation

A 2D example: $\mathcal{S} = \{N, W, SE\}$

$$\begin{aligned} &xyQ(x, y) - \bar{x}y^2Q(\bar{x}y, y) + \bar{x}^2yQ(\bar{x}y, \bar{x}) \\ &\quad - \bar{x}\bar{y}Q(\bar{y}, \bar{x}) + x\bar{y}^2Q(\bar{y}, x\bar{y}) - x^2\bar{y}Q(x, x\bar{y}) = \\ &\qquad\qquad\qquad \frac{xy - \bar{x}y^2 + \bar{x}^2y - \bar{x}\bar{y} + x\bar{y}^2 - x^2\bar{y}}{1 - t(y + \bar{x} + x\bar{y})} \end{aligned}$$

- Both sides are power series in t , with coefficients in $\mathbb{Q}[x, \bar{x}, y, \bar{y}]$.
- Extract the part with positive powers of x and y :

$$xyQ(x, y) = [x^{>0}y^{>0}] \frac{xy - \bar{x}y^2 + \bar{x}^2y - \bar{x}\bar{y} + x\bar{y}^2 - x^2\bar{y}}{1 - t(y + \bar{x} + x\bar{y})}$$

is a D-finite series.

[Lipshitz 88]

Extraction for quadrant models

- For 23 models, we found a finite group and wrote the orbit equation:

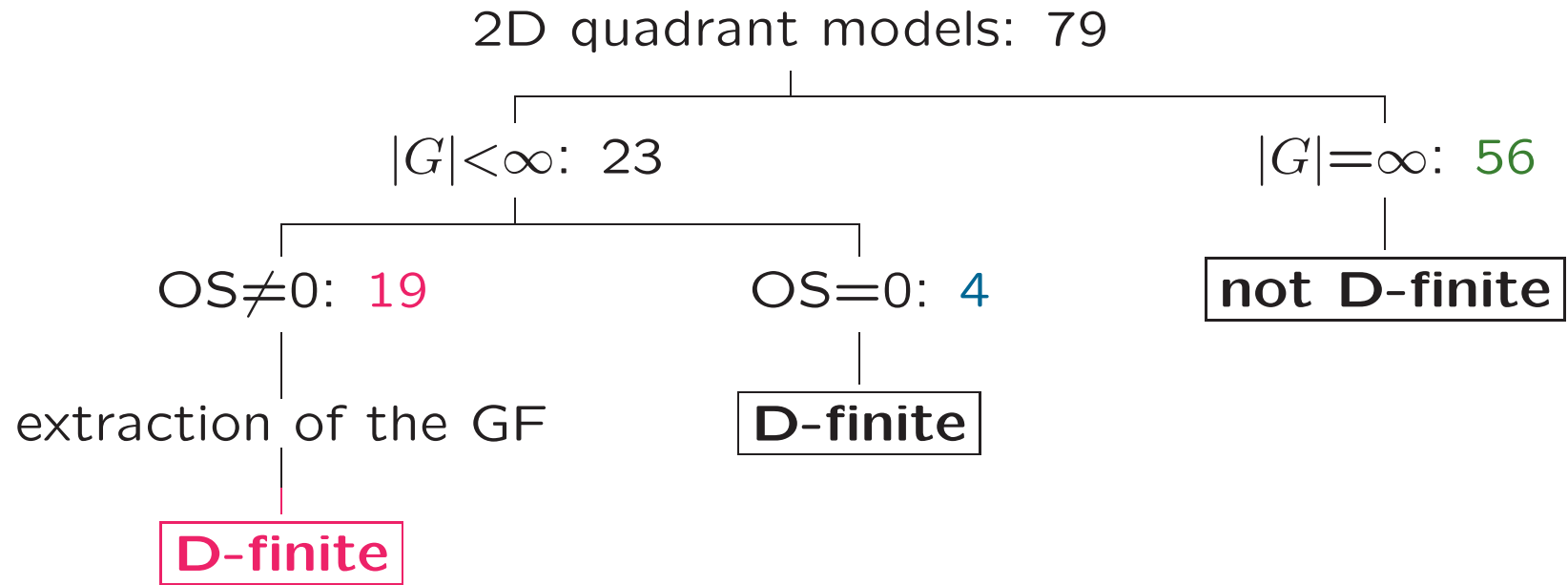
$$\sum_{g \in G} \text{sign}(g) g(xyQ(x, y; t)) = \frac{1}{K(x, y; t)} \sum_{g \in G} \text{sign}(g) g(xy),$$

- For the 19 models where the orbit sum is non-zero,

$$xyQ(x, y; t) = [x^{>0}y^{>0}] \frac{1}{K(x, y; t)} \sum_{g \in G} \text{sign}(g) g(xy)$$

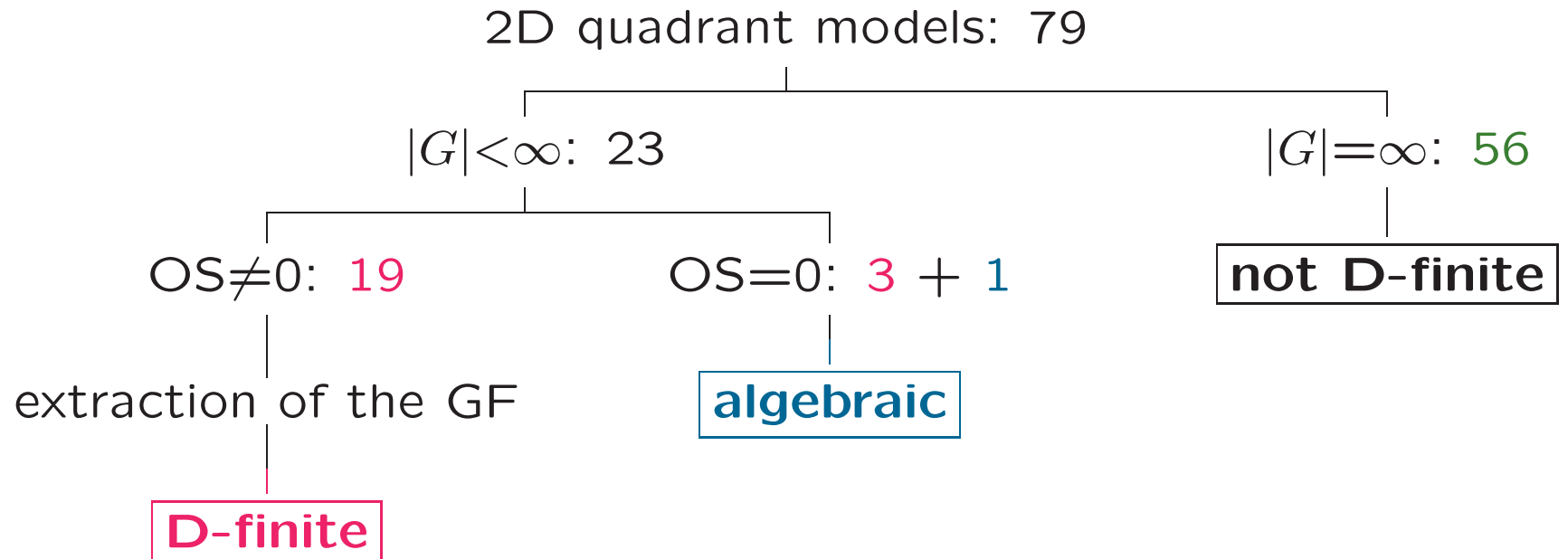
is a D-finite series.

Classification of quadrant walks with small steps



[mbm-Mishna 10]

Classification of quadrant walks with small steps



[mbm-Mishna 10], [Bostan-Kauers 10], [Bostan-Kurkova-Raschel 13(a)]

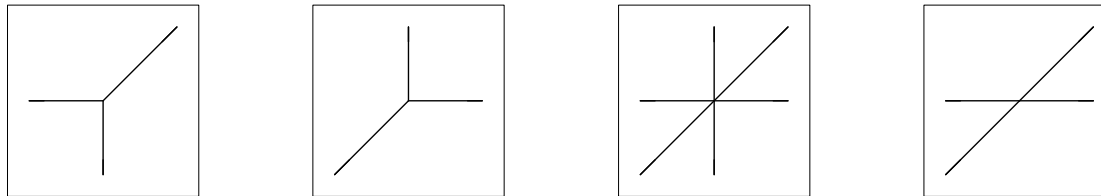
When the orbit sum is zero

In 4 cases, the orbit sum vanishes:

$$\sum_{g \in G} \text{sign}(g)g(xyQ(x, y; t)) = \frac{1}{K(x, y; t)} \sum_{g \in G} \text{sign}(g)g(xy) = 0.$$

This happens:

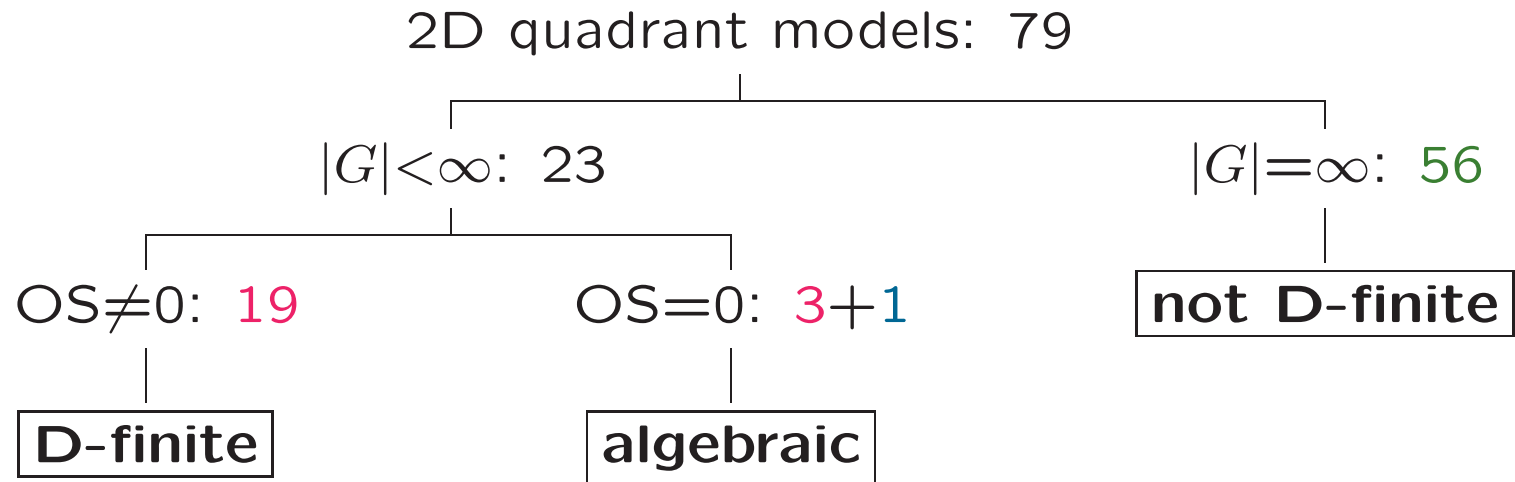
- for the Kreweras trilogy, $\mathcal{S} = \{W, S, NE\}, \{E, N, SW\}, \{W, S, E, N, NE, SW\}$,
- for Gessel's walks, $\mathcal{S} = \{E, W, NE, SW\}$.



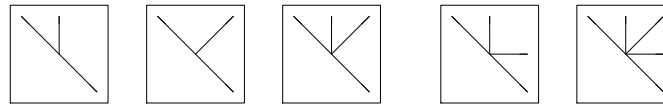
In all 4 cases, $Q(x, y; t)$ is algebraic.

[mbm-Mishna 10], [Bostan-Kauers 10], [Bostan-Kurkova-Raschel 13(a)]

Classification of quadrant walks



- D-finiteness and algebraicity: [mbm-Mishna 10], [Bostan-Kauers 10], [Bostan-Kurkova-Raschel 13(a)]
- Non-D-finiteness:
 - 5 singular cases: $Q(1, 1; t)$ is not D-finite [Mishna-Rechnitzer 07], [Melczer-Mishna 13]



- 51 non-singular cases: $Q(0, 0; t)$ is not D-finite [Bostan-Raschel-Salvy 14], and $Q(x, 0; t)$ is not D-finite in x [Kurkova-Raschel 12]

II. Application to octant models

The dimension of a model

Definition. A model has dimension (at most) d if d of the positivity conditions imply the remaining $3 - d$ ones.

We have already discarded models of dimension 0 or 1.

Proposition. Among the 35 548 models with at most 6 steps, 14 744 have dimension two and 20 804 have dimension three.

(integer linear programming)

Our toolbox

- Write a functional equation for $O(x, y, z; t) = \sum_{i,j,k,n} o(i, j, k; n) x^i y^j z^k t^n$
- Determine if the group of the walk is finite
- If it is, form the orbit equation
- and *try to* extract the generating function $O(x, y, z; t)$

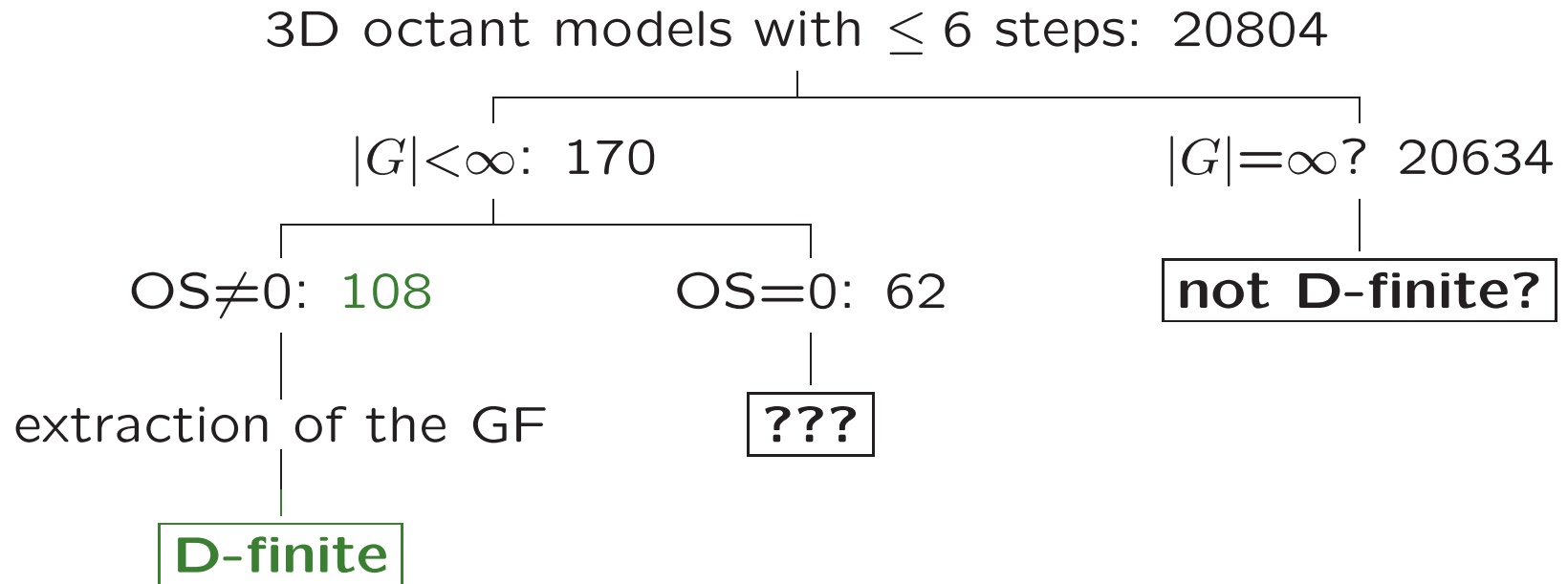
Our toolbox

- Write a functional equation for $O(x, y, z; t) = \sum_{i,j,k,n} o(i, j, k; n) x^i y^j z^k t^n$
- Determine if the group of the walk is finite
- If it is, form the orbit equation
- and *try to* extract the generating function $O(x, y, z; t)$

What happens?

III. Three-dimensional octant models (with at most 6 steps)

Classification of 3D octant models (with at most 6 steps)



[Bostan-MBM-Kauers-Melczer 14]

When the orbit sum **is** zero (62 models)

- For 19 models, including 3D Kreweras, we **did not guess** any DE

Example:

$$\mathcal{S} = \{111, \bar{1}00, 0\bar{1}0, 00\bar{1}\}$$

- the remaining 43 models are **of Hadamard type** and D-finite

Hadamard models: example

Take $S(x, y, z) = x + (1 + x + \bar{x})(yz + \bar{y} + \bar{z})$. The group has order 12, and the orbit sum is zero.

To construct an octant walk of length n with steps in \mathcal{S} :

- take a 1D walk $h = h_1 \dots h_n$ with steps in $\{\bar{1}, 0, 1, \mathbf{1}\}$ on the x -axis; say it has ℓ black steps;
- take a quadrant walk $q = q_1 \dots q_\ell$ with steps in $\{11, \bar{1}0, 0\bar{1}\}$ in the yz -plane;
- in h , replace h_i by $(h_i, 0, 0)$ if h_i is red, by (h_i, q_j) if h_i is the j th black step of h .

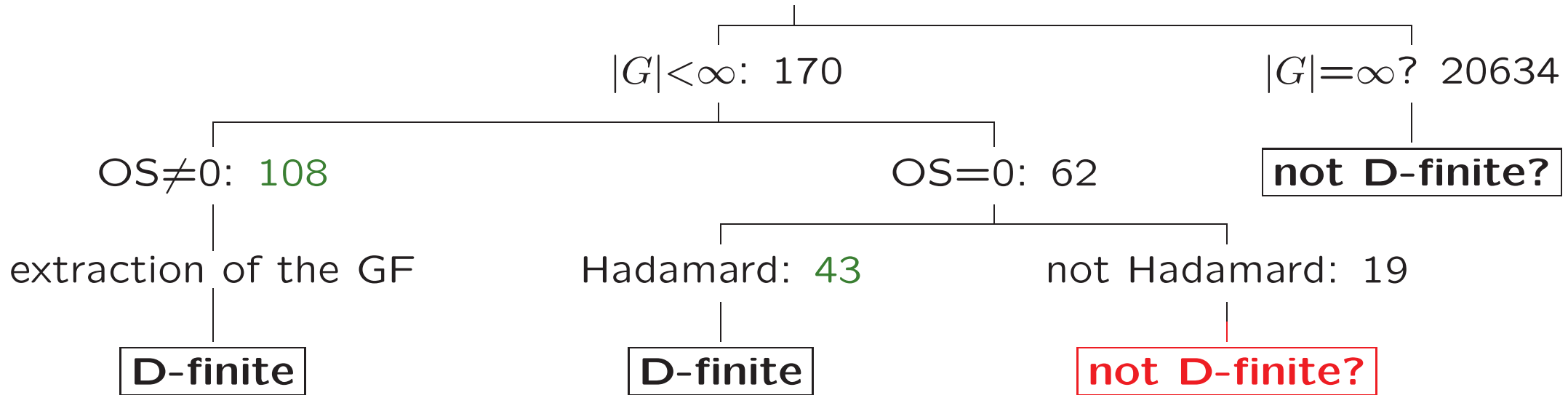
The D-finiteness of $O(x, y, z; t)$ then follows from the D-finiteness of the GFs $H(x; t)$ and $Q(y, z; t)$ of the two projected walks.

The argument applies with $S(x, y, z) = U(x) + V(x)T(y, z)$ or

$$S(x, y, z) = U(x, y) + V(x, y)T(z).$$

Classification of 3D octant models

3D octant models with ≤ 6 steps: 20804



[Bostan-MBM-Kauers-Melczer 14]

IV. Two-dimensional octant models (with at most 6 steps)

- One positivity condition (say, in z) holds automatically if the other two hold.
- Study the projection of the walk on the xy -plane: multiset of steps

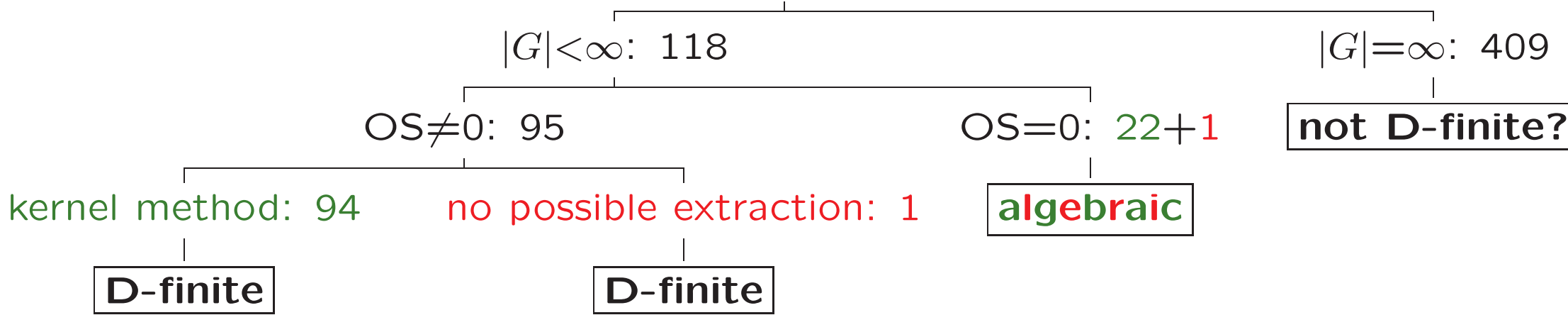
$$\mathcal{S}_1 = \{ij : \exists k \text{ such that } ijk \in \mathcal{S}\} \setminus \{00\}$$

Main series:

$$Q(x, y; t) := O(x, y, 1; t)$$

Classification of 2D quadrant models with (possibly) repeated steps

2D quadrant models with ≤ 6 steps (possibly repeated): 527



[Bostan-MBM-Kauers-Melczer 14]

Two remarkable quadrant models with repeated steps

Proposition

- For the quadrant model $\mathcal{S} = \{\bar{1}\bar{1}, \bar{1}0, 1\bar{1}, 10, 10, 11\}$ (with an East repeated step), the generating function $Q(x, y; t)$ is algebraic. Moreover some coefficients are nice:

$$Q(0, y; t) = \sum_{n \geq j \geq 0} \frac{6(2j+1)!(6n+1)!(2n+j+1)!}{j!^2(3n)!(4n+2j+3)!(n-j)!(n+1)} y^j t^{2n}.$$

(Group of order 6, zero orbit sum)

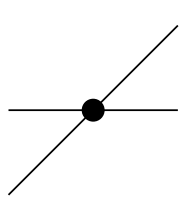
- For the reverse model $\bar{\mathcal{S}} = \{11, 10, \bar{1}1, \bar{1}0, \bar{1}0, \bar{1}\bar{1}\}$ (with a West repeated step), the series $Q(x, y; t)$ is D-finite.

In both cases, we only have computer algebra proofs
(in the spirit of [Bostan & Kauers 10])

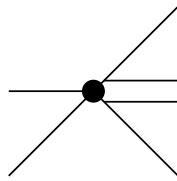


Questions

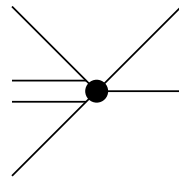
- Explore the 19 three-dimensional models with zero orbit sum that are not Hadamard: are they D-finite?
- Find bare hands proofs for



Gessel



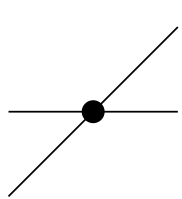
algebraic



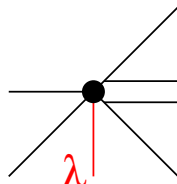
D-finite

Questions

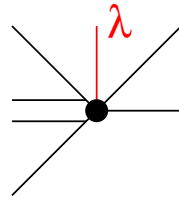
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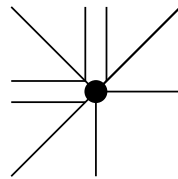
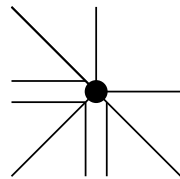
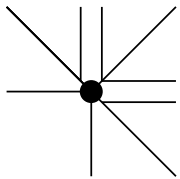
algebraic



D-finite

[Kauers, Yatchak 14(a)]

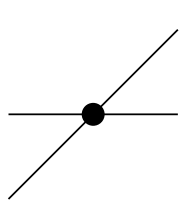
- Find any proof for the (conjecturally algebraic) models
[Kauers, Yatchak 14(a)]



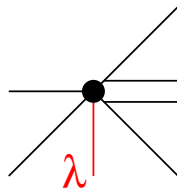
Questions

- Explore the 19 three-dimensional models with zero orbit sum that are not Hadamard: are they D-finite?

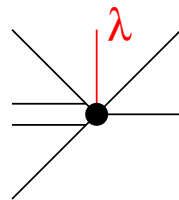
- Find bare hands proofs for



Gessel



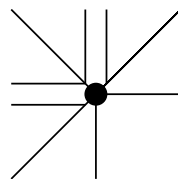
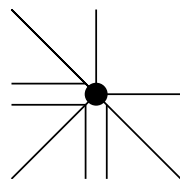
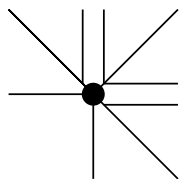
algebraic



D-finite

[Kauers, Yatchak 14(a)]

- Find any proof for the (conjecturally algebraic) models
[Kauers, Yatchak 14(a)]



- larger steps, arbitrary dimensions...