

Type Systems and Programming

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<https://www.labri.fr/perso/renault/working/teaching/stp/stp.php>

Introduction

What's a programming language?

```
int ackermann(int m, int n) {  
    if (!m) return n + 1;  
    if (!n) return ackermann(m-1,1);  
    return ackermann(m-1,  
                      ackermann(m,n-1));  
}
```

```
ackermann ← {  
    0 = 1 ⊃ ω : 1 + 2 ⊃ ω  
    0 = 2 ⊃ ω : ∇(¬1 + 1 ⊃ ω) 1  
    ∇(¬1 + 1 ⊃ ω), ∇(1 ⊃ ω), ¬1 + 2 ⊃ ω  
}
```

A complex and expressive tool for the representation of **computations**.

Introduction

Focus on the problem of the **verification** of these computations.

What properties can one expect to be enforceable?

- **Termination** properties : is it possible to be perfectly certain that a given program evaluates in a finite number of steps?
- **Correctness** properties : is it possible to be perfectly certain that a program never ends up in an uncontrolled error state?

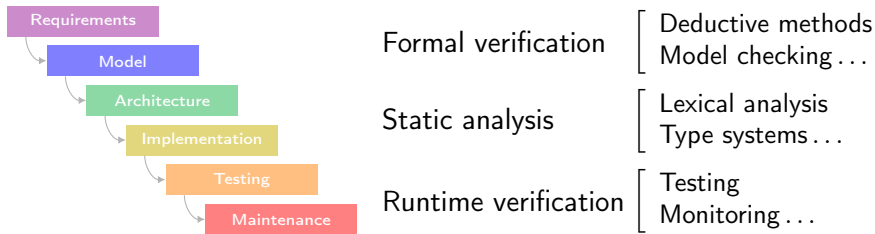
And more pragmatically, checking for the presence or absence of :

- null pointer exceptions, invalid file descriptors,
- indices out of array bounds, divisions by zero ...

Introduction

How is it possible to enforce some of these properties ?

⇒ Different families of methods, spread along the development cycle.



⇒ Each family possesses different characteristics :

- Compile-time or Runtime
- Automatic or Assisted
- Decidable (complexity ?) or Semi-decidable

Type systems

(informal description)

- a family of **tractable** methods,
- considering programs on a **syntactic** level,
- verifying some properties on their **behaviors**.

General tactics

- Classify the expressions occurring inside a program into **types**,
- Verify that the combination of these **types** into the program respect a set of coherence rules.

Example :

locomotive + flower

Programming languages and type systems studied in this course :

- OCaml (4.14) ocaml.org
- Haskell (ghc-9.4) haskell.org/ghc
- LiquidHaskell (0.9.4-git) ucsd-progsys.github.io/liquidhaskell-blog
- Scala (2.13) scala-lang.org

And their influence in mainstream languages :

- Java 8-21, C++ 14-23, C# 5-13 ...

Some references

- Pierce, B. C. *Types and Programming Languages*. MIT Press, 2002.
- Bruce, K. B. *Foundations of Object-oriented Languages : Types and Semantics*. MIT Press, 2002.
- Hindley, J. R. *Basic simple type theory*. Cambridge University Press, 1997.
- Wadler, P. *Propositions as types*. Communications ACM, 2015.

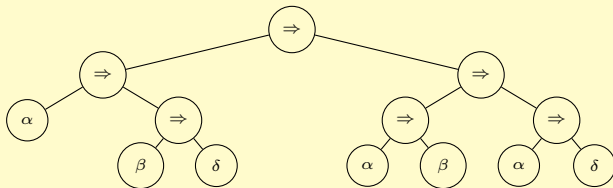
1 Simple lambda-calculus

- 1 **Simple lambda-calculus**
 - Propositional logic
 - Untyped lambda calculus

Definition (Minimal intuitionistic logic)

The **minimal intuitionistic logic** is the set of all formulae $P, Q, \dots$ constructed from :

- an infinite set of atomic formulae denoted as variables $\alpha, \beta, \dots$,
- if P, Q are two formulas, then $P \Rightarrow Q$ is also a formula.



It is a simple fragment of the more general propositional logic.

Definition (Sequent)

A **sequent** is an assertion $\Gamma \vdash \alpha$, where :

- Γ is a possibly empty sequence of formulae called the **antecedents**,
- and α is a formula called the **consequent**.

Writing $\Gamma, P \vdash Q$ means that the antecedents are constituted of a list of formulae Γ along with a specific formula P .

Definition (Derivation tree)

A **derivation tree** (or proof tree) is a tree whose nodes are syntactically coherent with a finite set of inference rules. In propositional logic, these rules are the following :

$$\frac{}{P \vdash P} [\text{ax}] \qquad \frac{\Gamma, P \vdash Q}{\Gamma \vdash P \Rightarrow Q} [\Rightarrow i] \qquad \frac{\Gamma \vdash P \quad \Gamma \vdash P \Rightarrow Q}{\Gamma \vdash Q} [\Rightarrow e]$$

Each inference rule possesses a name indicating its role, most of the time the introduction (I) or the elimination (E) of a logical operator.

Frege's theorem

$$\left(R \Rightarrow (S \Rightarrow T) \right) \Rightarrow \left((R \Rightarrow S) \Rightarrow (R \Rightarrow T) \right)$$

Inference rules

$$\frac{}{P \vdash P} [\text{ax}] \qquad \frac{\Gamma, P \vdash Q}{\Gamma \vdash P \Rightarrow Q} [\Rightarrow i] \qquad \frac{\Gamma \vdash P \quad \Gamma \vdash P \Rightarrow Q}{\Gamma \vdash Q} [\Rightarrow e]$$

Proof as a derivation tree

$$\frac{\frac{\frac{}{P \vdash P} [\text{ax}]}{P \vdash P} \quad \frac{\frac{\frac{}{S \vdash S} [\text{ax}]}{S \vdash S} \quad \frac{\frac{}{T \vdash T} [\text{ax}]}{T \vdash T}}{S \vdash S \Rightarrow T} [\Rightarrow i]}{P \vdash (S \Rightarrow T)} [\Rightarrow i] \quad \frac{\frac{}{R \vdash R} [\text{ax}]}{R \vdash R} [\Rightarrow i]}{\vdash (R \Rightarrow (S \Rightarrow T)) \Rightarrow ((R \Rightarrow S) \Rightarrow (R \Rightarrow T))} [\Rightarrow e]$$

Frege's theorem

$$\left(R \Rightarrow (S \Rightarrow T) \right) \Rightarrow \left((R \Rightarrow S) \Rightarrow (R \Rightarrow T) \right)$$

Inference rules

$$\frac{}{P \vdash P} [\text{ax}] \qquad \frac{\Gamma, P \vdash Q}{\Gamma \vdash P \Rightarrow Q} [\Rightarrow i] \qquad \frac{\Gamma \vdash P \quad \Gamma \vdash P \Rightarrow Q}{\Gamma \vdash Q} [\Rightarrow e]$$

Proof as a derivation tree

$$\frac{(R \Rightarrow (S \Rightarrow T)) \vdash (R \Rightarrow S) \Rightarrow (R \Rightarrow T)}{\vdash (R \Rightarrow (S \Rightarrow T)) \Rightarrow ((R \Rightarrow S) \Rightarrow (R \Rightarrow T))}$$

Frege's theorem

$$\left(R \Rightarrow (S \Rightarrow T) \right) \Rightarrow \left((R \Rightarrow S) \Rightarrow (R \Rightarrow T) \right)$$

Inference rules

$$\frac{}{P \vdash P} [\text{ax}] \qquad \frac{\Gamma, P \vdash Q}{\Gamma \vdash P \Rightarrow Q} [\Rightarrow \text{i}] \qquad \frac{\Gamma \vdash P \quad \Gamma \vdash P \Rightarrow Q}{\Gamma \vdash Q} [\Rightarrow \text{e}]$$

Proof as a derivation tree

$$\frac{\frac{\frac{}{} \quad \frac{}{} \quad \frac{}{} \quad \frac{}{}}{} \quad \frac{}{}}{} \quad \frac{}{}}{\frac{(R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S) \vdash (R \Rightarrow T)}{(R \Rightarrow (S \Rightarrow T)) \vdash (R \Rightarrow S) \Rightarrow (R \Rightarrow T)} \vdash (R \Rightarrow (S \Rightarrow T)) \Rightarrow ((R \Rightarrow S) \Rightarrow (R \Rightarrow T))$$

Frege's theorem

$$\left(R \Rightarrow (S \Rightarrow T) \right) \Rightarrow \left((R \Rightarrow S) \Rightarrow (R \Rightarrow T) \right)$$

Inference rules

$$\frac{}{P \vdash P} [\text{ax}] \qquad \frac{\Gamma, P \vdash Q}{\Gamma \vdash P \Rightarrow Q} [\Rightarrow i] \qquad \frac{\Gamma \vdash P \quad \Gamma \vdash P \Rightarrow Q}{\Gamma \vdash Q} [\Rightarrow e]$$

Proof as a derivation tree

$$\frac{\frac{\frac{\Gamma ::= \{(R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S), R\} \vdash T}{(R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S) \vdash (R \Rightarrow T)}}{(R \Rightarrow (S \Rightarrow T)) \vdash (R \Rightarrow S) \Rightarrow (R \Rightarrow T)}}{\vdash (R \Rightarrow (S \Rightarrow T)) \Rightarrow ((R \Rightarrow S) \Rightarrow (R \Rightarrow T))}$$

Frege's theorem

$$\left(R \Rightarrow (S \Rightarrow T) \right) \Rightarrow \left((R \Rightarrow S) \Rightarrow (R \Rightarrow T) \right)$$

Inference rules

$$\frac{}{P \vdash P} [\text{ax}] \qquad \frac{\Gamma, P \vdash Q}{\Gamma \vdash P \Rightarrow Q} [\Rightarrow i] \qquad \frac{\Gamma \vdash P \quad \Gamma \vdash P \Rightarrow Q}{\Gamma \vdash Q} [\Rightarrow e]$$

Proof as a derivation tree

$$\frac{\frac{\frac{\frac{\frac{\frac{}{\Gamma \vdash S \Rightarrow T}}{\Gamma ::= \{(R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S), R\} \vdash T}}{(R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S) \vdash (R \Rightarrow T)}}{(R \Rightarrow (S \Rightarrow T)) \vdash (R \Rightarrow S) \Rightarrow (R \Rightarrow T)}}{\vdash (R \Rightarrow (S \Rightarrow T)) \Rightarrow ((R \Rightarrow S) \Rightarrow (R \Rightarrow T))}}{\Gamma \vdash S} \quad \frac{}{\Gamma \vdash S}$$

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Inference rules

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Proof as a derivation tree

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Frege's theorem

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Proof as a derivation tree

$$\frac{\frac{\frac{\Gamma \vdash R}{\Gamma \vdash S \Rightarrow T} \quad \frac{\Gamma \vdash R \Rightarrow (S \Rightarrow T)}{\Gamma \vdash S \Rightarrow T}}{\Gamma \vdash S \Rightarrow T} \quad \frac{\frac{\Gamma \vdash R}{\Gamma \vdash S} \quad \frac{\Gamma \vdash R \Rightarrow S}{\Gamma \vdash S}}{\Gamma \vdash S} \quad \frac{\Gamma \vdash S \Rightarrow T \quad \Gamma \vdash S}{\Gamma \vdash (R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S), R \vdash T} \quad \frac{\Gamma \vdash (R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S), R \vdash T}{\Gamma \vdash (R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S) \vdash (R \Rightarrow T)} \quad \frac{\Gamma \vdash (R \Rightarrow (S \Rightarrow T)), (R \Rightarrow S) \vdash (R \Rightarrow T)}{\Gamma \vdash (R \Rightarrow (S \Rightarrow T)) \vdash (R \Rightarrow S) \Rightarrow (R \Rightarrow T)} \quad \frac{\Gamma \vdash (R \Rightarrow (S \Rightarrow T)) \vdash (R \Rightarrow S) \Rightarrow (R \Rightarrow T)}{\Gamma \vdash (R \Rightarrow (S \Rightarrow T)) \Rightarrow ((R \Rightarrow S) \Rightarrow (R \Rightarrow T))}$$

Frege's theorem

$$\left(R \Rightarrow (S \Rightarrow T) \right) \Rightarrow \left((R \Rightarrow S) \Rightarrow (R \Rightarrow T) \right)$$

Inference rules

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Proof as a derivation tree

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Summary on propositional logic

The model of propositional logic offers :

- a **language** describing a family of objects **inductively**,
- and a system for defining a subset of this family respecting **local rules**.

The difficulty lies in constructing a kind of **proof** (here a derivation tree) for assessing the validity of a proposition.

In the following, we construct an equivalent model for a programming language : the **untyped λ -calculus**.

So let's start again ...

Definition (Untyped λ -calculus)

The untyped λ -calculus is the set of expressions $t, u, \dots$ constructed from :

- **[Variable]** an infinite set of abstract variables $x, y, \dots$,
- **[Abstraction]** if t is an expression and x is a variable, then $\lambda x.t$ is an expression,
- **[Application]** if t, u are two expressions, then $(t\ u)$ is an expression.

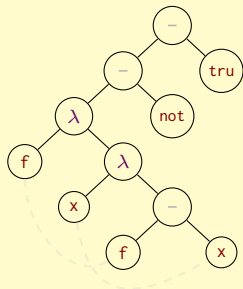
Example :

$((\lambda f. \lambda x. (f\ x))\ \text{not})\ \text{true}$

Python : `(lambda f: lambda x: f(x))(__not__)(True)`

Scheme : `((lambda (f) (lambda (x) (f x))) not) #t`

OCaml : `(fun f → fun x → f(x))(not)(true)`



Definition (Free / Bound variables)

A variable x in a λ -expression u is said to be **bound** iff it appears as a descendant of an abstraction node over the same variable x . Otherwise, it is said to be **free**.

$FV(u)$, the free variables of u :

- $FV(x) = \{x\}$
- $FV(u.v) = FV(u) \cup FV(v)$
- $FV(\lambda x.u) = FV(u) \setminus \{x\}$

$BV(u)$, the bound variables of u :

- $BV(x) = \{\}$
- $BV(u.v) = BV(u) \cup BV(v)$
- $BV(\lambda x.u) = BV(u) \cup \{x\}$

Examples

- $FV((\lambda f.\lambda x.(f\ x)_not)_true) = \{not, true\}$
- $BV((\lambda f.\lambda x.(f\ x)_not)_true) = \{f, x\}$

Definition (α -conversion)

Let $t ::= \lambda x.u$ be an expression and y a variable. An **α -conversion** of t is an expression $\lambda y.v$ where v is a copy of u where every free variable x in u has been replaced by y .

... where $r_{x \rightarrow y}(t)$ is defined as :

$\alpha\text{cnv}_{x \rightarrow y}(t)$ is defined as :

- $\alpha\text{cnv}_{x \rightarrow y}(t)$ is defined as :
- $\alpha\text{cnv}_{x \rightarrow y}(\lambda x.u) = \lambda y.r_{x \rightarrow y}(v)$
 - $\alpha\text{cnv}_{x \rightarrow y}(t) = t$ otherwise
- $r_{x \rightarrow y}(z) = y$ if $z = x$,
 $= z$ otherwise
- $r_{x \rightarrow y}(\lambda z.w) = \lambda z.w$ if $z = x$,
 $= \lambda z.r_{x \rightarrow y}(w)$ otherwise
- $r_{x \rightarrow y}(v.w) = (r_{x \rightarrow y}(v).r_{x \rightarrow y}(w))$

Examples

- $\alpha\text{cnv}_{x \rightarrow y}(\lambda x.x) = \lambda y.y$
- $\alpha\text{cnv}_{x \rightarrow y}(\lambda x.((\lambda x.x)_x)) = \lambda y.((\lambda x.x)_y)$

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- $r_{x \rightarrow y}(\lambda z.w) = \lambda z.w$ if $z = x$,
 $= \lambda z.r_{x \rightarrow y}(w)$ otherwise
- $r_{x \rightarrow y}(v _ w) = (r_{x \rightarrow y}(v) _ r_{x \rightarrow y}(w))$

- **Barendregt convention** : give distinct names to distinct bound variables.
- The λ -expressions can be considered **equivalent** up to α -conversion.

Definition (Substitution)

Let t, u be λ -expressions and x a variable. To **substitute** x by u into t , noted $[x \mapsto u]t$, consists in replacing every free occurrence of x in t by a copy of u .

$[x \mapsto u]t$ is defined as :

- $[x \mapsto u] z = u$ if $z = x$, z otherwise
- $[x \mapsto u](v . w) = ([x \mapsto u]v . [x \mapsto u]w)$
- $[x \mapsto u] \lambda z . w = \lambda z . [x \mapsto u]w$ if $z \neq x$ and $z \notin FV(u)$,
 $\lambda z . w$ otherwise.

Example

$$[x \mapsto \text{biiip}] \left((\lambda z . (x . z)) . y \right) = (\lambda z . (\text{biiip} . z)) . y$$

Definition (β -reduction)

A **redex** in a λ -expression t is a sub-expression of the form $((\lambda x.v) _ w)$. Applying a **β -reduction** step from t to u , noted $t \rightarrow_{\beta} u$, consists in finding a redex sub-expression $((\lambda x.v) _ w)$ inside t and replacing it by $[x \mapsto w]v$.

$t \rightarrow_{\beta} u$ is defined as :

- $(\lambda x.v) _ w \rightarrow_{\beta} [x \mapsto w]v$
 - if $u \rightarrow_{\beta} v$ then
 - Function reduction : $(u _ w) \rightarrow_{\beta} (v _ w)$
 - Parameter reduction : $(w _ u) \rightarrow_{\beta} (w _ v)$
 - Body reduction : $\lambda x.u \rightarrow_{\beta} \lambda x.v$
- $\left. \begin{array}{l} \text{Weak red.} \\ \text{Strong red.} \end{array} \right\}$

Example

$$\left(\lambda z. (\lambda x. x+1) _ (z+2) \right) _ (3+4) \rightarrow_{\beta} \dots \rightarrow_{\beta} ((3+4)+2)+1$$

Definition (β -reduction)

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 - Body reduction : $\lambda x.u \rightarrow_{\beta} \lambda x.v$
- } Weak red.
} Strong red.

- An expression to which no β -reduction step can be applied is said to be in **normal form**.
- The evaluation of a λ -expression consists in applying β -reductions as long as it is possible.

Properties of the λ -calculus

The λ -calculus endowed with the β -reduction relation is a Turing-complete computational model.

- **Church-Rosser theorem** : the β -reduction relation is **confluent**.
- There exist λ -expressions for which the evaluation is **infinite**.

$$nt ::= (\lambda x. (x _ x)) _ (\lambda x. (x _ x)) \qquad nt \rightarrow_{\beta} nt$$

- **Church undecidability theorem** : the problem of determining whether the evaluation of a λ -expression is finite or not is **undecidable**.

Undecidability is at the heart of dealing with programming languages.

Syntax	Evaluation rules
$t ::=$	
x <i>expressions</i>	
$\lambda x.t$ <i>variable</i>	
$(t_1 _ t_2)$ <i>abstraction</i>	
	$\frac{t_1 \rightarrow_{\beta} t'_1}{(t_1 _ t_2) \rightarrow_{\beta} (t'_1 _ t_2)}$
	$\frac{t \rightarrow_{\beta} t'}{(v _ t) \rightarrow_{\beta} (v _ t')}$
$v ::=$ <i>values</i>	
$\lambda x.t$ <i>abstraction value</i>	
	$(\lambda x.t_1 _ t_2) \rightarrow_{\beta} [x \mapsto t_2]t_1$

- **Values** are particular expressions that need no more evaluation.
- In this model, the values are **exactly** the expressions in normal form.

Church encodings : booleans

Let us encode the classical boolean values as the following expressions :

$$\begin{aligned}\text{true} &::= \lambda x. \lambda y. x \\ \text{false} &::= \lambda x. \lambda y. y\end{aligned}$$

(these are the classical projection functions)

The booleans can now be manipulated with the following expressions :

$$\begin{aligned}\text{if} &::= \lambda b. \lambda t. \lambda e. ((b\text{ }t)\text{ }e) \\ \text{or} &::= \lambda x. \lambda y. (((\text{if } x)\text{ } \text{true})\text{ } y) \\ \text{and} &::= \lambda x. \lambda y. (((\text{if } x)\text{ } y)\text{ } \text{false}) \\ \text{not} &::= \lambda x. (((\text{if } x)\text{ } \text{false})\text{ } \text{true})\end{aligned}$$

Example

$$\text{or true false} \rightarrow_{\beta}$$

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$$\begin{aligned}\text{if} &::= \lambda b. \lambda t. \lambda e. ((b\ t)\ e) \\ \text{or} &::= \lambda x. \lambda y. (((\text{if}\ x)\ \text{true})\ y) \\ \text{and} &::= \lambda x. \lambda y. (((\text{if}\ x)\ y)\ \text{false}) \\ \text{not} &::= \lambda x. (((\text{if}\ x)\ \text{false})\ \text{true})\end{aligned}$$

Example

$$\text{or true false} \rightarrow_{\beta} \text{if true true false} \rightarrow_{\beta}$$

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Example

$$\text{or true false} \rightarrow_{\beta} \text{if true true false} \rightarrow_{\beta} \text{true true false} \rightarrow_{\beta}$$

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Example

$$\text{or true false} \rightarrow_{\beta} \text{if true true false} \rightarrow_{\beta} \text{true true false} \rightarrow_{\beta} \text{true}$$

Church encodings : naturals

And the following expressions encode the natural numbers :

$\text{zero} ::= \lambda f. \lambda x. x$ f applied zero times
 $\text{succ} ::= \lambda i. \lambda f. \lambda x. (f ((i \text{ } f) \text{ } x))$ f applied once to the result of $(i \text{ } f)$

With the addition and multiplication functions defined as follows :

$\text{plus} ::= \lambda i. \lambda j. ((i \text{ } \text{succ}) ((j \text{ } \text{succ}) \text{ } \text{zero}))$ apply succ , first j times then i times to zero
 $\text{mult} ::= \lambda i. \lambda j. ((j \text{ } (\text{plus } i)) \text{ } \text{zero})$ apply $(\text{plus } i)$, j times to zero

Example : derivation tree of a β -reduction

In the λ -calculus extended with the Church boolean values :

$$\begin{array}{c}
 \frac{\text{(if_true)} \rightarrow_{\beta} \lambda t. \lambda e. ((\text{true_t})_e)}{\text{((if_true)_false)} \rightarrow_{\beta} (\lambda t. \lambda e. ((\text{true_false})_e)_false) \rightarrow_{\beta} \lambda e. ((\text{true_false})_e)} \\
 \text{(not_true)} \rightarrow_{\beta} \frac{\text{(((if_true)_false)_true)} \rightarrow_{\beta} (\lambda e. ((\text{true_false})_e)_true)}{\dots \rightarrow_{\beta} \text{((true_false)_true)} \rightarrow_{\beta} (\lambda y. \text{false_true}) \rightarrow_{\beta} \text{false}}
 \end{array}$$

The untyped λ -calculus is **everything but practical** :

- Its evaluation rule is remarkably simple.
- But the encodings are multiple and possibly overlapping.

Improvement idea

Extend the language with new expressions : **true**, **succ**, **zero** ...

Possible advantages : higher level of abstraction, custom constructs and values in the language, specific evaluation rules ...

But it becomes necessary to deal with expressions such as **succ true**.

$$(\text{succ_true}) \rightarrow_{\beta} \underbrace{(\lambda i f x. (f_((i_f)_x)))}_{\text{succ}} \underbrace{(\lambda u v. u)}_{\text{true}} \rightarrow_{\beta} \underbrace{\lambda f x. (f_f)}_{??}$$

Let's do it anyway ...

Extension of the λ -calculus : booleans & naturals

Syntax

$t ::= \dots$ *expressions*
true, false *booleans*
zero, succ t *naturals*
if t then t else t *if-then-else*
iszero t *zero-equality*

$v ::= \dots$ *values*
true, false *boolean value*
nv *numeric value*

$nv ::=$ *numeric values*
zero *zero value*
succ nv *successor value*

Evaluation rules

$$\frac{t_1 \rightarrow_{\beta} t'_1}{\text{if } t_1 \text{ then } t_2 \text{ else } t_3 \rightarrow_{\beta} \text{if } t'_1 \text{ then } t_2 \text{ else } t_3}$$

if true then t_2 else $t_3 \rightarrow_{\beta} t_2$
if false then t_2 else $t_3 \rightarrow_{\beta} t_3$

$$\frac{t \rightarrow_{\beta} t'}{\text{iszero } t \rightarrow_{\beta} \text{iszero } t'}$$

iszero zero $\rightarrow_{\beta}$ true
iszero (succ t) $\rightarrow_{\beta}$ false

Example : derivation tree of a β -reduction

Examples of evaluation in the λ -calculus with booleans and integers :

- $$\frac{\text{iszero (succ zero)} \quad \rightarrow_{\beta} \quad \text{false}}{\text{if (iszero (succ zero)) then zero else (succ zero)} \rightarrow_{\beta} \text{if false then zero else (succ zero)} \rightarrow_{\beta} \text{succ zero}}$$
- $$\frac{\text{if false then zero else false} \quad \rightarrow_{\beta} \quad \text{false}}{\text{succ (if false then zero else false)} \rightarrow_{\beta} \text{succ false} \rightarrow_{\beta} ??}$$

Problem

This new language contains **stuck** expressions, that cannot be evaluated further but are still not values, e.g `succ true` or `if zero then true else false`.

- These expressions are the sign of an indecision in the evaluation relation.
- They occur because most of the interesting functions are **partial**.

Summary on the untyped λ -calculus

Starting from now, we consider that the booleans and naturals are part of the definition of the λ -calculus.

- The obtained language is close to a classical programming language without side effects.
- There exist **stuck** expressions that are neither values nor in normal form.
- Stuck expressions are mostly **unavoidable** when extending the language.

In the following we shall endow this language with **types** that allow to determine whether an expression is stuck or not without its full evaluation.

- Pierce, B. C. *Types and Programming Languages*. MIT Press, 2002.
- Bruce, K. B. *Foundations of Object-oriented Languages : Types and Semantics*. MIT Press, 2002.
- Hindley, J. R. *Basic simple type theory*. Cambridge University Press, 1997.
- Wadler, P. *Propositions as types*. Communications ACM, 2015.