Bounding clique-width by means of split-decompositions, for directed and undirected graphs

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Graph decompositions are useful for FPT algorithms and graph structure theory.

Among the many notions we have

tree-decompositions  $\rightarrow$  parameter tree-width (twd(G)) clique-width decompositions  $\rightarrow$  param. clique-width (cwd(G)) modular decomposition (Gallai, 1967) split decomposition (Cunningham, 1981) Computations

NP-complete for tree-width and clique-width,

Good approximation algorithms for tree-width,

Linear time algorithms for modular and split decompositions (Gioan, Habib, Paul *et al.*).

Some algorithmic uses

Clique-width decompositions are useful for checking MSO properties.

Also for MSO2 properties (MSO using edge set quantification) because MSO2 = MSO on incidence graph Inc(G) and :  $cwd(Inc(G)) \leq twd(G) + 3$  for undirected graph G  $cwd(Inc(G)) \leq 2 \cdot twd(G) + 4$  for directed graph G

Tree-width must be bounded for MSO2 model-checking by XP algorithms (Kreutzer, 2010; exact statement is very technical)

How to obtain clique-width decompositions ?

For Inc(G) : from a tree-decomposition of G

For G : from a tree-decomposition of G if G is sparse in the following senses :

degree  $\leq$  d : cwd(G)  $\leq$  d. (twd(G)+1) + 2

planar : cwd(G) < 6. twd(G)

p-planar, cwd(G) < 6. twd(G). (2p+1)

in general, cwd(G) is not polynomially bounded in twd(G),

for G, directed or not.

From the modular decomposition because cwd(G) is the maximum cwd(H) where H is a component of the modular decomposition.

Computing the modular decomposition may be a preliminary step for the computation of a clique-width decomposition.

We will consider in a similar way the split-decomposition (Cunningham, 1981), for directed and undirected graphs.

Modular decomposition, also called substitution decomposition

is based on the following notion of substitution of H for a vertex in K (undirected graphs) :

 $G=K[x \leftarrow H]$ 

where H replaces x in K and all vertices of H are made adjacent to the neighbours of x.

The corresponding decomposing step expresses G as  $K[x \leftarrow H]$  if possible, and decomposes similarly K and H etc.

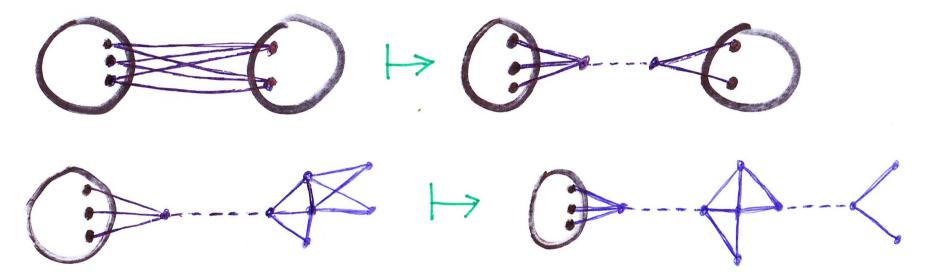
One obtains a tree that can be seen as an algebraic term defining the given graph, whose operations are substitutions in « prime » graphs, those that cannot be decomposed. That such a tree is unique in a certain sense is not important for our purposes. Clique-width fits well with modular decomposition, because from terms with < k labels defining K and H, one gets, by a substitution of terms (and a relabelling) a term with < k labels that defines K[x  $\leftarrow$  H].

Cographs have simple modular decompositions, from which we get the bound 2 for their clique-width.

Modular decomposition also works for directed graphs.

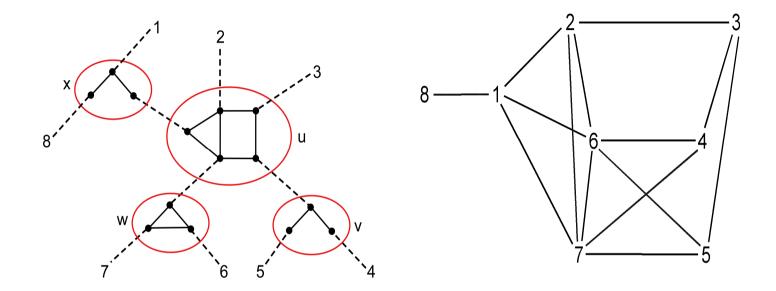
Split decomposition for undirected graphs

The basic decomposition can be iterated.



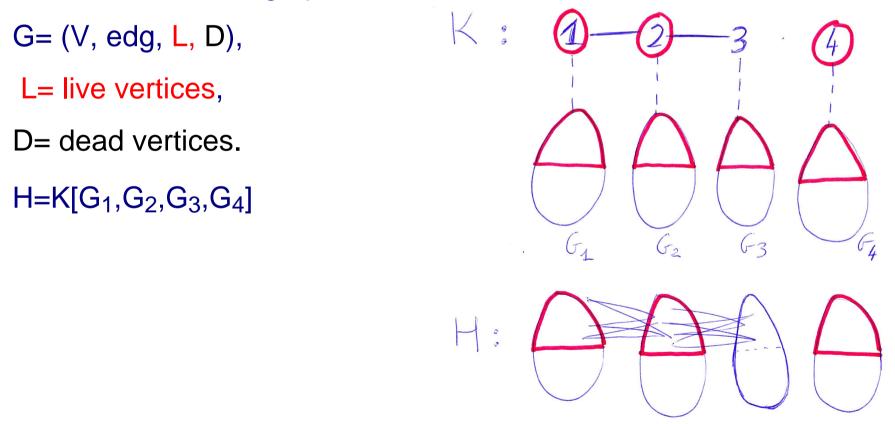
We obtain an unrooted tree (the tree of modular decomposition is a term, hence a rooted tree), called a *graph-labelled tree* (Gioan, Paul 2012). By some restrictions to decomposing steps, one obtains a unique tree, hence a canonical decomposition.

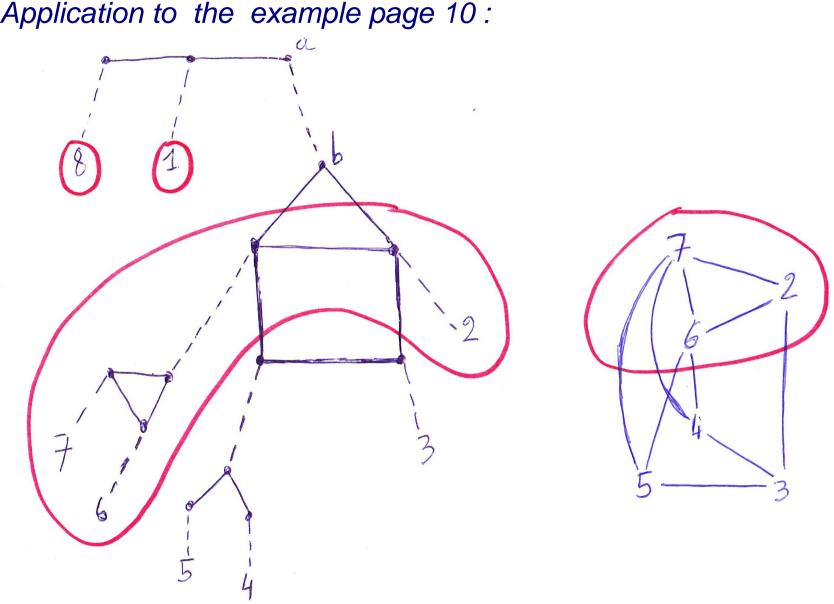
## Example of a graph labelled tree and the associated graph :



Leaves  $\rightarrow$  vertices ; alternating paths  $\rightarrow$  edges : between 1 and 8, 1 and 2, 2 and 3, etc. None between 1 and 3, 1 and 4, etc. Objectives : Graph labelled tree  $\rightarrow$  rooted graph labelled tree  $\rightarrow$  term over appropriate substitutions  $\rightarrow$  bound on clique-width.

Substitution for graphs with dead vertices.





Application to the example page 10 :

## Distance hereditary graphs :

*Definition :* The distance in any connected induced subgraph is the same as in the considered graph.

Characterization : The GØH ----components of a split decomposition are stars and cliques. We need GOH = only K<sub>3</sub> and S<sub>3</sub> T that yield the operations  $\otimes$  ,  $\oplus$  and  $\Lambda$  :  $\Lambda(G,H) =$ 

Distance hereditary graphs are defined by the grammar :

G ::=  $* \mid G \otimes G \mid G \oplus G \mid \Lambda(G,G)$ 

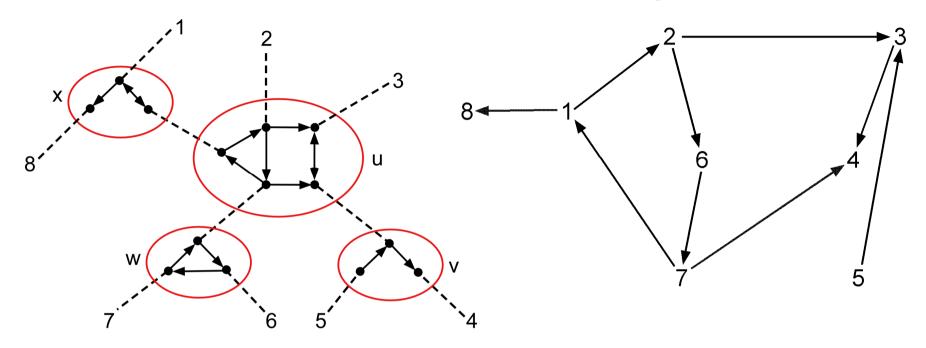
where **\*** is an isolated live vertex.

A similar grammar using substitution operations, say K[.,.,.], is obtained for the class of graphs defined by graph-labelled trees whose components are cliques, stars and finitely many graphs K.

*Theorem :* (1) If G is defined by a graph-labelled tree whose components are cliques, stars and graphs K of  $cwd(K) \leq m$ , then  $cwd(G) \leq 2m + 1$ .

(2) If in addition, K has degree  $\leq d < m$ , then  $cwd(G) \leq m + d + 1$ .

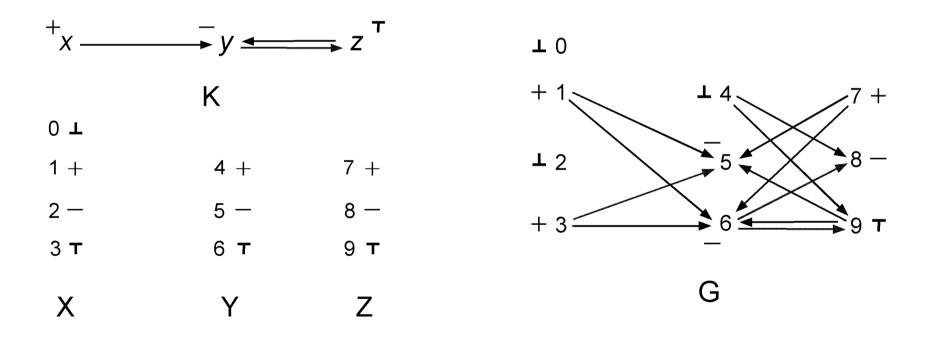
## Graph-labelled trees for directed graphs



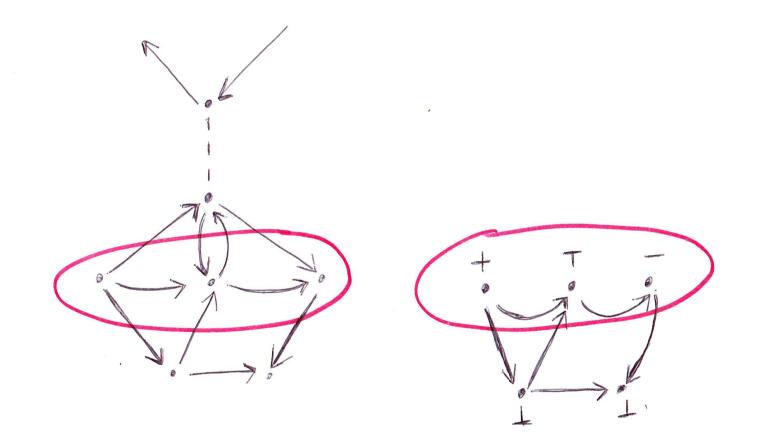
Directed edges are defined from *directed* alternating paths.

*Theorem :* If G is defined by a *directed* graph-labelled tree whose components have clique-width  $\leq$  m, then cwd(G)  $\leq$  8.m +1.

The live vertices are of 3 types : T, + and -; edges are directed +  $\rightarrow$  - and T means + or -. Dead vertices are labelled by  $\perp$ . Substitution : G = K[x  $\leftarrow$  X, y  $\leftarrow$  Y, z  $\leftarrow$  Z].



Why these 3 labels?



## Conclusion

Modified notions of substitution.

Split decompositions for undirected or directed graphs (not necessarily strongly connected) expressed by terms over substitution operations.

Good bounds on clique-width (from the clique-widths of components).

Graph grammars. If unambiguous, they can be used for counting or random generation (cf. Chauve, Fusy, Lumbroso for distance hereditary graphs)