

# On the Context-Freeness Problem for Vector Addition Systems

Jérôme Leroux, Vincent Penelle, Grégoire Sutre

LICS, 25 juin 2013

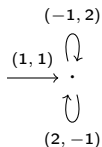
# Table of Contents

- 1 Introduction
- 2 The Context-Freeness Problem for VAS: Small Quiz
- 3 Simulating VAS with Pushdown Automata
- 4 Witnesses of Non-Context-Freeness

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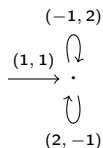
$$\begin{aligned} \mathbf{A} &= \{(-1, 2), (2, -1)\} \\ \mathbf{c}_{\text{init}} &= (1, 1) \end{aligned}$$



A trace is a sequence  $\mathbf{a}_1, \dots, \mathbf{a}_n$  such that:

$$\forall i \leq n, \mathbf{c}_{\text{init}} + \mathbf{a}_1 + \dots + \mathbf{a}_i \geq 0$$

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$$\begin{array}{cccc} \vdots & (-1, 2) & \vdots & (2, -1) & \vdots & (2, -1) & \vdots & & \text{is a trace} \\ (1, 1) & & (0, 3) & & (2, 2) & & (4, 1) & & \end{array}$$

$$\begin{array}{cccc} \vdots & (-1, 2) & (2, -1) & \vdots & (-1, 2) & (-1, 2) & \vdots & (-1, 2) & \vdots & & \text{is not a trace} \\ (1, 1) & & & (2, 2) & & & (0, 6) & & (-1, 8) & & \end{array}$$

# Overview of VAS

VAS  $\sim$  VAS with states  $\sim$  Petri nets

- Prove theorems on VAS
- Model systems with Petri nets

Many decidable problems:

- Coverability [Karp and Miller 69]
- Reachability [Mayr 81, Kosaraju 82]
- Regularity of trace languages [Ginzburg and Yoeli 80, Valk and Vidal-Naquet 81]
- Context-freeness of trace languages [Schwer 92]

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- Context-freeness of trace languages [Schwer 92] **Decidable**
  - ▶ intricate proof with flaws

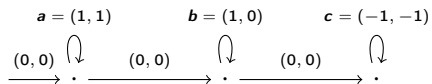


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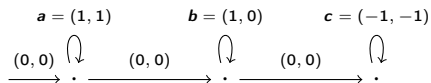
- 1 Introduction
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- Stack: store the value of the counters
- Positive vector  $\Rightarrow$  Push it onto the stack
- Non-positive vector  $\Rightarrow$  Match it with the stack
- Problem: some components may be lost

# Example



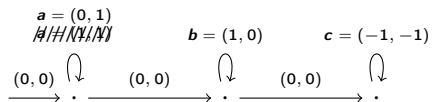
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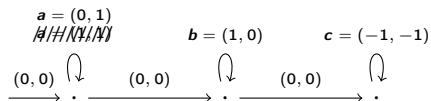
It is context-free.

$$L = \{ \mathbf{a}^n \mathbf{b}^m \mathbf{c}^p \mid n \geq p \wedge m \geq 0 \}$$

# Example



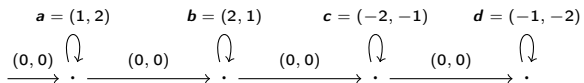
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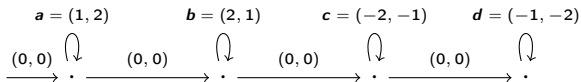
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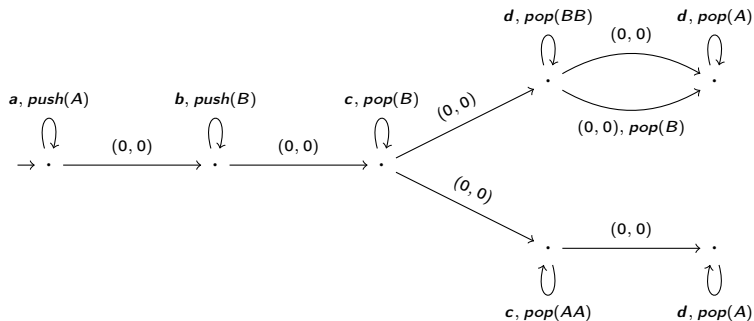
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# Example

$$\begin{array}{c} \mathbf{a} = (-1, 2) \\ (1, 1) \begin{array}{c} \curvearrowright \\ \downarrow \\ \cdot \\ \uparrow \\ \curvearrowleft \end{array} \\ \longrightarrow \\ \mathbf{b} = (2, -1) \end{array}$$

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It is not context-free.

$$\begin{aligned} L \cap (\mathbf{ab})^* \mathbf{a}^* \mathbf{b}^* \\ = \\ \{(\mathbf{ab})^n \mathbf{a}^m \mathbf{b}^p \mid n + 1 \geq m \wedge n + 1 + 2m \geq p\} \end{aligned}$$

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# Vector Pushdown Automata

A vector pushdown automaton (VPDA) contains:

- A set of states  $Q$
- A counter vector  $\mathbf{r} \in \mathbb{Q}_{\geq 0}^d$
- A **stack** containing vectors in  $\mathbb{Q}_{\geq 0}^d$
- A set of transitions  $T$ :
  - ▶ actions on **stack**: push and pop
  - ▶ addition of positive vectors to  $\mathbf{r}$
  - ▶ tests: boolean combinations of

$$\mathbf{r}(i) + \Delta(\mathbf{stack})(i) \# z \qquad \mathbf{r}(i) \# z$$

where  $\# \in \{\leq, \geq\}$

## Proposition

*The language of a VPDA with finitely many states and transitions is context-free*

Idea:

Finite set of transitions

⇒ Finite set of tests, finite stack alphabet

⇒ Above a given value of  $r$  and  $\Delta(\text{stack})$ , a test is always satisfied (or not)

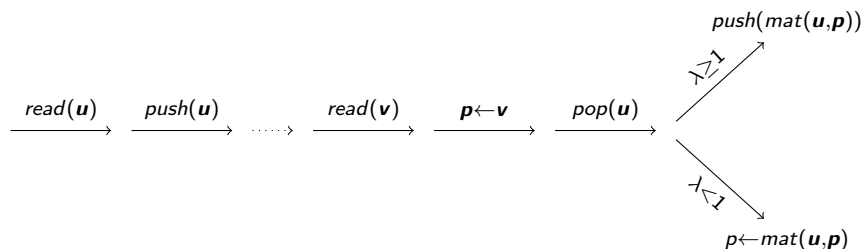
⇒ We can abstract their values and encode  $r$  in the states and  $\Delta(\text{stack})$  in  $\text{stack}$

# Match and Remainder

$\mathbf{u} \geq 0$ ,  $\mathbf{v} \not\geq 0$ , and  $\lambda$  the greatest rational such that  $\mathbf{u} + \lambda\mathbf{v} \geq 0$ ,

$$\text{mat}(\mathbf{u}, \mathbf{v}) = \begin{cases} (1 - \lambda) \cdot \mathbf{v} & \text{if } \lambda < 1 \\ (1 - \frac{1}{\lambda}) \cdot \mathbf{u} & \text{if } \lambda \geq 1 \end{cases}$$

$$\text{rem}(\mathbf{u}, \mathbf{v}) = \mathbf{u} + \mathbf{v} - \text{mat}(\mathbf{u}, \mathbf{v}) \geq 0$$



## Match and Remainder: Example with $\lambda < 1$

Take  $\mathbf{u} = (1, 2, 1)$  and  $\mathbf{v} = (-1, -3, 2)$

The greatest  $\lambda$  such that  $\mathbf{u} + \lambda\mathbf{v} \geq 0$  is  $\lambda = \frac{2}{3}$

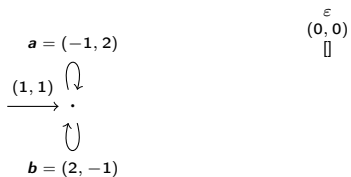
After matching  $\mathbf{u}$  and  $\mathbf{v}$ , we are left with

$$\text{mat}(\mathbf{u}, \mathbf{v}) = (1 - \lambda) \cdot \mathbf{v} = \left(-\frac{1}{3}, -1, \frac{2}{3}\right)$$

The remainder is

$$\text{rem}(\mathbf{u}, \mathbf{v}) = \mathbf{u} + \lambda\mathbf{v} = \left(\frac{1}{3}, 0, \frac{7}{3}\right)$$

# From VAS to VPDA: Example



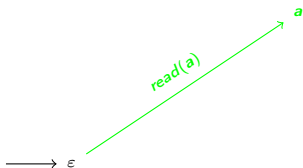
$$\begin{matrix} \varepsilon \\ (0, 0) \\ \square \end{matrix}$$

$\longrightarrow \varepsilon$

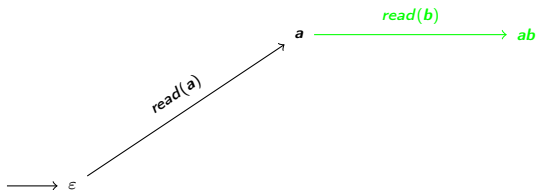
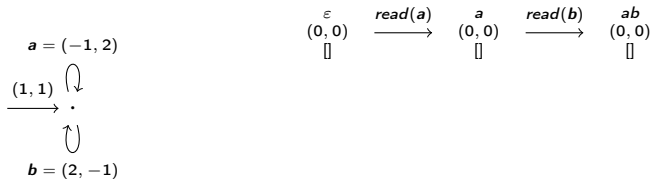


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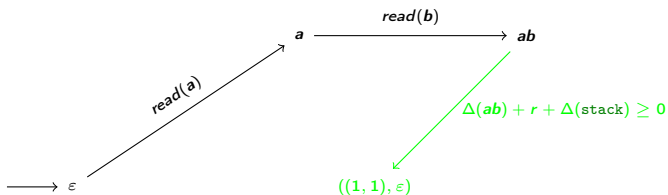
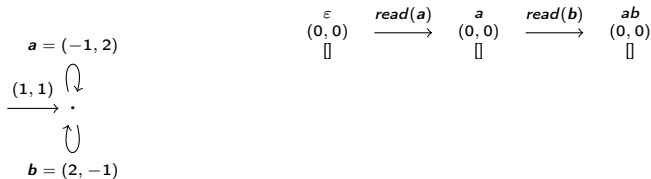
$$\begin{array}{l} \mathbf{a} = (-1, 2) \\ \begin{array}{c} \textcircled{\downarrow} \\ (1, 1) \rightarrow \cdot \\ \textcircled{\uparrow} \\ \mathbf{b} = (2, -1) \end{array} \end{array}$$
$$\begin{array}{ccc} \varepsilon & \xrightarrow{\text{read}(\mathbf{a})} & \mathbf{a} \\ \begin{array}{c} (0, 0) \\ \square \end{array} & & \begin{array}{c} (0, 0) \\ \square \end{array} \end{array}$$



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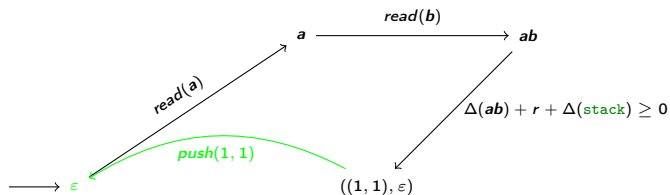
$$a = (-1, 2)$$

$$(1, 1) \downarrow$$



$$b = (2, -1)$$

$$\begin{array}{c} \varepsilon \\ (0, 0) \\ \square \end{array} \xrightarrow{\text{read}(a)} \begin{array}{c} a \\ (0, 0) \\ \square \end{array} \xrightarrow{\text{read}(b)} \begin{array}{c} ab \\ (0, 0) \\ \square \end{array} \xrightarrow{\text{push}(\Delta(ab))} \begin{array}{c} \varepsilon \\ (0, 0) \\ \square \\ [(1, 1)] \end{array}$$



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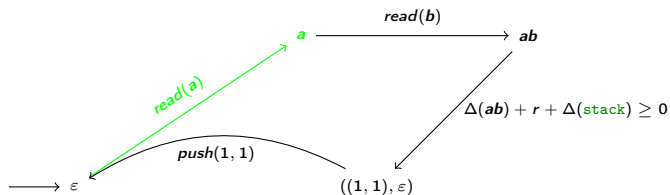
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$$\curvearrowleft$$

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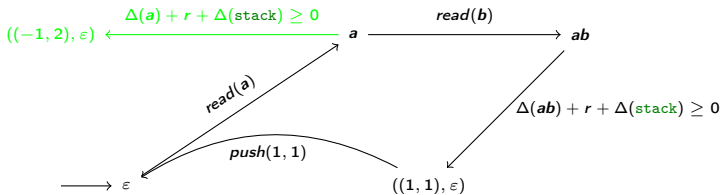
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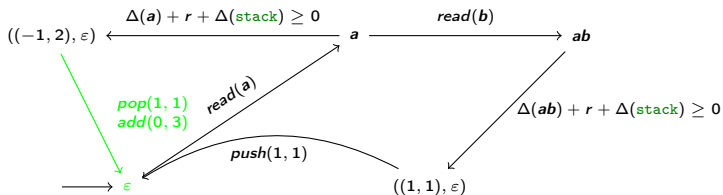
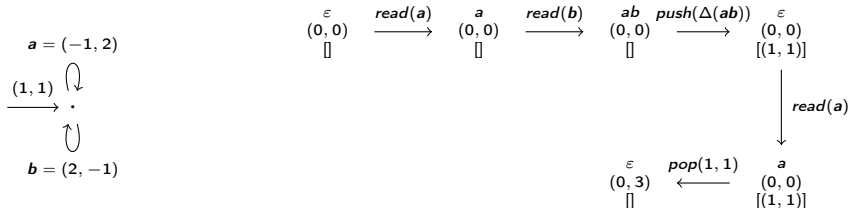
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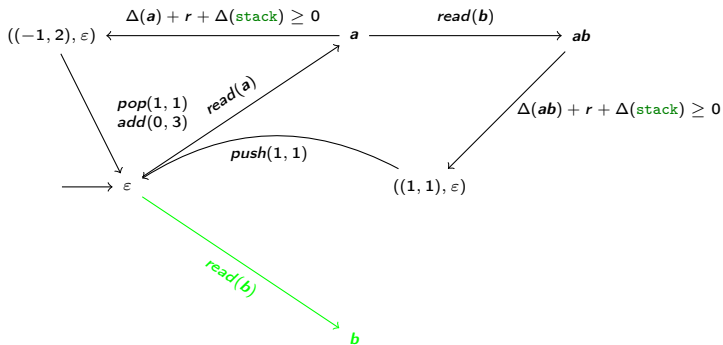
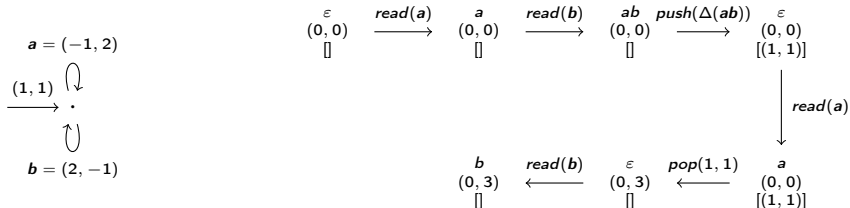
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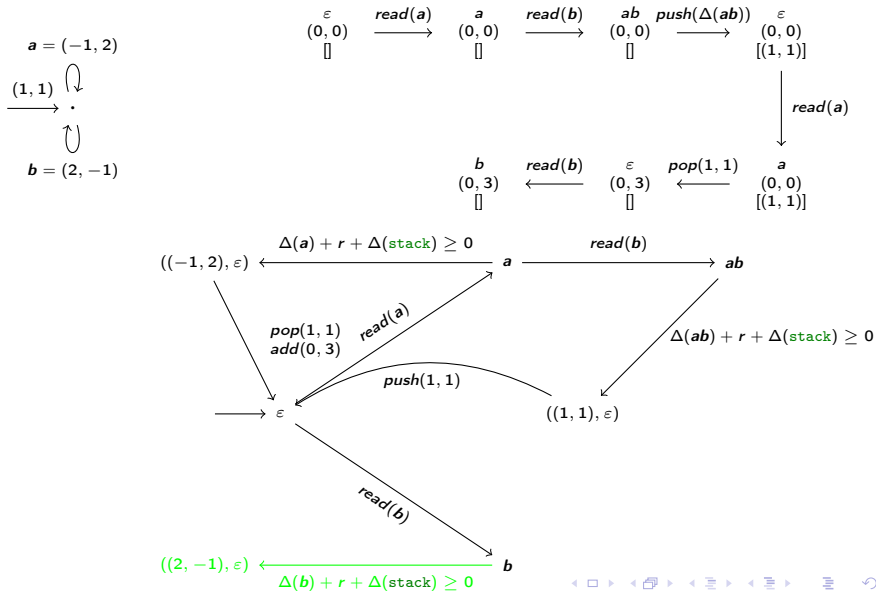


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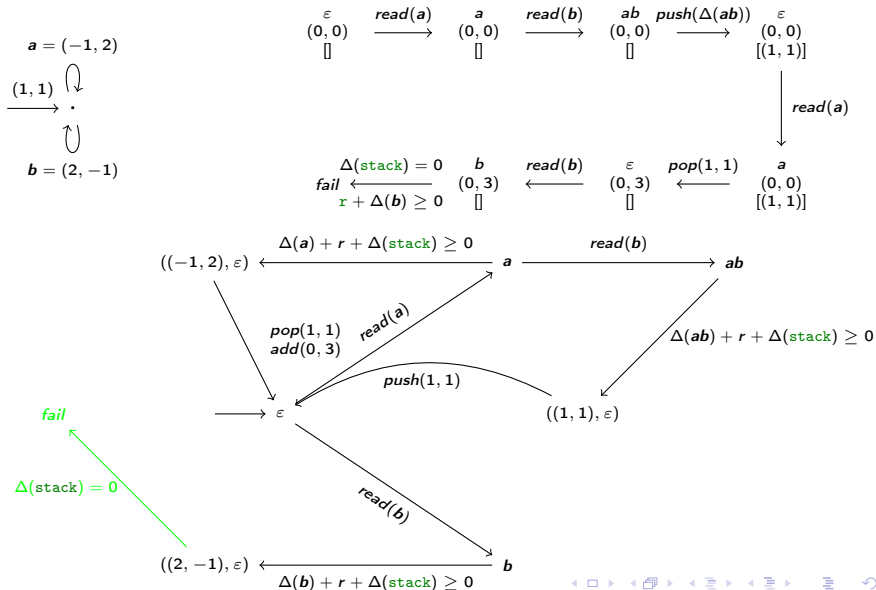




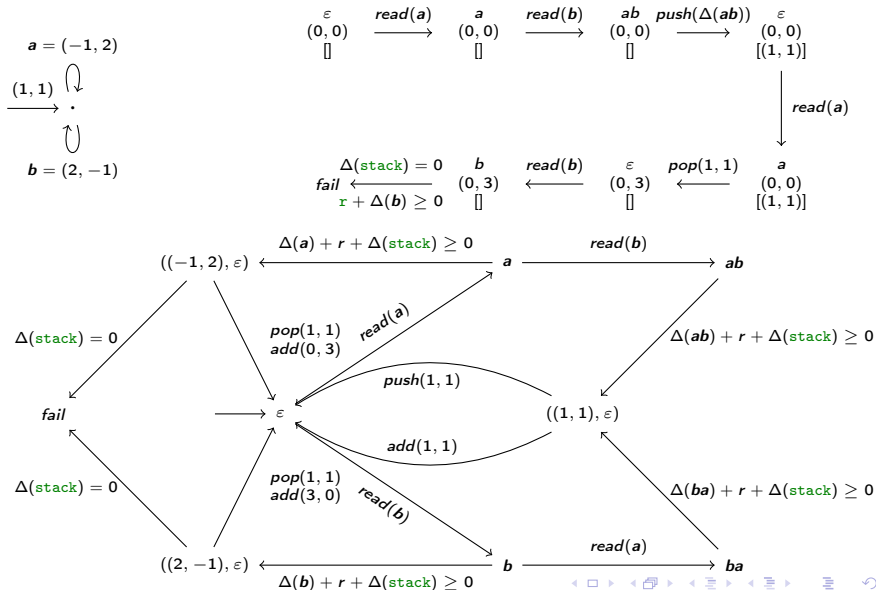
# From VAS to VPDA: Example



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# From VAS to VPDA: Properties

## Proposition

*The constructed VPDA has a finite set of states and transitions*

## Proposition

*If fail is not reachable, the VPDA recognises the same language as the VAS*

## Corollary

*If fail is not reachable, the VAS is context-free*

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# Witnesses of Non-Context-Freeness

$(2, 0)$        $(2, 2)$        $(0, 1)$        $(-2, -1)$        $(-1, -1)$

## Definition

A witness of non-context-freeness is a tuple  $(\sigma_1, \dots, \sigma_k, U)$  such that:

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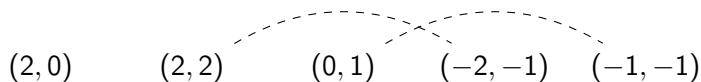
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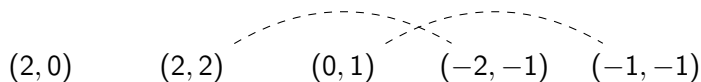
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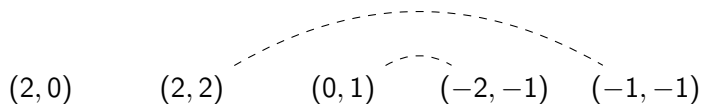


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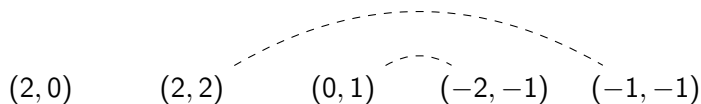


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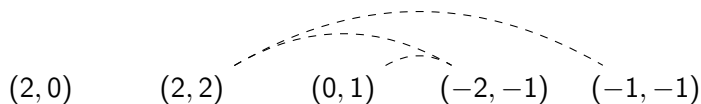


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- $\forall (s, t) \in U, \text{ with } t < k,$   
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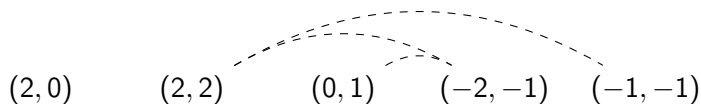


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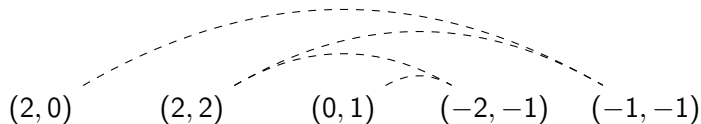


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- $\forall i, \sigma_k(i) > 0 \rightarrow \exists (s, t) \in U, \text{rem}(\sigma_s, \sigma_t)(i) > 0$

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## Proposition

*If a VAS admits a witness of non-context-freeness, it is not context free*

Proof based on Ginsburg characterisation of bounded context-free languages

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## Proposition

*If fail is reachable in the vector pushdown automaton of a VAS, it admits a witness of non-context-freeness*

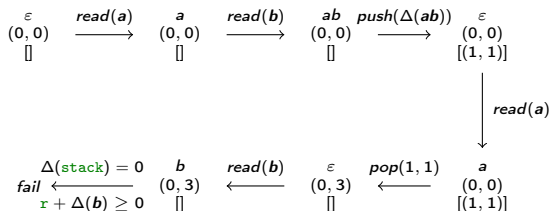
## Corollary

*If fail is reachable in the vector pushdown automaton of a VAS, it is not context-free*



# Witnesses and Vector Pushdown Automata: Example

$$\begin{array}{c}
 \mathbf{a} = (-1, 2) \\
 \xrightarrow{(1, 1)} \cdot \\
 \uparrow \\
 \mathbf{b} = (2, -1)
 \end{array}$$



# Witnesses and Vector Pushdown Automata: Example

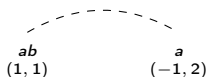
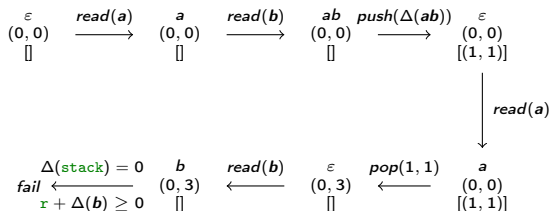
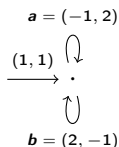
$$\begin{array}{c}
 \mathbf{a} = (-1, 2) \\
 \xrightarrow{(1, 1)} \cdot \\
 \mathbf{b} = (2, -1)
 \end{array}$$

$$\begin{array}{cc}
 \text{---} & \text{---} \\
 \mathbf{ab} & \mathbf{a} \\
 (1, 1) & (-1, 2)
 \end{array}$$

$$\begin{array}{ccccccc}
 \begin{array}{c} \varepsilon \\ (0, 0) \\ \square \end{array} & \xrightarrow{\text{read}(\mathbf{a})} & \begin{array}{c} \mathbf{a} \\ (0, 0) \\ \square \end{array} & \xrightarrow{\text{read}(\mathbf{b})} & \begin{array}{c} \mathbf{ab} \\ (0, 0) \\ \square \end{array} & \xrightarrow{\text{push}(\Delta(\mathbf{ab}))} & \begin{array}{c} \varepsilon \\ (0, 0) \\ [(1, 1)] \end{array} \\
 & & & & & & \downarrow \text{read}(\mathbf{a}) \\
 \begin{array}{c} \Delta(\text{stack}) = 0 \\ \text{fail} \leftarrow \\ \mathbf{r} + \Delta(\mathbf{b}) \geq 0 \end{array} & \xleftarrow{\mathbf{b}} & \begin{array}{c} \mathbf{b} \\ (0, 3) \\ \square \end{array} & \xleftarrow{\text{read}(\mathbf{b})} & \begin{array}{c} \varepsilon \\ (0, 3) \\ \square \end{array} & \xleftarrow{\text{pop}(1, 1)} & \begin{array}{c} \mathbf{a} \\ (0, 0) \\ [(1, 1)] \end{array}
 \end{array}$$

$$\begin{array}{c}
 \mathbf{b} \\
 (2, -1)
 \end{array}$$

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$b$   
 $(2, -1)$

$$\text{rem}(ab, b) = (0, 3)$$

$$\Delta(b) = (2, -1)$$

All negative components of  $b$  are lost.

It is a witness of non-context-freeness.

# Conclusion

- New proof, simpler than the one of Schwer

# Conclusion

- New proof, simpler than the one of Schwer
- Simpler characterisation of context-freeness:

**Theorem 5.1.** Let  $A = \langle T, \varphi, \mathbf{a} \rangle$  be a  $k$ -VAS and  $L(A)$  be its associated language. Let  $\mathcal{G}(A) = \langle T, Q, \delta, \mathbf{a} \rangle$  be its covering automaton.  $L(A)$  is context-free if and only if the following conditions hold:

- (P1) For every iterating system  $\mathcal{F} = (x_0, q_1, u_1, z_1, q_2, \dots, q_p, u_p, z_p, q)$  related to an elementary loop  $(q, u)$ ,  $\text{C1}(\mathcal{F}, (q, u))$  is satisfied.
- (P2) For no  $(q, v)$ ,  $(q', v')$  in  $\varepsilon^*$ ,  $(p, u)$ ,  $(p', u')$  in  $\varepsilon^+ \cap \mathbb{Z}((p, u), (p', u'), (q, v), (q', v'))$  is satisfied.
- (P3) For all classes  $[i]$  of states  $\mathbb{C}3(\text{label}(\mathcal{W}_i))$  and  $\mathbb{C}3(\text{label}(\mathcal{F}_i))$  are satisfied.
- (P4) For all  $j \in [1, m]$ , the set  $W = W_{\tau(j)}$  satisfies  $\mathbb{C}4(W)$ .
- (P5) For all  $j \in [1, m]$ , if  $W_{\tau(j)}$  has a dominating coordinate, then there is one in  $\text{ZERO}(J)$ .

**Definition 1.5.** Let  $A = \langle T, \varphi, \mathbf{a} \rangle$  be a  $k$ -VAS and  $\mathcal{G}(A) = \langle T, Q, \delta, \mathbf{a} \rangle$  be its covering automaton. Let  $(q, u)$  be a loop, and let  $\mathcal{F} = (x_0, q_1, u_1, z_1, q_2, \dots, q_p, u_p, z_p, q)$  be an iterating system of length  $p$  related to  $(q, u)$ . We note  $\text{C1}(\mathcal{F}, (q, u))$  the condition: the iterating system  $\mathcal{F}$  can be transformed into an elementary minimal iterating system, of length at most 1, by operations of decomposition or reduction.

**Corollary 1.6.** Let  $A = \langle T, \varphi, \mathbf{a} \rangle$  be a  $k$ -VAS and  $\mathcal{G}(A) = \langle T, Q, \delta, \mathbf{a} \rangle$  be its covering automaton. If  $L(A)$  is context-free, then the following condition holds:

- (P1) For every iterating system  $\mathcal{F} = (x_0, q_1, u_1, z_1, q_2, \dots, q_p, u_p, z_p, q)$  related to an elementary loop  $(q, u)$ ,  $\text{C1}(\mathcal{F}, (q, u))$  holds.

**Definition 4.8.** Let  $\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k$  be  $k$ -tuples of  $\mathbb{Z}^r$ . We denote by  $\mathbb{C}3(\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k)$  the condition: there exists a coordinate  $p$  which is a dominating coordinate with respect to  $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k\}$ , and by  $\mathbb{C}3(\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k; p, q)$  the condition: the coordinate  $p$  dominates the coordinate  $q$  with respect to  $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_k\}$ .

**Definition 2.1.** We note  $\mathbb{C}2((p, u), (p', u'), (q, v), (q', v'))$  the condition:  $(q, v)$  and  $(q', v')$  are two loops in  $\varepsilon^*$ , and  $(p, u)$  and  $(p', u')$  are two loops in  $\varepsilon^+$ , such that there exist  $s_1, s_2$  and  $s_3$  with  $\delta(q_1, s_1) = p, \delta(p, s_2) = p', \delta(p', s_3) = q$  and  $\delta(q, s_3) = q'$  and such that  $[v] \cap [s_1]^{-1}$  and  $[v'] \cap [s_2]^{-1}$  are not empty, and such that either  $[v]^{-1}$  is not included in  $[s_1]^{-1}$ , or  $[v']^{-1}$  is not included in  $[s_2]^{-1}$  for both.

We can state our second necessary condition.

**Proposition 2.2.** Let  $A = \langle T, \varphi, \mathbf{a} \rangle$  be a  $k$ -VAS and  $\mathcal{G}(A) = \langle T, Q, \delta, \mathbf{a} \rangle$  be its covering automaton such that (P1) holds. If  $L(A)$  is context-free, then the following condition holds:

- (P2) For no  $(q, v), (q', v')$  in  $\varepsilon^*$ ,  $(p, u), (p', u')$  in  $\varepsilon^+$ ,  $\mathbb{C}2((p, u), (p', u'), (q, v), (q', v'))$  holds.

**Definition 4.1.** For any set  $W$  of  $k$ -tuples, denote  $J_W$  the set:  $J_W = \{x \in H \mid \exists r, s \varphi, \mathbf{a}$  are not cofactor and  $x \in K, r \in K\}$ . We note  $\mathbb{C}4(W)$  the condition: the set  $J_W$  is a stratified set.

The language of traces of a VAS is context-free if and only if it has a context-free intersection with every bounded regular language

**Proposition 4.5.** Let  $A = \langle T, \varphi, \mathbf{a} \rangle$  be a  $k$ -VAS and  $\mathcal{G}(A) = \langle T, Q, \delta, \mathbf{a} \rangle$  be its covering automaton such that (P1), (P2), (P3) and (P4) hold. If  $L(A)$  is context-free, then the following condition holds:

- (P5) For all  $j \in [1, m]$ , if  $W_{\tau(j)}$  has a dominating coordinate, then there is one in  $\text{ZERO}(J)$ .

# Conclusion

- New proof, simpler than the one of Schwer
- Simpler characterisation of context-freeness:

**Theorem 5.1.** Let  $A = \langle T, \varphi, \mathbf{a} \rangle$  be a  $k$ -VAS and  $L(A)$  be its associated language. Let  $\mathcal{C}(A) = \langle T, Q, \delta, \mathbf{a} \rangle$  be its covering automaton.  $L(A)$  is context-free if and only if the following conditions hold:

- (P1) For every iterating system  $\mathcal{F} = (x_0, q_1, u_1, x_1, q_2, \dots, x_{p-1}, q_p, u_p, x_p, q)$  related to an elementary loop  $(q, u)$ ,  $\mathcal{C}1(\mathcal{F}, (q, u))$  is satisfied.
- (P2) For no  $(q, v), (q', v')$  in  $\varepsilon^-$ ,  $(p, u), (p', u')$  in  $\varepsilon^+ \subseteq \mathcal{C}2((p, u), (p', u'), (q, v), (q', v'))$  is satisfied.
- (P3) For all classes  $[i]$  of states  $\mathcal{C}3(\text{label}(\mathcal{W}_i))$  and  $\mathcal{C}3(\text{label}(\mathcal{X}_i))$  are satisfied.
- (P4) For all  $j \in [1, m]$ , the set  $W = W_{i^*(j)}$  satisfies  $\mathcal{C}4(W)$ .
- (P5) For all  $j \in [1, m]$ , if  $W_{i^*(j)}$  has a dominating coordinate, then there is one in  $\text{ZERO}(J)$ .

The language of traces of a VAS is context-free if and only if it has a context-free intersection with every bounded regular language

## Perspectives:

- The complexity is shown to be  $\text{EXPSpace}$  by J. Leroux, M. Praveen, and G. Sutre in an upcoming paper to CONCUR'13