

Monadic second-order logic for graphs. Algorithmic and language theoretical applications

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 Reference :
 Graph structure and monadic second-order logic,

 book to be published by Cambridge University Press, readable on :

 http://www.labri.fr/perso/courcell/ActSci.html

History : Confluence of 4 independent research directions, now intimately related :

- 1. Fixed-Parameter Tractable algorithms for parameters reflecting hierarchical structurings : tree-width, clique-width. This research started with case studies for series-parallel graphs, cographs, partial k-trees.
- 2. <u>Extension to graphs of the main concepts of Formal Language Theory</u>: grammars, recognizability, transductions, decidability questions
- 3. Excluded minors and related notions of forbidden configurations (matroid minors, « vertex-minors »).
- 4. Decidability of Monadic Second-Order logic on classes of finite graphs.

Two ways of considering graphs

 A graph (finite, up to isomorphism) is an algebraic object, an element of an algebra of graphs (Similar to words, elements of monoids)

2) A graph is a *logical structure*;
 graph properties can be expressed by logical formulas
 (FO = first-order, MS = monadic second-order, SO = second-order)

Consequences:

- a) Language Theory concepts extend to graphs
- b) Algorithmic meta-theorems

An overview chart



Key concepts of Language Theory and their extensions

Languages	Graphs	
Algebraic structure :	Algebras based on graph operations : \oplus , \otimes , //	
monoid (X*,*,ε)	quantifier-free definable operations Algebras : HR, VR	
Context-free languages :	Equational sets of the	
Equational subsets of (X*,*,ε)	algebras HR, VR	
Regular languages :	Recognizable sets of the algebras HR, VR	
Finite automata ≡		
Finite congruences \equiv	defined by finite congruences	
Regular expressions \equiv		
\equiv Monadic Second-order	\cup	
definable sets of words or terms	Monadic Second-order definable sets of graphs	
Rational and other types of transductions	Monadic Second-order transductions	

Summary

- 1. Context-free sets defined by equation systems
- 2. Two graph algebras; tree-width and clique-width.
- 3. Recognizability : an algebraic notion.
- 4. Monadic second-order sentences define recognizable sets.
- 5. Fixed-parameter tractable algorithms : constructions of automata
- 6. Monadic second-order transductions.
- 7. Robustness results : preservation of classes under direct and inverse monadic second-order transductions. Short proofs in graph theory. (black= graph theory)
- 8. Logic and graph structure theory : Comparing encoding powers of graph classes *via* monadic second-order transductions
- 9. Graph classes on which monadic second-order logic is decidable10.Open questions

1. Equational sets (generalization of context-free languages)

Equation systems = Context-Free (Graph) Grammars in an algebraic setting

In the case of words, the set of context-free rules $X \rightarrow a X Y$; $X \rightarrow b$; $Y \rightarrow c Y Y X$; $Y \rightarrow a$

is equivalent to the system of two equations:

X = a X Y	\cup	{ b }
Y = c Y Y X	\cup	{ a }

where X is the language generated by X (idem for Y and Y).

In arbitrary algebras (\rightarrow in graph algebras) we consider equation systems like:

$$X = f(k(X), Y) \cup \{b\}$$

Y = f(Y, f(g(Y), m(X))) \cup \{a\}

where :

- f is a binary operation,
- g, k, m are unary operations on graphs,
- a, b denote basic objects (graphs up to isomorphism).

An *equational set* is a component of the least solution of such an equation system. This is well-defined in any algebra.

The general algebraic setting

F: a finite set of operation symbols with (fixed) arities, called a signature

 $M = \langle M, (f_M)_{f \in F} \rangle$: an F-algebra.

 $P(\mathbf{M})$ its power-set algebra with domain $P(\mathbf{M})$ and operations extended to sets : $f_{P(\mathbf{M})}(\mathbf{A},\mathbf{B}) = \{ f_{\mathbf{M}}(\mathbf{a},\mathbf{b}) / \mathbf{a} \in \mathbf{A}, \mathbf{b} \in \mathbf{B} \}.$

Equation systems of the general form :

$$S = \langle X_1 = p_1, ..., X_n = p_n \rangle$$

 $X_1,...,X_n$ are unknowns (ranging over sets)

p₁,...,p_n are polynomials for example :

 $f(k(X_1),X_2) \cup f(X_2, f(g(X_3), X_1))) \cup c$

Its solutions are the fixed-points of the (recursive) equation :

$$X = S_{P(M)}(X)$$
 (1) where $X = (X_1,...,X_n)$
 $S_{P(M)}(X) := (p_{1P(M)}(X),...,p_{nP(M)}(X))$

The set $P(M)^n$ ordered by component-wise inclusion is ω -complete, the mapping $S_{P(M)}$ is monotone and ω -continous, hence Equation (1) has a least solution defined by iteration :

 $\mu \mathbf{X}.S_{P(\mathbf{M})}(\mathbf{X}) = \mathbf{U}_{i \ge 0} S_{P(\mathbf{M})}(\mathbf{X})^{i}(\emptyset, ..., \emptyset) \quad (\text{increasing sequence})$

An *equational set* of **M** is a component of μX . $S_{P(M)}(X)$ for some equation system S

Classical examplesAlgebraEquational sets\varepsilon, a,b,...,d>Context-free languages\varepsilon,
$$(\lambda u \in A^*.ua)_{a \in A}$$
Regular languagesT(F), terms over F, (*initial F-algebra*)Regular sets of termsk, +, $(0,...,0), ..., (0,...,1,0,...,0)$ Semi-linear sets =
finite unions of sets { $u + n_1.v_1 + ... + n_p.v_p | n_1,...,n_p \in \mathbf{N}$
for $u,v_1,...,v_p \in \mathbf{N}^k$

Properties of context-free languages valid at the algebraic level

- 1) If K and L are equational sets of M, so are $K \cup L$ and $f_{P(M)}(K,L)$.
- 2) The emptiness of an equational set is decidable *Proof*: A system S can be solved in *P*(T(F)) where T(F) is the
 F-algebra of terms over F.

"Transfer" of least fixed-points by homomorphisms :

If $h: \mathbf{M}' \rightarrow \mathbf{M}$ then $h(\mu \mathbf{X}.S_{P(\mathbf{M}')}(\mathbf{X})) = \mu \mathbf{X}.S_{P(\mathbf{M})}(\mathbf{X})$

Hence, $\mu X.S_{P(M)}(X) = \operatorname{val}_{M}(\mu X.S_{P(T(F))}(X))$ (val_M = value mapping : $T(F) \rightarrow M$)

Each component of $\mu X.S_{P(T(F))}(X)$ is a context-free language (terms are words written in Polish prefix notation). Emptiness can be checked.

3) If **M** is "effectively given" and the components of $\mu X.S_{P(M)}(X)$ are all finite sets, $\mu X.S_{P(M)}(X)$ can be computed (by straightforward iteration and by stopping as soon as $S_{P(M)}(X)^{i}(\emptyset,...) = S_{P(M)}(X)^{i+1}(\emptyset,...)$).

4) Finiteness test (with some natural "size" conditions).

5) For every context-free language L over k letters : a,...,d, the set of k-tuples $(|u|_a, ..., |u|_d)$ in **N**^k for all u in L is semi-linear (using transfer theorem for least fixed-points; "Parikh's Theorem").

Here : each function f has a *weight* w(f) in \mathbf{N}^{k} , the weight w(t) of a term t is the sum of weights of its symbols ; if L is equational w(L) is semi-linear.

2. The graph algebras HR and VR

We define two graph algebras \rightarrow Equational sets of graphs, two generalizations of context-free languages.

HR operations : Origin: Hyperedge Replacement hypergraph grammars associated graph complexity measure : tree-width

Graphs have distinguished vertices called *sources,* (or terminals or boundary vertices) pointed to by source labels from a finite set : {*a, b, c, ..., d*}.

Binary operation(s) : Parallel composition

G // H is the disjoint union of G and H and sources with same label are fused.



Unary operations :

Forget a source label

Forget_a(G) is G without a-source: the source is no longer distinguished; (it is made "internal").

Source renaming :

 $Ren_{a \leftarrow b}(G)$ exchanges source labels *a* and *b*

(replaces *a* by *b* if *b* is not the label of any source)

Nullary operations denote basic graphs : edge graphs, isolated vertices.

Terms over these operations *define* (or *denote*) graphs (with or without sources)

Example : Trees

Constructed with two source labels, r (root) and n (new root). Fusion of two trees at their roots : G G // H Н Extension of a tree by parallel composition with a new edge, forgetting the old root, making the "new root" as current root : $e = r \bullet$ • **n** $Ren_{n} \leftarrow r (Forget_{r} (G // e))$ G

Trees are defined by : $T = T // T \cup extension(T) \cup r$

Example: (Directed) series-parallel graphs

defined as directed graphs with sources 1 and 2, generated from $e = 1 \longrightarrow 2$ by the operations // (parallel-composition) and the series-composition defined from the basic operations by :

$$G \bullet H = Forget_3(Ren_2 \leftrightarrow_3 (G) // Ren_1 \leftarrow_3 (H))$$

Example :



Their defining equation is : $S = S / / S \cup S \bullet S \cup e$

Relation to tree-decompositions and tree-width



Proposition: A graph has tree-width $\leq k$ *if and only if* it can be constructed from edges by using the operations //, *Rena b* and *Forgeta* with $\leq k+1$ labels a,b,....

Consequences :

- Representation of tree-decompositions by terms.
- Algebraic characterization of tree-width.
- The set of graphs of tree-width at most k is equational for each k.
- Every **HR** equational set of graphs has bounded tree-width (an upper bound is easy to obtain from a system S : just count the number of source labels used in S).

From an algebraic expression to a tree-decomposition

Example : cd // *Ren*_{a \leftarrow c} (ab // *Forget*_b(ab // bc)) (ab denotes an edge from a to b)



The tree-decomposition associated with this term.

Negative facts about HR-equational sets

- The set of all finite graphs is not HR-equational.
- Neither is the set of all square grids (planar graphs of degree 4)

- Parsing is NP-complete for certain fixed equation systems (graphs of cyclic bandwidth < 3)

But finding a tree-decomposition of width $\leq k$ (if it exists) can be done in "linear" time (O(2^p.n) where n = number of vertices and p = 32.k²)

Examples of **HR**-equational sets:

- Every context-free language but also the language $\{a^n b^n c^n \mid n > 0\}$.

- Outerplanar graphs (having a planar embedding with all vertices on the infinite (external) face) and Halin graphs (planar, made of a tree with a cycle linking all leaves).

The VR graph algebra

Origin : Vertex Replacement *graph grammars*. associated complexity measure: clique-width.

Graphs are *simple*, directed or not
(the definitions can be extended to graphs with multiple edges)
We use labels : *a* , *b* , *c* , ..., *d*.
Each vertex has one and only one label ; *several* vertices may
have same label (whereas a source label designates a unique vertex)

One binary operation: disjoint union : \oplus

Unary operations: Edge-addition denoted by Adda,b

Add_{a,b}(G) is G augmented with edges *between* every *a*-port and every *b*-port (undirected case) or *from* every *a*-port to every *b*-port (directed case).



 $H = Add_{a,b}(G)$; only 5 edges added

The number of added edges depends on the argument graph.

Vertex relabellings :

 $Relab_a \rightarrow b(G)$ is G with every vertex labelled by a relabelled into b

Basic graphs are those with a single vertex.

Definition: A graph G has clique-width $\leq k \Leftrightarrow$ it can be constructed from basic graphs with the operations \bigoplus , *Adda,b* and *Relaba* $\longrightarrow b$ by using *k* labels. Its clique-width *cwd*(G) is the smallest such *k*

Clique-width has no combinatorial characterization (like tree-width). It is defined in terms of few very simple graph operations, giving easy inductive proofs. *Equivalent notion*: rank-width (Oum and Seymour) with better structural and algorithmic properties (characterization by excluded *vertex-minors*, *exact cubic* decomposition algorithm).



 K_n is defined by t_n where $t_{n+1} = Relabb \longrightarrow a(Adda, b(t_n \oplus b))$

Cliques are defined by the equation :

 $\mathsf{K} = \operatorname{Relabb} \longrightarrow a(\operatorname{Adda,b}(\mathsf{K} \bigoplus \mathsf{b})) \cup \mathsf{a}$

Example 2 : Cographs

They are generated by \oplus and \otimes (the *complete join*) defined by :

 $G \otimes H = Relab_{b} \rightarrow a(Adda, b (G \oplus Relaba \rightarrow b(H)))$

 $= G \oplus H$ with "all possible" undirected edges between G and H.

Cographs are defined by :

 $C = C \oplus C \quad \cup \quad C \otimes C \quad \cup \quad a$

Fact: A simple undirected loop-free graph is a cograph if and only if it has clique-width at most 2.

Example 3 : *Distance hereditary graphs* have clique-width at most 3 (and are the graphs of rank-width 1).

Proposition : (1) Bounded tree-width implies bounded clique-width $(cwd(G) \le 2^{2twd(G)+1} \text{ for } G \text{ directed}), \text{ but not conversely.}$

(2) Unlike tree-width, clique-width is sensible to edge directions : Cliques have clique-width 2, tournaments have unbounded clique-width.

Classes of <u>unbounded tree-width</u> and <u>bounded clique-width</u>:

Cographs (2), Distance hereditary graphs (3),

Graphs without $\{P_5, \mathbf{1} \otimes P_4\}$ (5), or $\{\mathbf{1} \oplus P_4, \mathbf{1} \otimes P_4\}$ (16)

as induced subgraphs.

(many similar results for exclusion of induced subgraphs with 4 and 5 vertices).

Classes of <u>unbounded clique-width</u>:

Planar graphs of degree 3, Tournaments, Interval graphs, Graphs without induced P_5 . ($P_n = path$ with n vertices)

Summary Two algebras of (finite) graphs HR and VR

Two notions of "context-free sets" : the equational sets of algebras **HR** and **VR**, (and *below*, two notions of recognizable sets, based on congruences).

1) Comparison of the two classes :

 $Equat(HR) \subseteq Equat(VR)$

= sets in Equat(VR) whose graphs are without some fixed $K_{n,n}$ as subgraph.

2) Why not using a third algebra?

One could, but Equat(**HR**) and Equat(**VR**) are robust in the following sense :

- * logical characterizations independent of the initial definitions,
- * stability under certain logically defined transductions,
- * generation from trees.

For other algebras, we would loose these properties (proofs below).

3) Properties following from the algebraic setting :

- Closure under union, // , \oplus and the unary operations
- Emptiness and finiteness are decidable (finite sets are computable)
- Semi-linearity Theorem (extends "Parikh's Theorem")
- Derivation trees
- Denotation of the generated graphs by terms,
- Upper bounds to tree-width and clique-width.
- 4) Properties that do not hold as we could wish :
 - The set of all finite (even planar) graphs is neither HR- nor VR-equational.
 - Parsing is NP-complete (even for some fixed equation systems)

Exercises

1) Prove that $\{a^n b^n c^n \mid n > 0\}$ and the set of square words (ww) are HR-equational.

2) Construct HR equation systems for the outerplanar and the Halin graphs.

3) Construct an HR equation system for the series-parallel graphs having an even number of vertices.

4) Construct a VR equation system for the trees having an number of nodes multiple of 3.

5) Construct a VR equation system for the cographs having an even number of edges.

6) Prove that the non-context-free language $\{a^n \mid n=2^p \text{ for some } p \ge 0\}$ is HR-equational for some appropriate algebra extending the monoid of words.

7) Complete the proof of the proposition page 19: transform a tree-decomposition of width k into a term of the HR algebra defining the same graph and using k+1 source labels.

8) Prove that the proposition of page 19 holds without the source renaming operations.

3. Recognizable sets : an algebraic definition

 $M = \langle M, (f_M)_{f \in F} \rangle$: an F-algebra where F is a *finite* signature.

Definition : $L \subseteq M$ is (M-)*recognizable* if it is a union of equivalence classes for a finite congruence \approx on M.

Congruence = equivalence relation such that :

 $m \approx m'$ and $p \approx p' \implies f_{\mathbf{M}}(m,p) \approx f_{\mathbf{M}}(m',p')$.

Finite means that M / \approx is finite, i.e., \approx has finitely many classes. Equivalently, $L = h^{-1}(D)$ for a homomorphism $h : M \rightarrow A$, where

A is a *finite* F-algebra and $D \subseteq A$.

Rec(M) = the recognizable subsets of M. This notion is relative to the algebra M (not only to the underlying set M).

Classical examples Algebra Recognizable sets <A* , ., ε , a,b,...,d> Regular languages (syntactic monoid)

 $<A^*$, ε , $(\lambda u \in A^*.ua)_{a \in A} >$

Regular languages (Myhill-Nerode)

T(F), terms over F, (initial F-algebra)
 Regular sets of terms
 On terms, h (cf. page 31) is the run of a *finite deterministic bottom-up automaton*

<N^k, + , (0,...,0), ... (0,...,1,0,...,0) ...> Finite unions of Cartesian
products of k sets { u + n.v | n $\in \mathbb{N}$ } for u,v $\in \mathbb{N}$

The algebras **HR** and **VR** have *infinite* signatures We introduce two notions of type (or *sorts* in a many-sorted framework). For **HR**: G has type $\tau(G)$ = the set of labels of its sources.

 $\boldsymbol{\tau}$ has a homomorphic behaviour :

 $\tau(G//H) = \tau(G) \cup \tau(G) ; \tau(Forget_a(G)) = \tau(G) - \{a\};$

 $\tau(\operatorname{Ren}_{a} \leftrightarrow b(G)) = \tau(G)[a/b, b/a].$

For VR : the type is $\pi(G)$ = the set of vertex labels having an occurrence.

 π has a homomorphic behaviour :

 $\tau(G \bigoplus H) = \tau(G)U\tau(H) ; \tau(Add_{a,b}(G)) = \tau(G) ;$

 $\tau(\operatorname{Relaba} \longrightarrow b(G)) = \tau(G)[b/a].$

For defining recognizability of set L, we require that the congruence \approx is *type preserving* (for τ or π according to the case, HR or VR):

 $G \approx H \implies \tau(G) = \tau(H)$

locally finite : it has finitely many classes of each type. and L is a union of classes (possibly of different types).

We can also use many-sorted algebras **HR** and **VR** with countably many sorts, and $\tau(G)$ and $\pi(G)$ as respective sorts of a graph G, (because the type function has a homomorphic behaviour).

Two notions of recognizable sets of graphs, for algebras HR and VR.

Comparison of the two classes :

 $Equat(HR) \subseteq Equat(VR)$

= sets in Equat(VR) whose graphs are without some fixed $K_{n,n}$ as subgraph.

Intuition : VR has more powerful operations than HR, but they make difference only for graphs without some $K_{n,n}$ as subgraph.

Properties of recognizable sets that follow from the algebraic setting :

- Closure under \cup , \cap and (difference),
- under inverse homomorphisms and inverse unary derived operations. (*Proofs* : clear from the definitions).

- *Filtering Theorem*: The intersection of an equational set and a recognizable one is equational

with effective constructions.

(*Proof* : cf. 2-colorability of series-parallel graphs detailed below).

Properties of recognizable sets of graphs that do not follow "algebraically"

> Closure under the binary operations of the algebras : //, \oplus , under the unary operations fg_a , $ren_{a \leftrightarrow b}$, $relab_a \rightarrow b$

Remarks: (1) This closure is false for $Add_{a,b}$ but is true if some "harmless" restriction of the use of this operation is made.

(2) Compare with regular languages:

it is *more difficult* to prove their closure under concatenation than under the Boolean operations; this is reflected by the sizes of syntactic monoids. Properties that do not hold as we could wish or expect:

- Emptiness is not decidable (because of infinite signatures).
- Rec and Equat are incomparable (for HR and VR).
- Every set of square grids is HR- and VR-recognizable.
- There are uncountably many recognizable sets and *no* characterization by finite automata or logical formulas.

(To be contrasted with the cases of words and terms).

Inductive proofs and computations

Based on equations like the one that defines Series-Parallel graphs :

 $S = S / / S \cup S \bullet S \cup e$

Examples: "Proof that all series-parallel graphs are connected",
"Proof that all series-parallel graphs are planar",
"Number of directed paths from *Entry* to *Exit* in a given series-parallel graph".

Sometimes, auxiliary properties and / or functions are necessary.

Recognizability means "finitely many auxiliary properties suffice"

Inductive computation :

Test of 2-colorability for series-parallel graphs

Not all series-parallel graphs are 2-colorable (see K₃)

G, H 2-colorable does not imply that G//H is 2-colorable (because $K_3=P_3//e$). One can check 2-colorability with 2 auxiliary properties :

> Same(G) = G is 2-colorable with sources of the same color, Diff(G) = G is 2-colorable with sources of different colors

by using the rules :

Diff(e) = True ; Same(e) = False

Same(G//H) \Leftrightarrow Same(G) \land Same(H)Diff(G//H) \Leftrightarrow Diff(G) \land Diff(H)

Application 1 : Linear algorithm

For every term t, we can compute, by running a finite deterministic bottom-up automaton on t, the pair of Boolean values (Same(Val(t)), Diff(Val(t))).

We get the answer for G = Val(t) (the graph that is the *value* of t) regarding 2-colorability.

Example : σ at node u means that Same(Val(t/u)) is true, $\overline{\sigma}$ that it is false, δ that Diff (Val(t/u)) is true, etc... Computation is *done bottom-up* with the rules of previous page.



The graph is not 2-colorable.

Application 2 : Equation system for 2-colorable series-parallel graphs

 $S_{\sigma,\delta}$ = the set of series-parallel graphs that satisfy Same (σ) and Diff (δ) $S_{\sigma,\overline{\delta}}$ = the set of those that satisfy Same and *not* Diff, etc ...

From the equation : $S = S//S \cup S \cdot S \cup e$, we get the equation system : (a) $S_{\sigma,\delta} = \frac{S_{\sigma,\delta}}{S_{\sigma,\delta}} \cup \frac{S_{\sigma,\delta}}{S_{\sigma,\delta}} \cup \frac{S_{\sigma,\delta}}{S_{\sigma,\delta}} = \frac{S_{\sigma,\delta}}{S_{\sigma,\delta}} \cup \frac{S_{\sigma,\delta}}{S_{\sigma,\delta}}$

$$S_{\sigma,\delta} \bullet S_{\sigma,\delta} \ \cup \ S_{\sigma,\delta} \bullet S_{\sigma,\bar{\delta}} \ \cup \ S_{\sigma,\delta} \bullet S_{\bar{\sigma},\delta} \ \cup \ S_{\sigma,\bar{\delta}} \bullet S_{\sigma,\delta} \ \cup \ S_{\bar{\sigma},\delta} \bullet S_{\sigma,\delta}$$

In equation

 $S_{\sigma,\delta}$ is in all terms of the righthand side : it defines (least solution) the empty set. This proves (a small theorem) :

Fact: No series-parallel graph satisfies Same and Diff.

We can simplify the system {(a), (b), (c), (d)} into: (b') $S_{\bar{\sigma},\delta} = e \cup S_{\bar{\sigma},\delta} / S_{\bar{\sigma},\delta} \cup S_{\sigma,\bar{\delta}} \bullet S_{\bar{\sigma},\delta} \cup S_{\bar{\sigma},\delta} \bullet S_{\sigma,\bar{\delta}}$

$$(c') \quad S_{\sigma,\bar{\delta}} = S_{\sigma,\bar{\delta}} / / S_{\sigma,\bar{\delta}} \ \cup \ S_{\sigma,\bar{\delta}} \bullet S_{\sigma,\bar{\delta}} \ \cup \ S_{\bar{\sigma},\delta} \bullet S_{\bar{\sigma},\delta}$$

$$\begin{array}{rcl} (d') & S_{\bar{\sigma},\bar{\delta}} = S_{\bar{\sigma},\bar{\delta}} / / S_{\bar{\sigma},\bar{\delta}} \ \cup \ S_{\bar{\sigma},\bar{\delta}} / / S_{\bar{\sigma},\bar{\delta}} \ \cup \ S_{\bar{\sigma},\bar{\delta}} & \cup$$

By replacing $S_{\overline{\sigma},\overline{\delta}}$ by T_{σ} , $S_{\sigma,\delta}$ by T_{δ} , by using commutativity of //, we get the system (for the 2-colorable series-parallel graphs) $\begin{cases} T = T_{\sigma} \cup T_{\delta} \\ T_{\sigma} = T_{\sigma} / / T_{\sigma} \cup T_{\sigma} \bullet T_{\sigma} \cup T_{\delta} \bullet T_{\delta} \\ T_{\delta} = e \cup T_{\delta} / / T_{\delta} \cup T_{\sigma} \bullet T_{\delta} \cup T_{\delta} \bullet T_{\sigma} \end{cases}$

Recognizability and inductive sets of properties

Definition : A set P of properties on an F-algebra **M** is F-inductive if, for every $p \in P$ and $f \in F$, there exists a Boolean formula **B** such that :

 $p(f_{M}(a,b)) = B[...,q(a),...,q'(b),...]$ for all a and b in M

 $q, q' \in P$, $q(a), \dots, q(b) \in \{True, False\}$.

Proposition : A subset L of **M** is recognizable if and only if it is the set of elements that satisfy a property belonging to a *finite* inductive set P of properties

Inductive sets formalize the notion of "auxiliary properties" in proofs by induction.

Inductive sets of properties and automata on terms

The simultaneous computation of m inductive properties can be implemented by a finite deterministic bottom-up automaton with 2^m states running on terms *t*.

This computation takes time O(|t|): this fact is the key to fixed-parameter tractable algorithms.

Remark : Membership of an element **m** of **M** in a recognizable set L can be tested by such an automaton on any term t in T(F) defining **m** (in some term if L is equational, i.e. "context-free"). 4. Monadic Second-Order (MS) Logic

A logical language that specifies inductive properties and functions

- = First-order logic on power-set structures
- = First-order logic extended with (quantified) variables denoting subsets of the domains.

MS (expressible) properties : transitive closure, properties of paths, connectivity, planarity (via Kuratowski, uses connectivity), k-colorability.

Examples of formulas for $G = (V_G, edg_G(.,.))$, undirected

G is 3-colorable :

$$\begin{array}{l} \exists X,Y \; (\; X \cap Y = \emptyset \; \land \\ \forall u,v \; \{ \; edg(u,v) \Rightarrow \\ \quad [(u \in X \; \Rightarrow \; v \notin X) \land (u \in Y \Rightarrow \; v \notin Y) \land \\ \quad (u \notin X \cup Y \; \Rightarrow \; v \in X \cup Y) \;] \\ \quad \} \end{array}$$

G (undirected) is not connected :

 $\exists X (\exists x \in X \land \exists y \notin X \land (\forall u, v (u \in X \land edg(u, v) \Longrightarrow v \in X))$

Transitive and reflexive closure : TC(R, x, y):

 $\begin{array}{l} \forall \ X \ \{ ``X \ is \ R-closed" \ \land \ x \in X \ \Longrightarrow y \in X \ \} \\ \\ where \ ``X \ is \ R-closed" \ is \ defined \ by : \\ \\ \forall u,v \ (u \in X \ \land \ R(u,v) \Longrightarrow v \in X) \end{array}$

The relation R can be defined by a formula as in :

$$\forall x, y (x \in Y \land y \in Y \Rightarrow TC("u \in Y \land v \in Y \land edg(u,v)", x, y)$$

expressing that G[Y] is connected (note that Y is free in R).

Application : G contains (fixed) H as a minor where $V_H = \{1,...,p\}$: there exist disjoint sets of vertices $X_1,..., X_p$ in G such that each $G[X_i]$ is connected and, whenever if i -- j in H, there is an edge between X_i and X_j .

Consequence : planarity is MS-expressible (no minor K_5 or $K_{3,3}$).

Provably non-expressible properties

- G is isomorphic to $K_{p,p}$ for some p (*not fixed*; needs equipotence of two sets, hence quantification over binary relations to find if there is a bijection).
- G has a nontrivial automorphism, or has all vertices of same degree.
- Card(X) is a multiple of p. (But this is possible if the graph is linearly ordered or some linear order is definable by an MS formula).

Definition: Adding these *cardinality set predicates* to MS logic gives Counting monadic second-order logic (or CMS): all good properties of MS logic hold for it.

(Adding an *equicardinality* set predicate to MS would spoil everything.)

Edge set quantifications *increase* the expressive power Incidence graph of G undirected, $Inc(G) = (V_G \cup E_G, inc_G(.,.))$ $inc_G(v,e) \Leftrightarrow v$ is a vertex of edge e.

Monadic second-order formulas written with inc can use quantifications on sets of edges : they define MS_2 –expressible graph properties.

The existence of a perfect matching or a Hamiltonian circuit is MS_2 -expressible but not MS-expressible.

Definition : A set L of finite graphs is MS-definable (MS₂-definable) if L = { G finite / G $|= \phi$ } (L = { G finite / Inc(G) $|= \phi$ }) for a fixed MS sentence (a formula without free variables) ϕ . Recognizability Theorem : (1) A language (set of words or *finite terms*) is recognizable (by congruence or automaton) \Leftrightarrow it is MS definable

(2) A set of finite graphs is VR-recognizable \leftarrow it is CMS-definable

(3) A set of finite graphs is HR-recognizable \leftarrow it is CMS₂-definable

Proofs: (1) Doner, Thatcher & Wright, (1968 - 1970).

(2) and (3) can be proved together in two ways:

- by using the Feferman-Vaught paradigm
- by constructing an automaton on terms by induction on the structure of the given formula. This method (see Section 5 below) is better for concrete implementation.

The Feferman-Vaught paradigm

Main idea: the validity of an MS formula in the disjoint union of two relational structures can be deduced from those of finitely many auxilliary formulas of no larger quantifier-height in each of the two structures. (A very simple case of the "Composition Method" for infinite combinations of structures by Feferman & Vaught and Shelah.)

This is inductivity / recognizability.

We consider the easiest case, that of VR-recognizability

Notation: The result of the *query* defined by formula φ with free variables among X₁,...,X_n, i.e., the set of satisfying assignments in G is Sat(G, φ , X₁,...,X_n) = { (V₁,...,V_n) / G | = φ (V₁,...,V_n) }

Lemma 1 : If *f* is a *quantifier-free* mapping on graphs (edge-addition, vertex relabeling, edge complement), every φ has a Backwards Translation $f^{\#}(\varphi)$ relative to *f* such that for all G :

$$Sat(f(G), \phi, X_1,...,X_n) = Sat(G, f^{\#}(\phi), X_1,...,X_n)$$

where $f^{\#}(\phi)$ has no larger quantifier-height than ϕ .

Splitting Theorem : One can construct formulas ψ_i , θ_i , i = 1,...,p, of no larger quantifier-height than ϕ such that for all disjoint G and H : Sat(G \oplus H, ϕ , X₁,...,X_n) is the disjoint union of the sets Sat(G, ψ_i , X₁,...,X_n) \diamond Sat(H, θ_i , X₁,...,X_n), i = 1,...,p, where \diamond combines "partial answers" as follows : $A \Diamond B = \{ (A_1 \cup B_1, \dots, A_n \cup B_n) / (A_1, \dots, A_n) \in \underline{A}, (B_1, \dots, B_n) \in \underline{B} \}$ *Proof* : Induction on the structure of ϕ .

Lemma 2 : For each n and h there are finitely many formulas $\phi(X_1,...,X_n)$ of quantifier-height \leq h, up to a decidable and sound equivalence.

Proof : Routine. But yields large number !

Proof of the Recognizability Theorem :

For each h, the equivalence relation such that :

 $G \approx H \iff Sat(G, \psi) = Sat(H, \psi) (= \emptyset \text{ or } (), \text{ the empty sequence})$ for every sentence ψ of quantifier-height \leq h is a *type-preserving*, *locally finite* congruence on VR that saturates the set of graphs defined by ϕ , for each ϕ of quantifier-height \leq h

(The same proof works for **HR**, the algebra of graphs with sources, but one more lemma is necessary to handle the fusion of sources in parallel composition; sources are represented by constants of the logical structures).

Extensions of the proof

1) For *counting* valid assignments, i.e., for computing, for given G and fixed formula φ the cardinality of the set Sat(G, φ , X₁,...,X_n), the Splitting Theorem gives (*because of disjoint unions*) the recursion : Sat(G \oplus H, φ , X₁,...,X_n) =

$$\sum_{i=1,\ldots,p} |\operatorname{Sat}(G, \psi_i, X_1, \ldots, X_n)| \cdot |\operatorname{Sat}(H, \theta_i, X_1, \ldots, X_n)|$$

2) Similar fact for *optimizing functions*, defined by : $MaxSat(G, \phi, X) = Max \{ |A| / G | = \phi(A) \}$ Algorithmic consequences of the Recognizability Theorem

MS formulas MS₂ formulas

using edge quantifications

 $G = (V_G, edg_G(.,.)) \qquad Inc(G) = (V_G \cup E_G, inc_G(.,.))$

for G undirected : $inc_G(e, v) \Leftrightarrow$

v is a vertex (in V_G) of edge e (E_G)

FPT *cubic* for clique-width finding a VR-term defining the graph is possible in cubic time (Hlineny, Oum & Seymour)

-width FPT *linear* for tree-width ng the finding a tree-decomposition bic time is possible in linear time (Bodlaender) (even in *LogSpace*, Elberfeld *et al.*, FOCS 2010)

Language Theoretical consequences

One can filter out from HR- or VR-equational sets the graphs which do not satisfy given MS_2 - or MS-properties and one obtains HR- or VR-equational sets.

Generalizes : the intersection of a context-free language and a regular language is context-free.

Consequences for the decidability of logical theories

The MS₂-theory of the set of graphs of tree-width \leq k is decidable. (is a given sentence true in all graphs of tree-width \leq k ?) The MS-theory of the set of graphs of clique-width \leq k is decidable.

Exercises

1) Write an MS-sentence expressing that the considered simple graph is a tree. 2) Write an MS-formula with free variables x,y,z expressing that, in a tree (undirected and unrooted), if one takes x as root, then y is an ancestor of z. 3) Write an MS_2 -sentence expressing that a graph has a Hamiltonian cycle. 4) A nonempty word over alphabet {a,b} can (also) be considered as a directed path given with unary relations lab_a and lab_b representing the sets of occurrences of letters a and b. Prove that every regular language over {a,b} is MS-definable. 5) A complete bipartite graph $K_{n,m}$ has a Hamiltonian cycle iff n=m. Construct such a graph "over" any word in {a,b}⁺ having at least one a and at least one b. Deduce from 4) that Hamiltonicty is not MS-expressible.

6) Write an MS₂-sentence expressing that a graph has a spanning tree of degree \leq 3. Show as in 5) that this property is not MS-expressible.