

Toward a Computational Steering Environment for Legacy Coupled Simulations

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Outline

1 Introduction

- General Notions about Computational Steering
- Introduction to EPSN Model

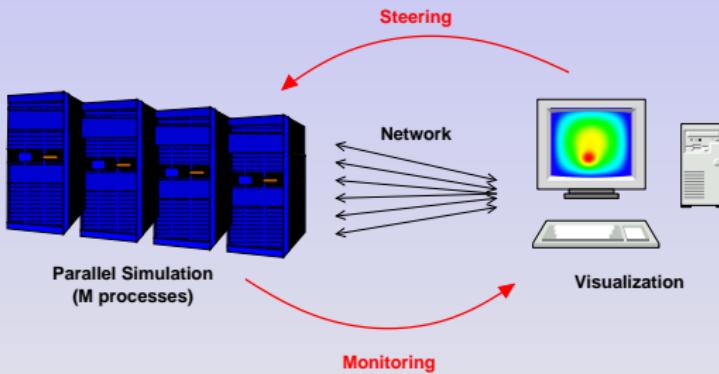
2 Coupled Simulations

- Main issues
- Unique description for each coupled simulations kind

3 Conclusion

Numerical Simulations and Computational Steering

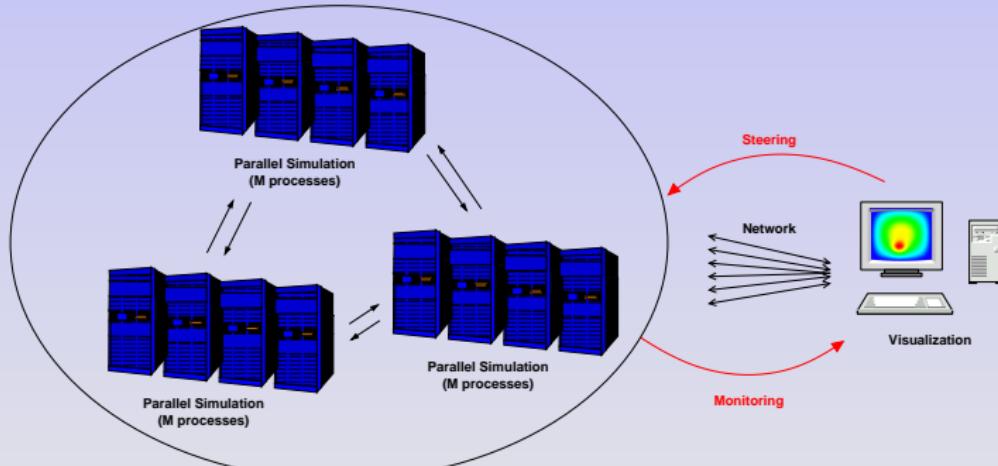
- Traditionally: Numerical simulation → Post-processing (Visualization)
- Computational steering: a more interactive approach
 - Monitoring: Online visualization of intermediate results
 - Steering: Change simulation parameters and data on-the-fly



→ Drive the simulation more rapidly in the right direction

Steering of Coupled Simulations

- Coupled simulations: different models coupled in different distributed codes
- Simulation representation and interaction mechanism
→ how, when, and where safely interacts with the simulations?

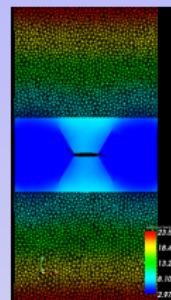


→ Two main kinds of coupled simulations: M-SPMD and Client-Server

“M-SPMD” Simulations

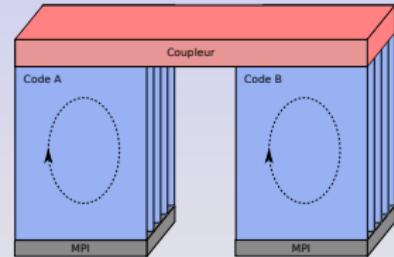
LibMultiScale

- Simulation of crack propagation in materials
- Code A : elastodynamic (macroscopic)
data : mesh (displacement, velocity, ...)
- Code B : molecular dynamics (microscopic)
data : atoms (position, velocity, ...)
- The coupling program is distributed on the
2 codes



M-SPMD

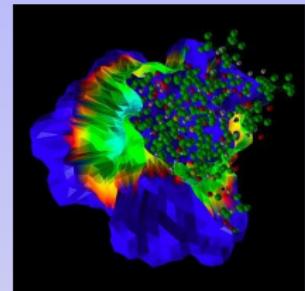
- Multiple SPMD codes with roughly the same execution flow
- As many time loops as codes



“Client-Server” Simulations

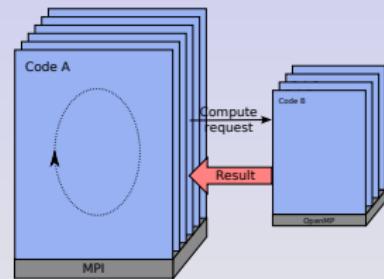
Simbio

- Molecular simulation in fluids
- Code A : molecular dynamic
data : atoms (position, velocity)
- Code B : electrostatic computation
data : surface mesh, scalar field



Client-Server

- A code (client) which use functionalities of an other code (server)
- Client as a time loop and servers don't have any

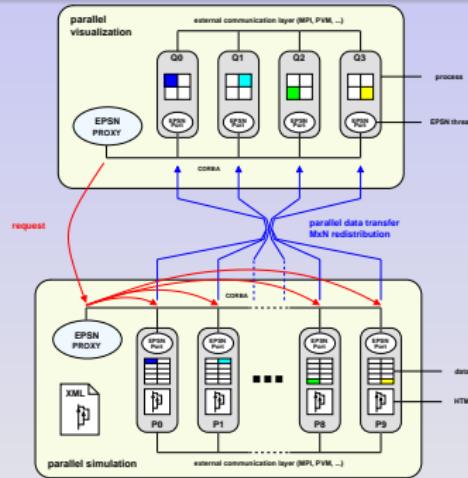


- Problem Solving Environment: SCIRun, COVISE
 - interconnect modules to build new simulations
 - provides visualisation and steering modules
- Steering frameworks: CUMULVS, Visit, EPSN
 - instrumentation of legacy simulations codes
 - dedicated to steer simulations
- Grid and Component frameworks: Cactus, CCA, RealityGrid
 - Some steering possibilities

EPSN Keypoints

Features

- Legacy parallel simulations
- Parallel visualisation capable
- Client/Server relationship
- Communication layer based on CORBA



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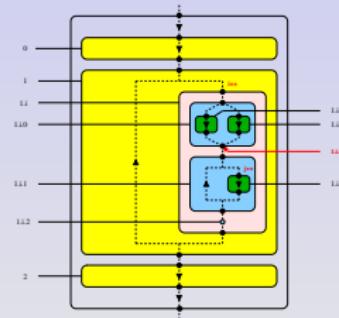
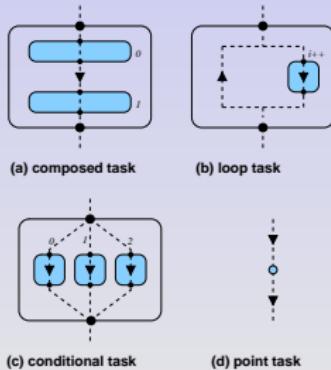
Abstract model for simulations representation

- EPSN based on an abstract description in 2 parts :
 - Description model:
 - Execution flow description
 - Data description
 - Steering model
 - Steering requests - Interaction availability on tasks

Description Model 1/2

HTM : Hierarchical Task Model to capture the execution flow

- Description based on a task tree
- 4 tasks kinds (grasp main structures):
 - (a) simple, (b) loop, (c) conditional and (d) point
- Date associated to each task
- Task defined by an XML file and by code annotations

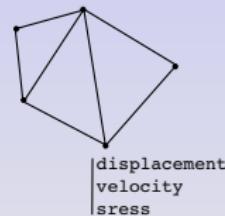


Data we want to steer or visualize

- Geometry description (mesh, particles, grid, etc.)
- Variables
- Data distribution and storage description
- Data access right on tasks
- Description given by an XML file and by code annotations

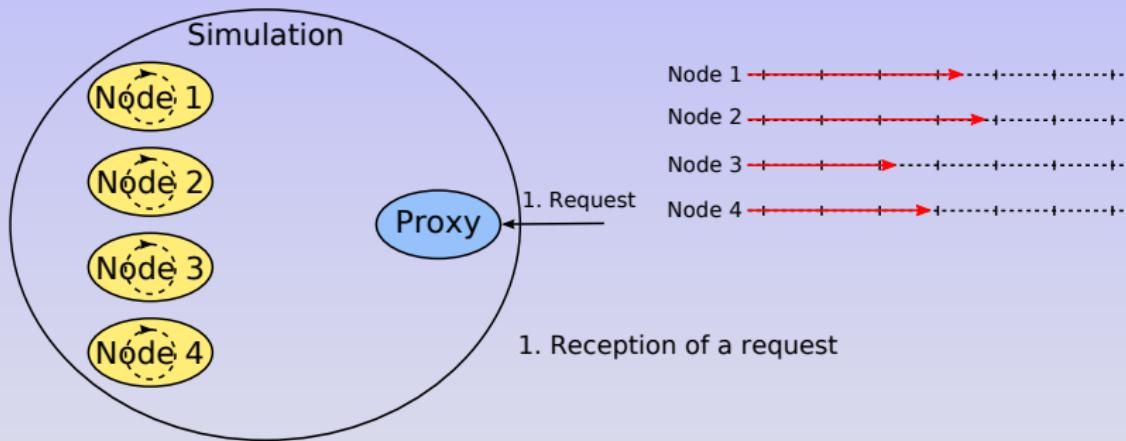
```
<simulation id="Finite Elements">
  <data>
    <object class="mesh" id="FE">
      <variable id="vertex" />
      <variable id="connectivity" />
      <variable id="displacement" />
      <variable id="velocity" />
      <variable id="stress" />
    </object>
  </data>
</simulation>
```

geometry
data



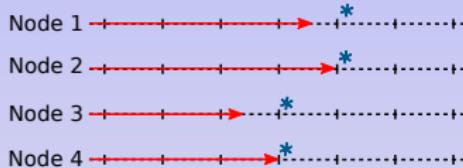
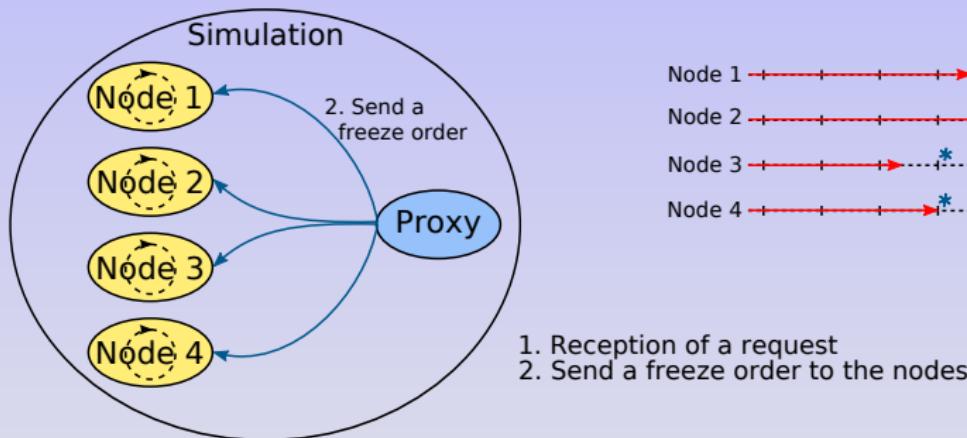
SPMD Coordination Algorithm

Aims : Date of treatment prevision with minimum influence on the code execution



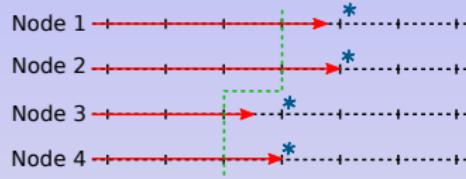
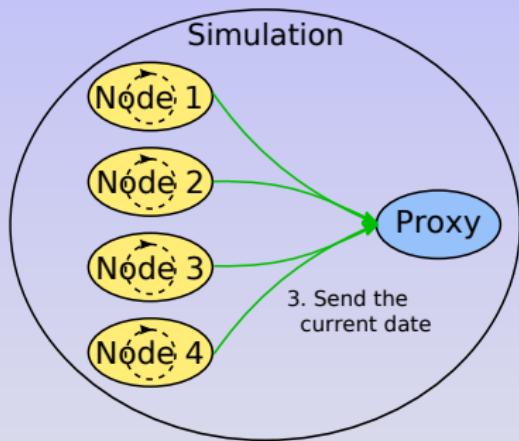
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SPMD Coordination Algorithm

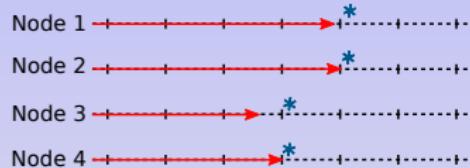
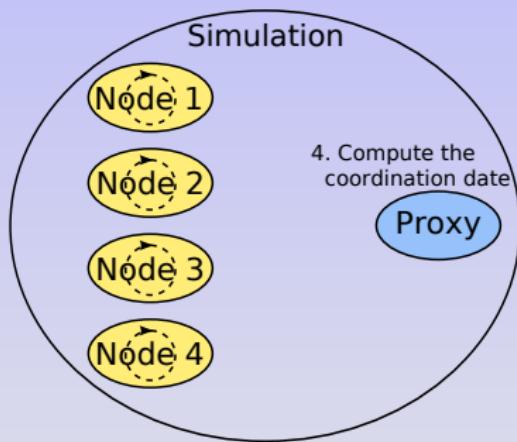
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1. Reception of a request
2. Send a freeze order to the nodes
3. Get the current date from the nodes

SPMD Coordination Algorithm

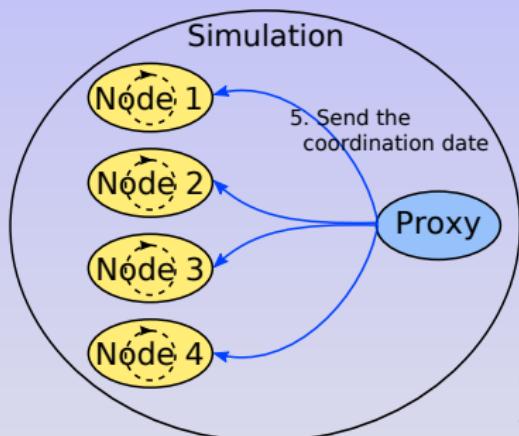
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4. Computation of the coordination date

SPMD Coordination Algorithm

Aims : Date of treatment prevision with minimum influence on the code execution



1. Reception of a request
2. Send a freeze order to the nodes
3. Get the current date from the nodes
4. Computation of the coordination date
5. Broadcast the coordination date to the nodes

Structure description

- SPMD Simulations : ✓
- M-SPMD Simulations :
 - on codes with the same HTM : ✓
 - on codes with too many differences in HTMs: ✗
- Other simulations kind : ✗

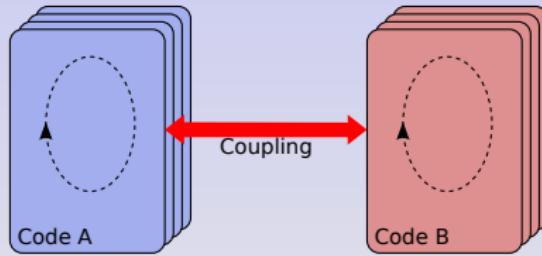
Data description

- SPMD Simulations : ✓
- Other simulation kinds : ✗
 - No way to represent data that are combination of many data on different codes

Problem to Solve 1/2

How to describe M-SPMD and Client-Server simulations to steer them efficiently ?

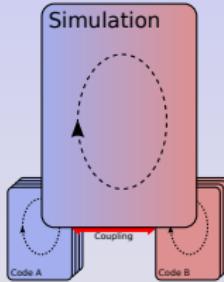
- Need a model to capture the execution flow
 - have a unique date system
 - coordinate precisely treatment
 - ensure data coherency



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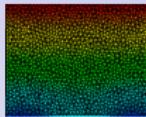
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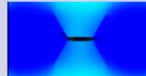
Problem to solve 2/2

How to describe M-SPMD and Client-Server simulations to steer them efficiently ?

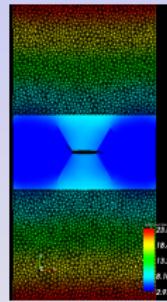
- Data description which afford to have a global view of them
 - ensure data coherency
 - get data as a unique entity to visualize them



Mesh on code A



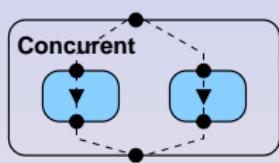
Atoms on code B



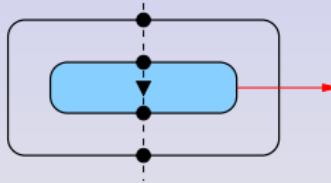
What we want to visualize

Execution flow description

- Build an unique HTM that
 - Describes the main loop of the distributed simulation
 - Describes the common steerable tasks of HTM of both codes
 - Afford to have only one model of description for M-SPMD and Client-Server simulations
- Two new task types
 - Remote : corresponds to remote function call on remote codes
 - Concurrent : represents tasks which are executed at the same time on different codes



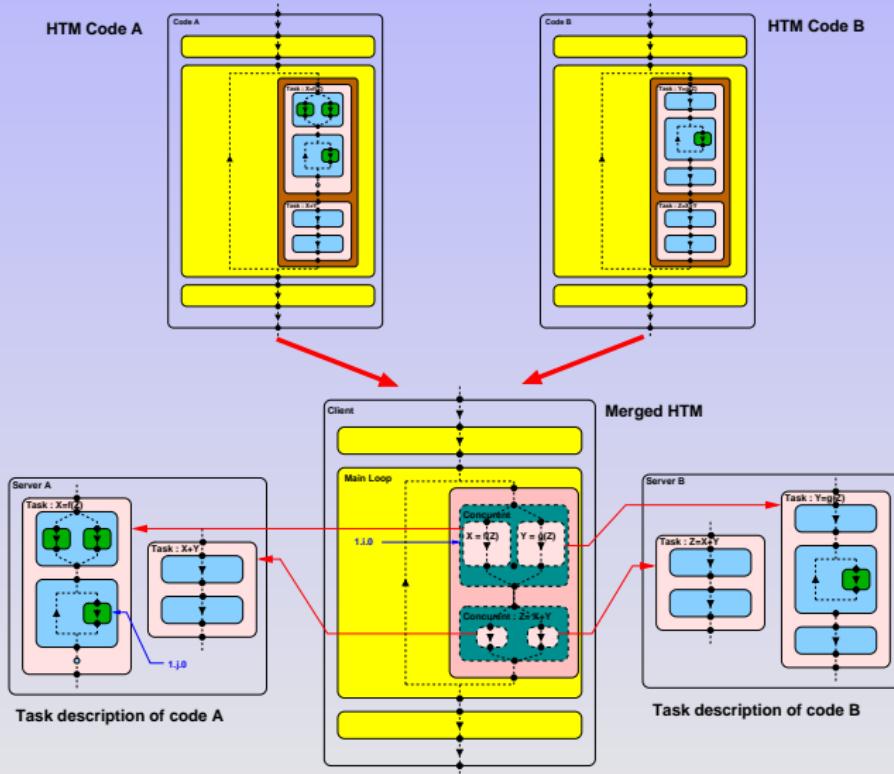
(a) concurrent task



(b) remote task

Sample HTM for a coupled code

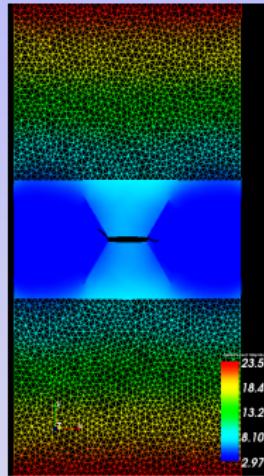
To illustrate :



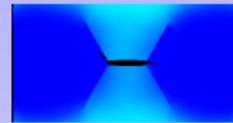
Introduction of a new object type

- Meta-object that grab the description of data present on codes
 - Name of concerned data and variables
 - Task in codes where the data are coherent
- New key word in the XML file: meta-object

Data description for LibMultiScale

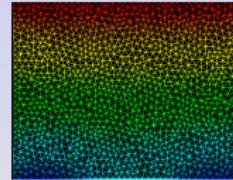


```
<simulation id="LibMultiScale">
<data>
<meta-object id="displacement">
<variable id="atoms-displacement"
object_id="atoms"
variable_id="X"
function="Leapfrog"
task_id="Forces (n+1)"
location="Atoms"/>
<variable id="fe-displacement"
object_id="FE"
variable_id="displacement"
function="Leapfrog"
task_id="Forces (n+1)"
location="Finite Element"/>
</meta-object>
</data>
</simulation>
```

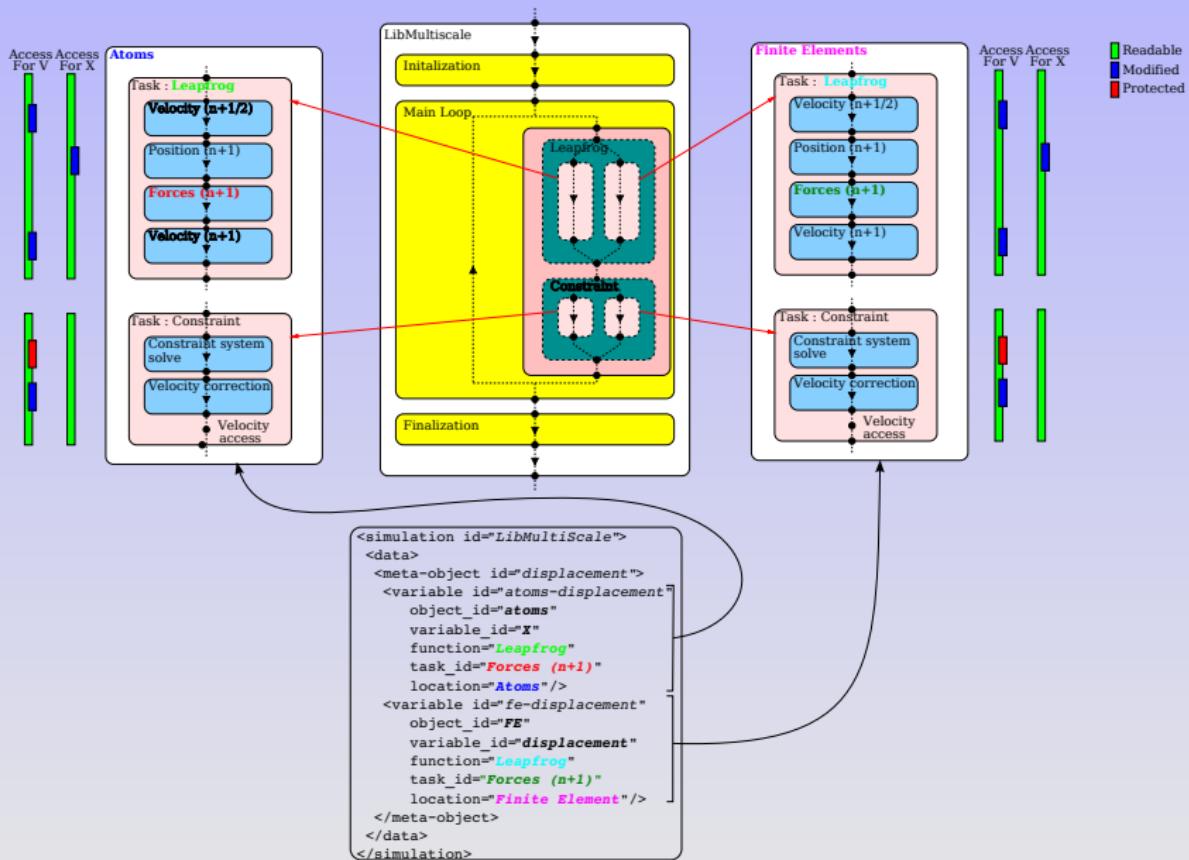


```
<simulation id="Atoms">
<data>
<object class="points" id="atoms">
<variable id="X0" />
<variable id="Xn" />
<variable id="velocity" />
</object>
</data>
</simulation>
```

```
<simulation id="Finite Elements">
<data>
<object class="mesh" id="FE">
<variable id="vertex" />
<variable id="connectivity" />
<variable id="displacement" />
<variable id="velocity" />
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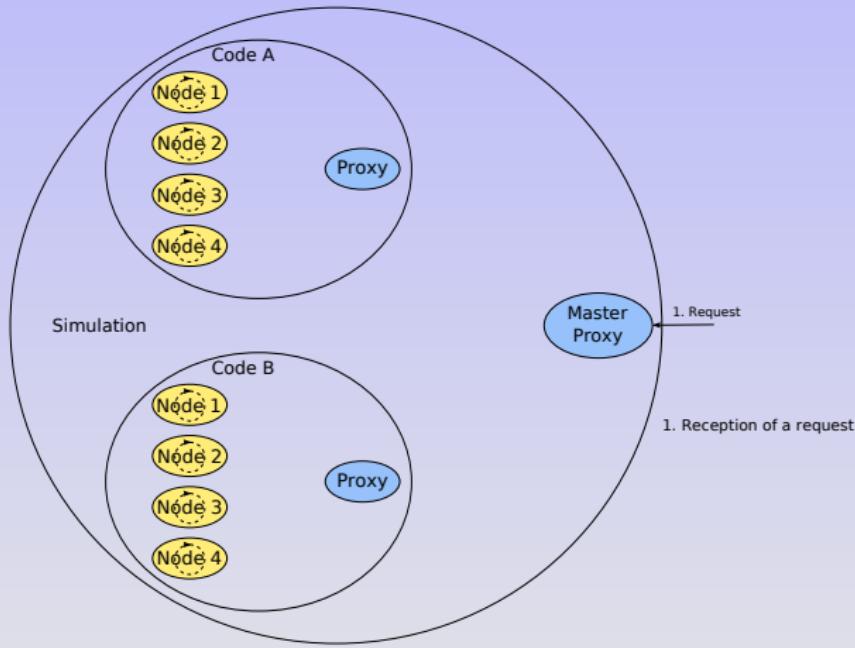


Data description for LibMultiScale



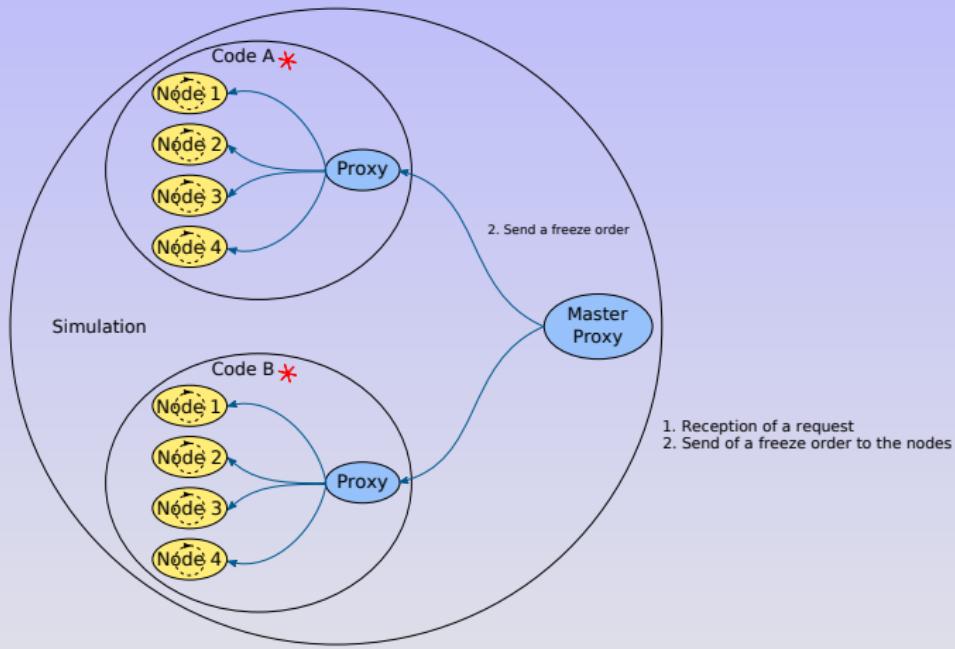
Coordination algorithm for data request

Aim : get coherent data for all codes



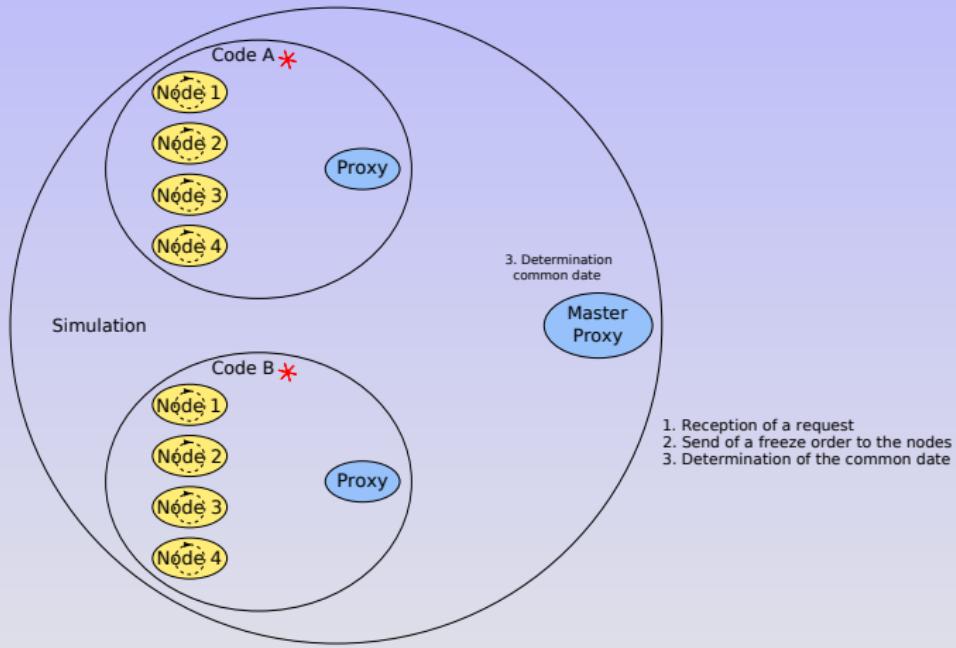
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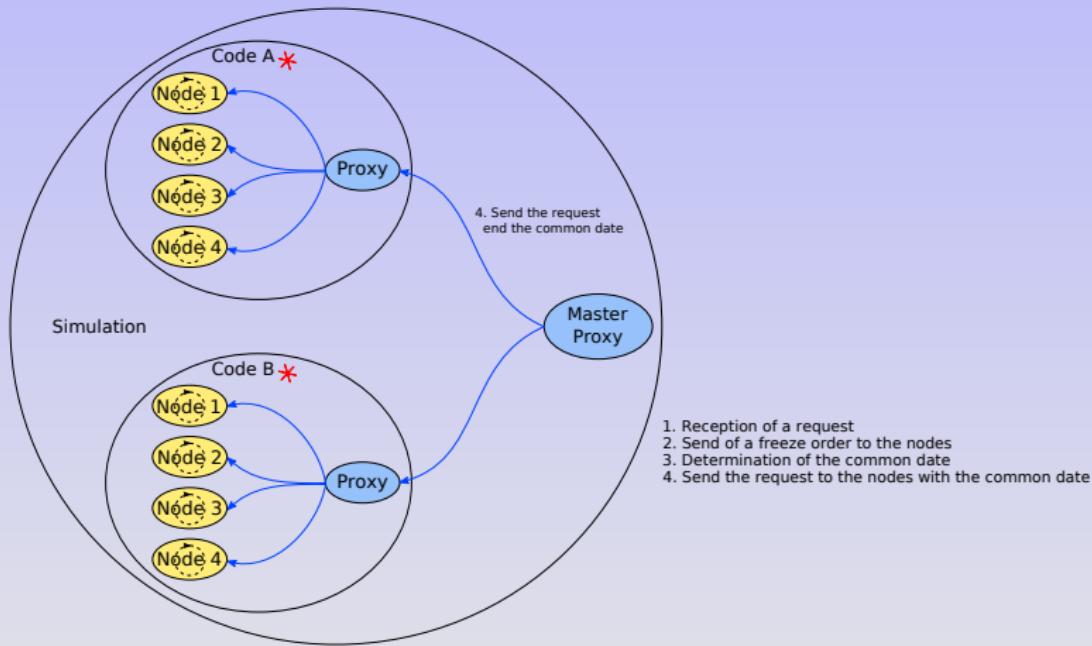
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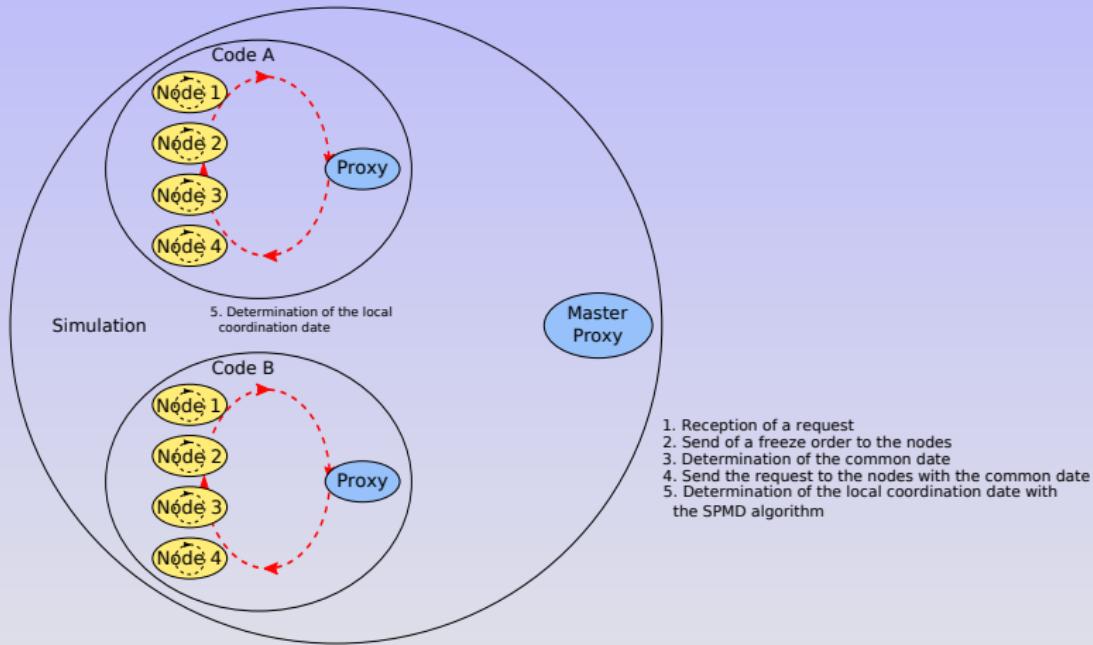
Coordination algorithm for data request

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Coordination algorithm for data request

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Steering of coupled simulations

- Steering framework for legacy SPMD simulations
Open source project : <http://epsn.gforge.inria.fr/>
- A model to steer coupled simulations
 - Way to describe execution flow of M-SPMD and Client-Server simulations, and to describe distributed data
 - Coordination algorithm to manage coherent treatments in such simulations

Future works

- Test the scalability of this approach
- Test on a real case study