

Laboratoire Bordeaux de Recherche en Informatique

# Distributed algorithms in a (highly) dynamic context

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LaBRI, Université Bordeaux 1

Ref: 0001/02012-jan-08 12:53:01 (s. Chaumette) - keynote-workshop-2010

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# Based on

**Secured fleets of P2P mobile and autonomous communicating systems**

Serge Chaumette  
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Mobility, Ubiquity, Security (Mus) research sub-group of the Languages, Systems and Networks (LSR) research group of

LaBRI UMR CNRS 5800  
 University of Bordeaux  
 FRANCE

 The 2010 World Congress in Computer Sciences, Computer Engineering and Applied Computing  
 invited keynote talk at WorldComp 2010

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# Outline

- Secured fleets of autonomous communicating mobile terminals
- Dynamic graphs and (secured) fleets of autonomous communicating mobile terminals
- The relationship of hardware design and security
- Example applications

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# Secured fleets of autonomous communicating mobile terminals



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Ref: 0001@2012-Jan-05@12:55@131-1-From:ef-kyocera-workshop-2010

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## Outline

- Context
- Current approaches
- Real life
- Our approach, our target platforms

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## Goals and research topics of the Muse research group at LaBRI

Contribute to the definition and development of supporting middleware, tools and mechanisms formally validated that make it possible to take advantage of the resources (static or mobile) connected to the network (wired or wireless) and to develop applications on top of these resources.

### Target systems

→ Secured fleets of autonomous communicating mobile terminals ←

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## We target real world networks



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## Nodes can move/appear/disappear

Ref. 000102012-jan-08 12:58:11 J. Fromeef. keynote-workshop-2010

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## The network can become disconnected

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## Summary of context and consequences

- (really) mobile Ad-hoc Networks (MANets)
  - beyond Delay/Disruptive Tolerant Networks (DTN)
- High instability
  - Very limited neighbourhood relationship
    - No communication guarantee
    - Routing is not a solution
    - Brute flooding is not a sufficient solution
- Users are most of the time not known in advance
  - Unsecure boundaries

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## Outline

- Context
- Current approaches
- Real life
- Our approach, our target platforms
- Associated models
- Example applications

Ref: 000102012-jan08-02-5581-1-1-1-promet-4-kyocera-workshop-2010

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## Current approaches

Applications have a **global** vision/knowledge

middleware



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## Current approaches

- Their goal is to hide the underlying network aspect by providing (or trying to provide):
  - Routing
  - Synchronization (or guaranteed) communications

STOP TALKING ABOUT ROUTING!!!!!!!!!!!!
   
 (in this precise context)

Ref: 000102012-jan08-02-5581-1-1-1-promet-4-kyocera-workshop-2010

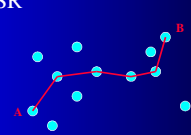
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[ Current approaches: their limitations ]

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## The routing based approach

- Proactive
  - OLSR, DSDV
- Reactive
  - AODV, TORA, DSR



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## Basic assumption

- At any time a route can be established between two mobile units of the network, i.e. the network is connected and virtually stable
- → classical applications can be used
- → classical security techniques can be used ex.: Certification Authority (the problem of keys distribution remains)

Ref: 000102012-jan-06@13:58:13.1.1 from:ef-keysec-workshop-2010

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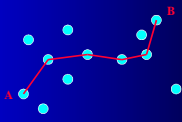
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[ Real life ]

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## In the real life ...

- Example:
  - Network of cars
  - Students on a campus
  - Tactical military networks
  - Crisis management
  - Home networking
  - ...



Ref: 000102012-jan-06@13:58:13.1.1 from:ef-keysec-workshop-2010

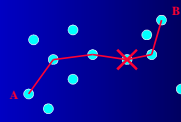
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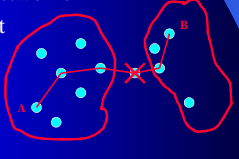
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[ Real life ]

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## In the real life ...

- Example:
  - Network of cars
  - Students on a campus
  - Tactical military networks
  - Crisis management
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  - ...



More and more realistic!

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## The nature of the network changes

- ➔ The nature of applications changes
  - group/community based, dynamic, ...
  - ➔ *the Internet of Things*
- ➔ The management of security changes

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## Paradigm shift for applications



How many people are there ?



Are there many people ?  
(or approximate number)

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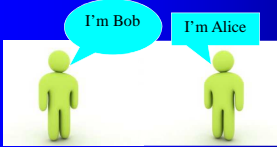
## Impact on applications

- The objectives must be lowered because of high instability
- Examples:
  - counting → lower bound
  - covering tree → covering forest
- But .. this is real life ☺

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## Paradigm shift for security



Share keys, authenticate

Recognize

- individually
- group/topic based



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## Impact on security

- The objectives must be lowered because of unsecure boudaries
- Examples:
  - Entity based keyes → group/topic based keyes
  - authenticate → recognize
- But once again ... this is real life ☺

Ref: 000102012-jan-06@13:58@13.1, From: efi-keynote-workshop-2010  
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## Outline

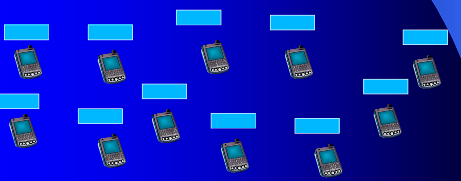
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[ Our approach ]

Our approach

The middleware is never seen as something global  
→ the applications interact locally



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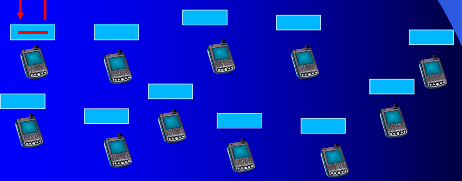
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[ Our approach ]

Applications management  
Local – local primitives

Local impact  
Local computation  
Examples: one way communication



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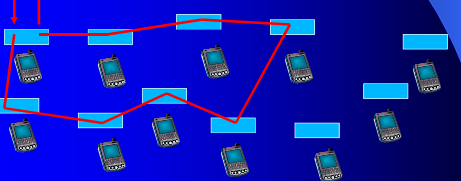
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Applications management  
Local – remote primitives

Local impact  
Distributed/remote computation  
Examples: *haveBeenHeard* trigger  
*notAlone* trigger  
*information hiding*



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Security management

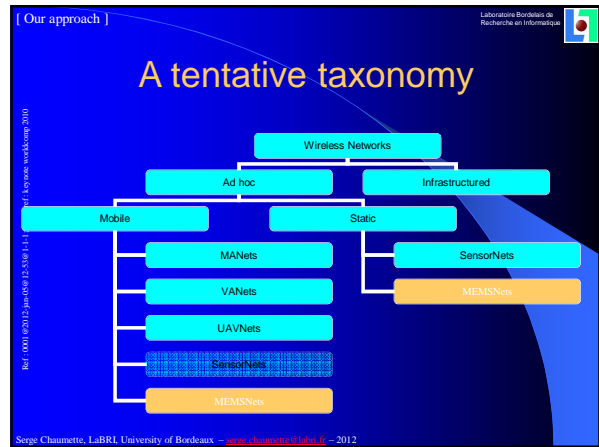
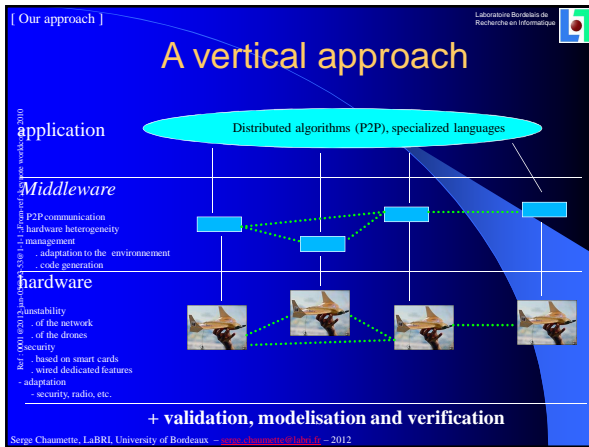


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## Our target systems

Secured fleets of autonomous communicating mobile terminals

- Fleets of mobile phones
  - 100 Android phones
- Fleets of robots
  - 10 prototypes being built → fleet of 200
- Fleets of UAVs
  - Fly-n-Sense + DGA (French army)

Ref: 00010/2012-jan-06@13:53@13.1 - From: s.f. luyon@cs.uibm.ac.uk - 2012



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## Underlying constraints

- Behavior of the fleet members
  - unpredictable mobility
  - unpredictable volatility
- Possible controls of the fleet members
  - none

Ref: 0001102012-jan-08 12:55:01 [L. Thomé] / kypocoworkshop/2010


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## Fleet of robots

- This work is being carried out with Olivier Ly and Hugo Gimbert
  - Mobility
  - XBee Communication
  - Localization (?)
  - Infra-red targeting (?)



Ref: 0001102012-jan-08 12:55:01 [L. Thomé] / kypocoworkshop/2010

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## Underlying constraints

- Behavior of the fleet members
  - partially predictable mobility
  - unpredictable volatility
- Possible controls of the fleet members
  - partial mobility control

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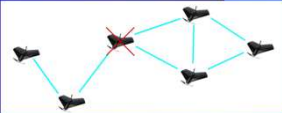
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## Fleet of UAVs

- Collaboration
  - Fly-n-Sens, IMS, ENAC
    - SYMM project labeled by the world competitiveness cluster Aerospace Valley
  - DGA (french Army)



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## Underlying constraints

- Behavior of the fleet members
  - partially predictable mobility
  - unpredictable volatility
- Possible control of the fleet members
  - (almost) total mobility control

Ref. 000102012-jur-008-12-508-1-1-1-From-ef-kyose-workshop-2010

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Scancopter CB 750



FNS 900 SEEKER  
with ground station

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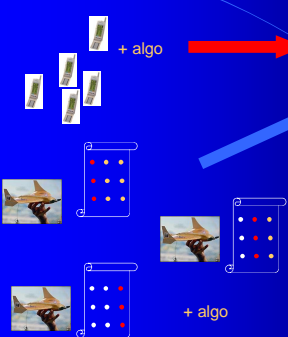


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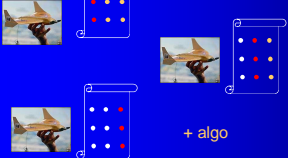
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+ algo

application is valid =  
f(structure of the underlying  
mobility graph)



+ algo

control/modification  
of the mobility graph by  
local but possibly  
collective decisions

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Ref: 00010-2012-jan-08 12:53:01 [J. Bourgeois, A. Rasse, workcomp, 2010]

application is valid =  $f(\text{structure of the underlying mobility graph})$

control/modification of the mobility graph by local but possibly collective decisions

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## Underlying constraints

- Behavior of the fleet members
  - Mobilité contrainte
  - Volatilité incontrôlée
- Control
  - Partial (see VANets)

Ref: 00010-2012-jan-08 12:53:01 [J. Bourgeois, A. Rasse, workcomp, 2010]

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## Fleet of MEMS

Micro-Electro-Mechanical Systems

Image courtesy of Sandia National Laboratories, SUMMIT(TM) Technologies, [www.mems.sandia.gov](http://www.mems.sandia.gov)

Ref: 00010-2012-jan-08 12:53:01 [J. Bourgeois, A. Rasse, workcomp, 2010]

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## Fleet of MEMS

- Programmable Matter is a project of Carnegie Mellon University and Intel
- This work on fleets of MEMS is just starting with Julien Bourgeois, LIFC, University of Franche-Comté

Credit: J. Bourgeois, E. Dedu, A. Rasse, University of Franche-Comté

Ref: 00010-2012-jan-08 12:53:01 [J. Bourgeois, A. Rasse, workcomp, 2010]

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## Main problems


Volatility (unstability)

- of terminals
- of the network

Security is a major problem

**Redesign of algorithms**  
(no routing, no global knowledge, disconnected network, etc.)

**Using Smart Cards**



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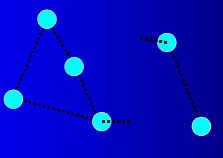
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## Dynamic graphs and (secured) fleets of autonomous communicating mobile terminals



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
[ Approach ]

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## Approach

- Local computation

graph relabeling



- (other approach: CCS/CBP (Milner, Prasad) like models - work in progress -)

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[ Graph relabeling ]

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## Graph relabeling

- Static graphs → [Sirocco-2008-2,2](#)
- Dynamic, évolutive graphs → [Sirocco-2008-1,23,7](#)
- The dynamic aspect must be taken into account by the applications
  - Example of the spanning forest → [PhD-AC-2007-1,4,4](#)

Ref.: 00011@2012-Jan-08@13:58@14.1.From:ref.:kyosee-workshop-2010


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[ Relabeling over graphs ]

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## Relabeling over graphs

- Static graphs
  - see [Litovsky, Metivier, Sopena 1999]



- extension to dynamic graphs
  - see [Casteigts, Chaumette, Ferreira 2009]

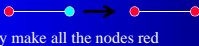
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[ Relabeling over static graphs ]

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## Relabeling over static graphs

- Local computation in static graphs
  - A node can only interact with a direct neighbor
  - Nodes/communication links are static
- Example :
  - the rule  will eventually make all the nodes red
  - More complex example: an algorithm that creates a spanning tree

→ I. Litovsky, Y. Metivier, and E. Sopena. Graph relabelling systems and distributed algorithms. In World Scientific Publishing, editor, Handbook of graph grammars and computing by graph transformation, volume III, Eds.

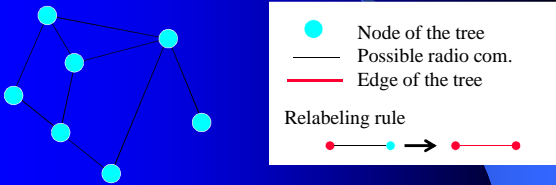
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[ Relabeling over static graphs / the spanning tree example ]

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## The spanning tree example



● Node of the tree  
--- Possible radio com.  
— Edge of the tree

**Relabeling rule**  


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[ Relabeling over static graphs / the spanning tree example ]

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● Node of the tree  
— Possible radio com.  
— Edge of the tree

Relabeling rule

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- Possible radio com.
- Edge of the tree

Relabeling rule

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## The spanning tree example

- Node of the tree
- Possible radio com.
- Edge of the tree

Relabeling rule

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## The spanning tree example

● Node of the tree  
— Possible radio com.  
— Edge of the tree

Relabeling rule

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[ Relabeling over static graphs ]

Relabeling over static graphs

Set of all possible static graphs

Set of all static graphs for which the algo. works

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[ Relabeling over dynamic graphs ]

Relabeling over dynamic graphs

- Relabeling rules as for static graphs
- Management of appearing vertices
- Management of disappearing vertices

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[ Relabeling over dynamic graphs ]

Model

- Local computation in dynamic graphs
  - A node can only interact with a direct neighbor
  - Nodes/com links can appear/disappear at any time
- Example :
  - the rule will not necessarily make all the nodes red

More complex example: an algorithm that maintains a spanning forest with nodes arriving and leaving at any time and with unstable communication links

→ Amal Kulkarni, Serge Chaumette, Afonso Ferreira:  
 Characterizing Topological Assumptions of Distributed Algorithms in Dynamic Networks.  
 SIROCCO 2009: 126-140  
<http://hal.archives-ouvertes.fr/docs/00/37/67/01/PDF/RR-1457-09.pdf>

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[ Relabeling over dynamic graphs / The spanning forest example ]

The spanning forest example

- Node of one of the trees
- Token
- Possible radio com.
- Edge of one of the trees

→ At any time each node is inside one and only one tree (that also has one and only one token)

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## Local computation (P2P) rules

Token circulation

Merging of two trees

Token management when a tree is split (a token is regenerated on the side where there is no token - not detailed here -)

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(1) Each token randomly circulates its tree

Rule:

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(2) Each token randomly circulates its tree

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(3) Each token randomly circulates its tree

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(4) One of the nodes moves ...

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(5) ... and communication with another tree becomes possible

Ref: 0001@2012-Jan-08@12:53@1-1-1-Dromed-4-qyoc-worhkomg-2010

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(6) Each token randomly circulates its tree

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(7) When two nodes that can communicate each have a token then ...

Rule:


Ref: 0001@2012-Jan-08@12:53@1-1-1-Dromed-4-qyoc-worhkomg-2010

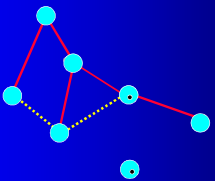
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(8) ... the trees are merged and one of the tokens is discarded

Rule: 




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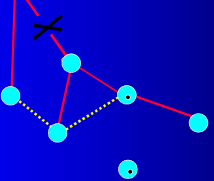
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(9) When one of the nodes moves and a connection is broken inside a tree ...

Rule: 




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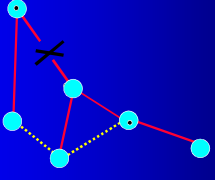
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(10) ... a new token is regenerated in the tree that has lost it

Rule: 



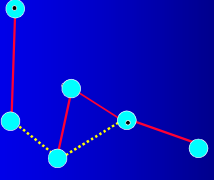
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→ At any time each node is inside one and only one tree (that also has one and only one token)



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## Evolving graphs

Formalism to represent dynamic topology

**Evolving graphs [Ferreira 2004]**

|                                  |                                  |                                  |                                  |
|----------------------------------|----------------------------------|----------------------------------|----------------------------------|
| period $t_0 \rightarrow t_1$<br> | period $t_1 \rightarrow t_2$<br> | period $t_2 \rightarrow t_3$<br> | period $t_3 \rightarrow t_4$<br> |
| $G_0$                            | $G_1$                            | $G_2$                            | $G_3$                            |

$S_T = t_0, t_1, t_2, t_3, t_4$   
 $S_G = G_0, G_1, G_2, G_3$   
 $G = \bigcup_{G \in S_G} G$

$\mathcal{G} = (G, S_G, S_T)$   
 is the corresponding *Evolving Graph*.

↓ graphical representation ↓

A. Casteigts, S. Chaumette, A. Ferreira  
Characterizing Topological Assumptions of Dist. Algo. in Dynamic Networks  
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## DAGRS over evolving graphs

Combination

**Relabellings over Evolving Graphs**

An execution is an alternated sequence of relabellings and topological events:  
 $X = R_{A_{[t_{last-1}, t_{last}]}} \circ Event_{t_{last-1}} \circ \dots \circ Event_{t_1} \circ R_{A_{[t_1, t_2]}} \circ \dots \circ Event_{t_0} \circ R_{A_{[t_0, t_1]}}(G_0)$

We note  $\mathcal{X}_{A/G}$  the set of all possible execution sequences of an algorithm  $A$  over an evolving graph  $\mathcal{G}$ .

Topology-related necessary condition:  $\neg CN(\mathcal{G}) \implies \nexists X \in \mathcal{X}_{A/G} \mid \text{success.}$   
Topology-related sufficient condition:  $C_S(\mathcal{G}) \implies \forall X \in \mathcal{X}_{A/G} \mid \text{success.}$

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## DAGRS over evolving graphs


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## Fleet of mobile phone

- The mobility is not known in advance
- The volatility is not known in advance
- There is no control over mobility

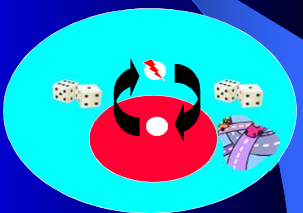
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## Fleet of robots (or cars)


- The mobility is not known in advance
- The volatility is not known in advance
- There is some control over mobility



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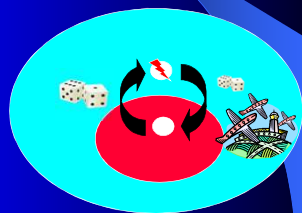
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## Fleet of UAVs

- The mobility is not known in advance
- The volatility is not known in advance
- There is (almost) full control over mobility



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## CCS-bx [ work in progress ]

- Synchronous communication
- Asynchronous communication
- Message loss
- Delayed reception when broadcasting
- Mobility of nodes and messages

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## Outline

- Secured fleets of autonomous communicating mobile terminals
- Dynamic graphs and (secured) fleets of autonomous communicating mobile terminals
- The relationship of hardware design and security
- Example applications

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## The relationship of hardware design and security



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## Outline

- Identities
- Components interconnections
- Add-ons

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[ How hardware support can help / Identities ]

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## Identities

- Identities (even if not available at user level) are usefull to solve some effective problems:
  - election
  - routing
  - ...



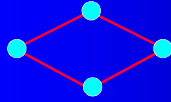
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[ How hardware support can help / Identities ]

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## Why they cannot be generated



There is no way to make any difference between any two nodes.

Any algorithm will be executed the same way and will thus produce exactly the same values on each node

Ref: 0001@2012-Jan-08@12:55@12-1-1-From:ref-keynote-workshop-2010

Serge Chaumette, LaBRI, University of Bordeaux - [www.laforge.fr/laforge](http://www.laforge.fr/laforge) - 2012

[ How hardware support can help / Identities ]

« The » reference paper

Dana Angluin  
*Local and global properties in networks of processors*  
 (Extended Abstract)  
 Proceedings of the twelfth annual ACM symposium on Theory of computing, p.82-93, April 28-30, 1980, Los Angeles, California, United States

Ref: 00010@2012-jan-08 12:53:01 [L. J. Fromard - keynote-workshop-2010]

Serge Chaumette, LaBRI, University of Bordeaux – [www.labri.fr/perso/chaumette](http://www.labri.fr/perso/chaumette) – 2012

[ How hardware support can help / Identities ]

Hardware approaches

- Crypto based approach
  - Based on RNGs
    - are TRNGS really available in mobile devices?
    - probabilistic result
- TPM based
  - Additional cost (hard)
  - Expensive to secure (personalization)
  - How to link it to the rest of the hardware ?
- Physical Unclonable Function based (see '*project proposal*' later) as a solution ?

Ref: 00010@2012-jan-08 12:53:01 [L. J. Fromard - keynote-workshop-2010]

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[ How hardware support can help / Components interconnections ]

Components interconnections



Ref: 00010@2012-jan-08 12:53:01 [L. J. Fromard - keynote-workshop-2010]

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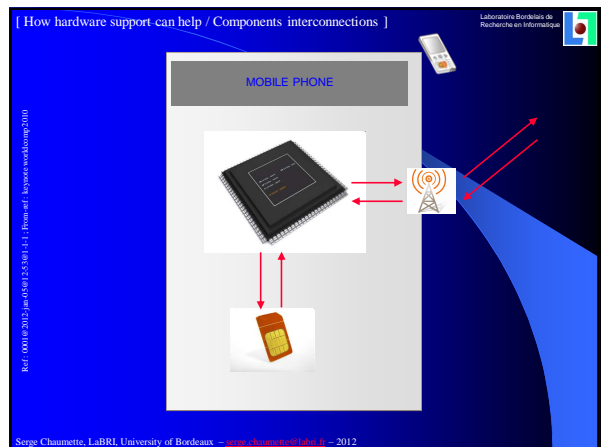
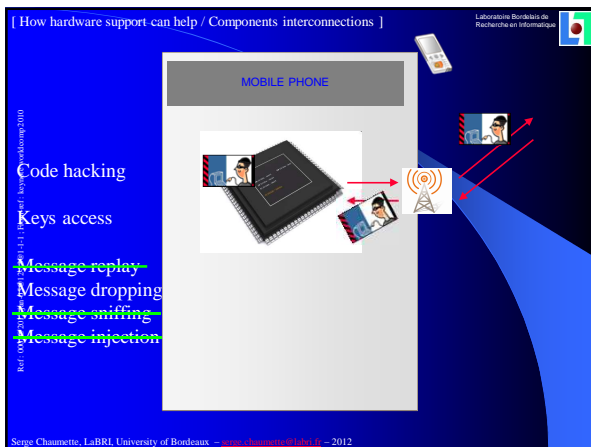
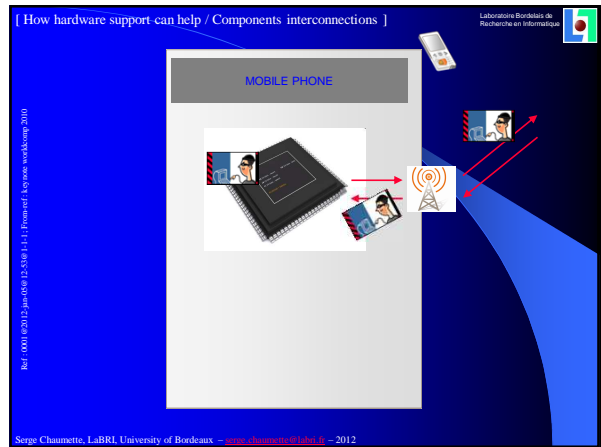
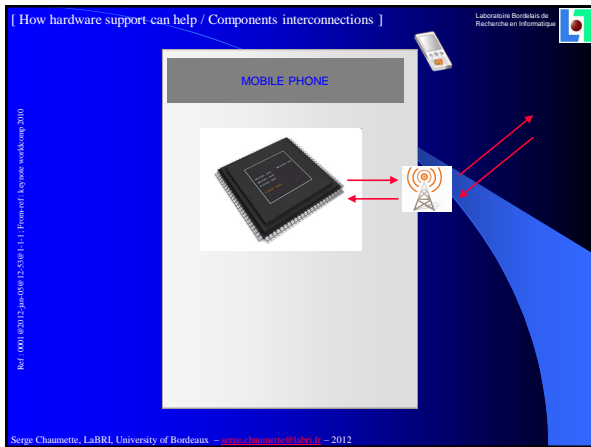
[ How hardware support can help / Components interconnections ]

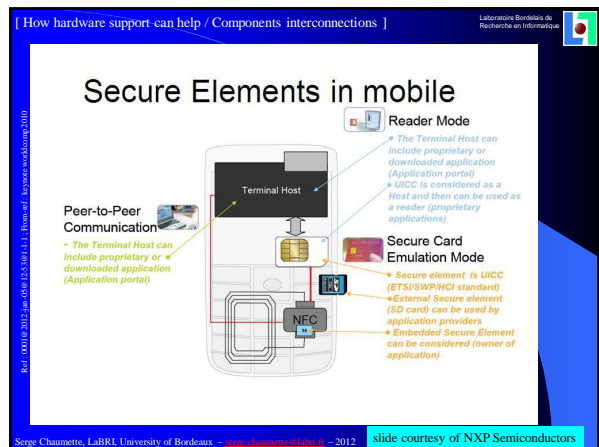
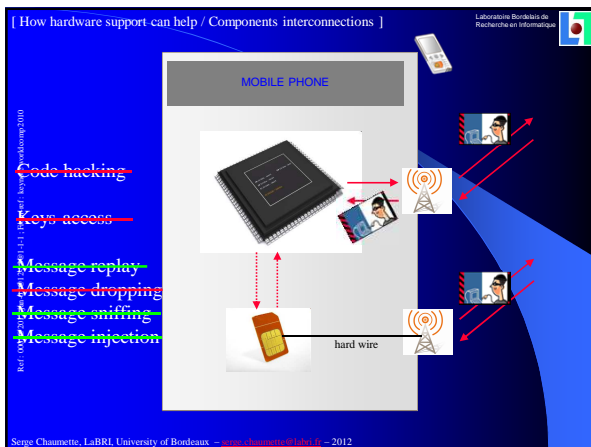
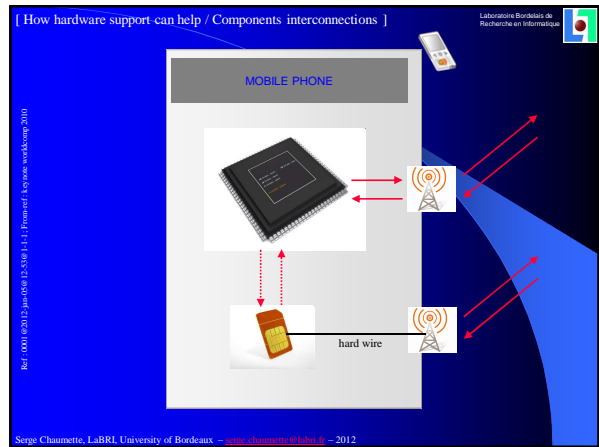
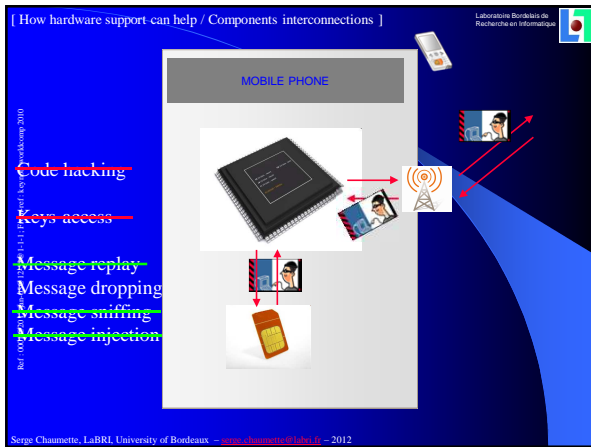
From an application perspective

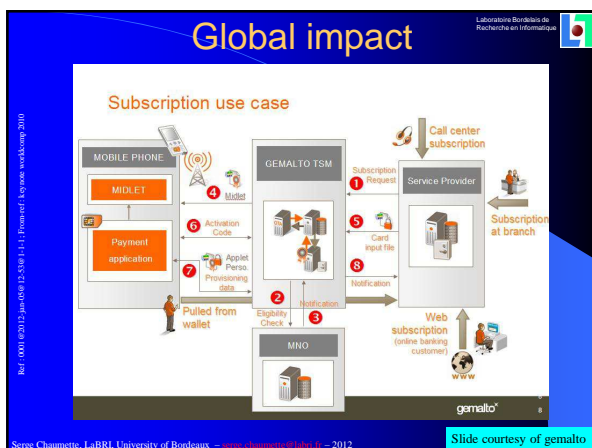
- Non functional properties
  - Secure the application itself
  - Secure secret/public keys
- Functional properties
  - What is the best you can do to send a message ?
  - What is the best you can do to properly handle an incoming message ?

Ref: 00010@2012-jan-08 12:53:01 [L. J. Fromard - keynote-workshop-2010]

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[ How hardware support can help / add-ons ]

### Add-ons

The case of NFC technology

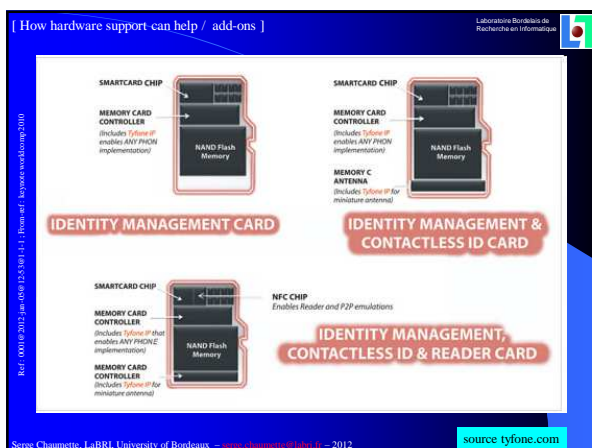
- Phones hardly available (Nokia from 2011)
- Extra cost for (yet) little usage opportunities
- Responsibility of manufacturers for embedding untested (on a large scale) technology

→ add-ons provide an on demand solution

Ref: 00011@2012-jan-08 13:58:11 | J. Fromard | keynote-workshop-2010

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[ How hardware support can help / add-ons ]

Ref: 00011@2012-jan-08 13:58:11 | J. Fromard | keynote-workshop-2010

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source: www.icarte.ca

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## Outline

- Secured fleets of autonomous communicating mobile terminals
- Dynamic graphs and (secured) fleets of autonomous communicating mobile terminals
- Example applications

Ref: 00018 (2012) Jan 08 12:53:01 [L1] From: s-f. l@univ-bordeaux.fr [mailto:s-f. l@univ-bordeaux.fr] - 2012

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[ Example applications ]

## Example applications (based on collaborations)

- With the industry
  - Gemalto, Thales, NXP, Oberthur, Orange, G&D
  - Verisign
  - Intelligere
  - Fly-n-Sense
  - ...
- With governmental bodies
  - Ville de Caen
  - Pôle de compétitivité Aerospace Valley (AESE)
  - Région Aquitaine
  - DGA
  - ...
- With Universities
  - Université de Caen ; Laboratoires LITIS, XLIM, Valoria
  - ENAC
  - ...

Ref: 00018 (2012) Jan 08 12:53:01 [L1] From: s-f. l@univ-bordeaux.fr [mailto:s-f. l@univ-bordeaux.fr] - 2012

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[ Example applications ]

## Strategic map sharing



Map sharing (DGA)  
[ IEEE milcom ]

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[ Example applications ]

## Museum Quest

- European project (ITEA2)
  - Smart Urban Spaces
  - <http://www.smarturbanspaces.org/>
- 25 partners, 4 countries
  - Gemalto, Thales, NXP, ...
  - VTT, LaBRI, University of Caen
  - Valence, Bordeaux, Bilbao, ...



Ref: 00018 (2012) Jan 08 12:53:01 [L1] From: s-f. l@univ-bordeaux.fr [mailto:s-f. l@univ-bordeaux.fr] - 2012

Serge Chaumette, LaBRI, University of Bordeaux - [www.la-bri.fr/~serge](http://www.la-bri.fr/~serge) - 2012

[ Example applications ]

Ref: 0001102012-jur-008-02-508-1-1-1-Dromed-1-kyosee-workshop-2010

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Alice  
Carol  
Bob

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[ Example applications ]

### Anonymously counting people in a demonstration

Ref: 0001102012-jur-008-02-508-1-1-1-Dromed-1-kyosee-workshop-2010

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- Goals
  - Count a lower bound
  - People have to remain anonymous
  - Observer (Police ?) should not be able to determine if someone was at the demonstration or not
- This relies on secure hardware and proper components interconnections

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### Questions ?

Ref: 0001102012-jur-008-02-508-1-1-1-Dromed-1-kyosee-workshop-2010

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Le monde de la téléphonie mobile

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